

TENTATIVE TOSHIBA MOS DIGITAL INTEGRATED CIRCUIT SILICON MONOLITHIC

8,388,608-WORDS \times 4 BANKS \times 16-BITS Network FCRAMTM
 16,777,216-WORDS \times 4 BANKS \times 8-BITS Network FCRAMTM

DESCRIPTION

Network FCRAMTM is Double Data Rate Fast Cycle Random Access Memory. TC59LM913/05AMB is Network FCRAMTM containing 536,870,912 memory cells. TC59LM913AMB is organized as 8,388,608-words \times 4 banks \times 16 bits, TC59LM905AMB is organized as 16,777,216-words \times 4 banks \times 8 bits. TC59LM913/05AMB feature a fully synchronous operation referenced to clock edge whereby all operations are synchronized at a clock input which enables high performance and simple user interface coexistence. TC59LM913/05AMB can operate fast core cycle compared with regular DDR SDRAM.

TC59LM913/05AMB is suitable for Network, Server and other applications where large memory density and low power consumption are required. The Output Driver for Network FCRAMTM is capable of high quality fast data transfer under light loading condition.

FEATURES

| PARAMETER | | TC59LM913/05 | | |
|---------------------------------------------------------|--------|--------------|---------|---------|
| | | -50 | -55 | -60 |
| t _{CK} Clock Cycle Time (min) | CL = 3 | 5.5 ns | 6.0 ns | 6.5 ns |
| | CL = 4 | 5.0 ns | 5.5 ns | 6.0 ns |
| t _{RC} Random Read/Write Cycle Time (min) | | 25.0 ns | 27.5 ns | 30.0 ns |
| t _{RAC} Random Access Time (max) | | 22.0 ns | 24.0 ns | 26.0 ns |
| I _{DD1S} Operating Current (single bank) (max) | | TBD | TBD | TBD |
| I _{DD2P} Power Down Current (max) | | TBD | TBD | TBD |
| I _{DD6} Self-Refresh Current (max) | | TBD | TBD | TBD |

- Fully Synchronous Operation
 - Double Data Rate (DDR)
Data input/output are synchronized with both edges of DQS.
 - Differential Clock (CLK and $\overline{\text{CLK}}$) inputs
 $\overline{\text{CS}}$, FN and all address input signals are sampled on the positive edge of CLK.
Output data (DQs and DQS) is aligned to the crossings of CLK and $\overline{\text{CLK}}$.
- Fast clock cycle time of 5 ns minimum
Clock: 200 MHz maximum
Data: 400 Mbps/pin maximum
- Fast cycle and Short Latency
- Distributed Auto-Refresh cycle in 7.8 μ s
- Self-Refresh
- Power Down Mode
- Variable Write Length Control
- Write Latency = $\overline{\text{CAS}}$ Latency-1
- Programmable $\overline{\text{CAS}}$ Latency and Burst Length
 $\overline{\text{CAS}}$ Latency = 3, 4
Burst Length = 2, 4
- Organization: TC59LM813AMB : 8,388,608 words \times 4 banks \times 16 bits
TC59LM805AMB : 16,777,216 words \times 4 banks \times 8 bits
- Power Supply Voltage V_{DD}: 2.5 V \pm 0.15V
V_{DDQ}: 2.5 V \pm 0.15 V
- 2.5 V CMOS I/O comply with SSTL-2 (half strength driver)
- Package: 60Ball BGA, 1mm \times 1mm Ball pitch

Notice : FCRAM is trademark of Fujitsu Limited, Japan.

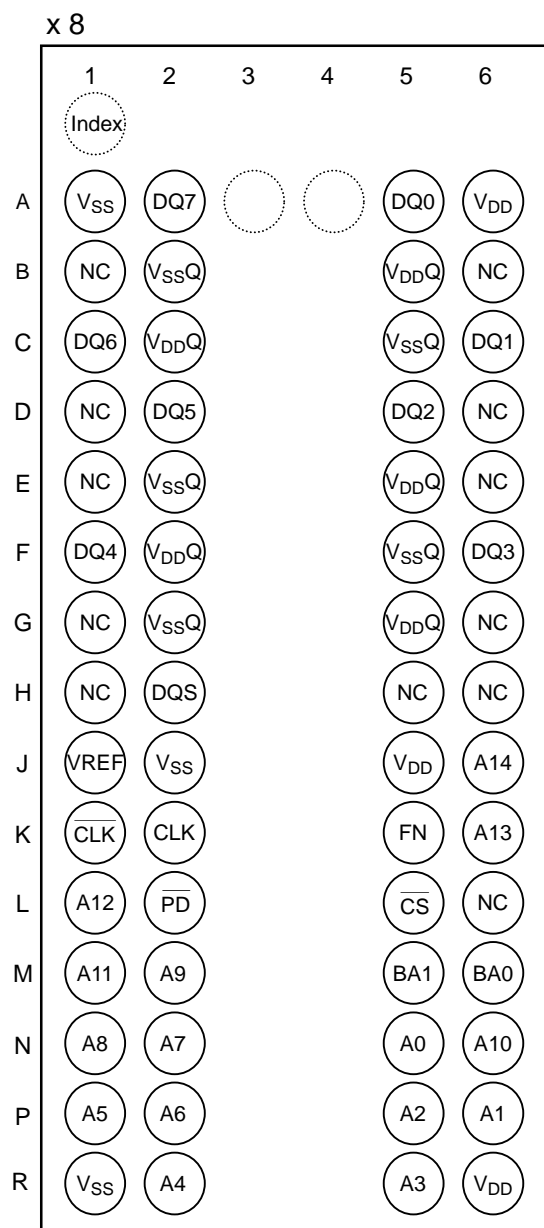
TC59LM905AMB

PIN NAMES

| PIN | NAME |
|------------------------------|------------------------------------|
| A0~A14 | Address Input |
| BA0, BA1 | Bank Address |
| DQ0~DQ7 | Data Input/Output |
| $\overline{\text{CS}}$ | Chip Select |
| FN | Function Control |
| $\overline{\text{PD}}$ | Power Down Control |
| CLK, $\overline{\text{CLK}}$ | Clock Input |
| DQS | Write/Read Data Strobe |
| V _{DD} | Power (+2.5 V) |
| V _{SS} | Ground |
| V _{DDQ} | Power (+2.5 V) (for I/O buffer) |
| V _{SSQ} | Ground (for I/O buffer) |
| V _{REF} | Reference Voltage |
| NC | Not Connected |

PIN ASSIGNMENT (TOP VIEW)

ball pitch=1.0 x 1.0mm



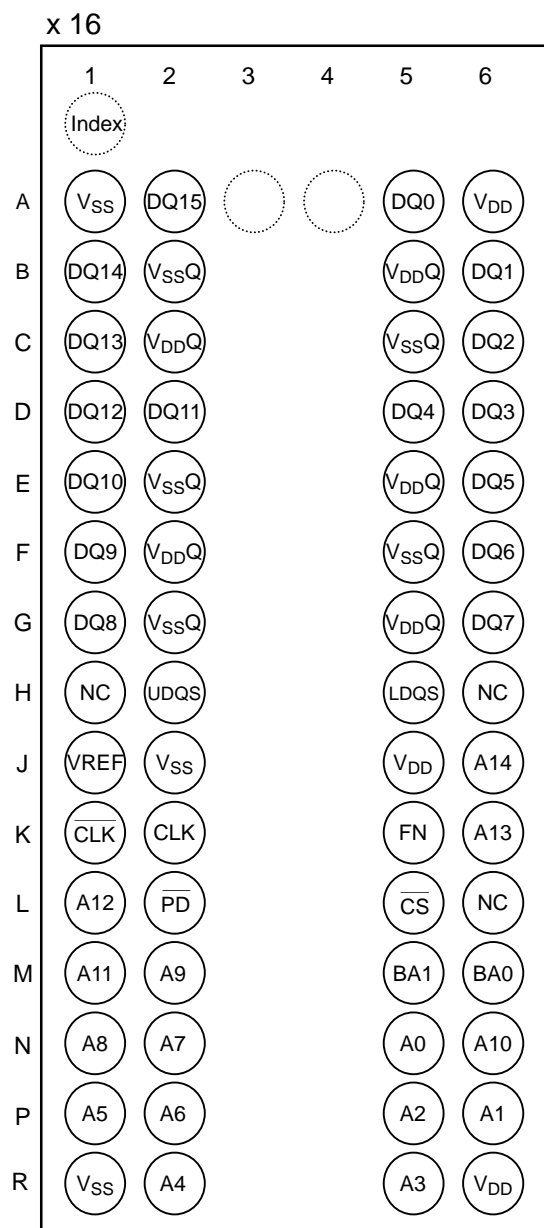
TC59LM913AMB

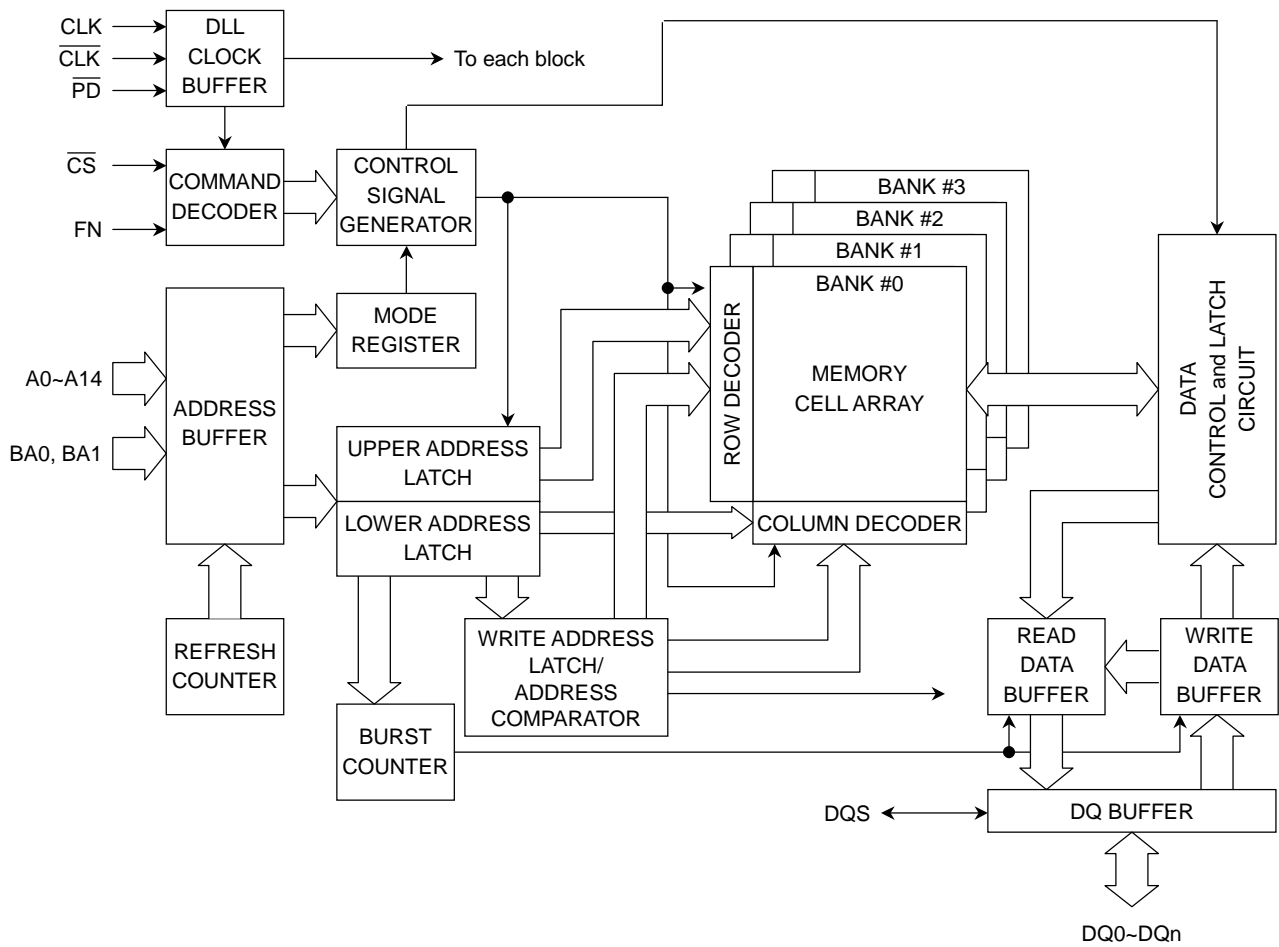
PIN NAMES

| PIN | NAME |
|------------------------------|------------------------------------|
| A0~A14 | Address Input |
| BA0, BA1 | Bank Address |
| DQ0~DQ15 | Data Input/Output |
| $\overline{\text{CS}}$ | Chip Select |
| FN | Function Control |
| $\overline{\text{PD}}$ | Power Down Control |
| CLK, $\overline{\text{CLK}}$ | Clock Input |
| UDQS / LDQS | Write/Read Data Strobe |
| V _{DD} | Power (+2.5 V) |
| V _{SS} | Ground |
| V _{DDQ} | Power (+2.5 V) (for I/O buffer) |
| V _{SSQ} | Ground (for I/O buffer) |
| V _{REF} | Reference Voltage |
| NC | Not Connected |

PIN ASSIGNMENT (TOP VIEW)

ball pitch=1.0 x 1.0mm



BLOCK DIAGRAM


Note: The TC59LM905AMB configuration is 4 Bank of $32768 \times 512 \times 8$ of cell array with the DQ pins numbered DQ0~DQ7.
 The TC59LM913AMB configuration is 4 Bank of $32768 \times 256 \times 16$ of cell array with the DQ pins numbered DQ0~DQ15.

ABSOLUTE MAXIMUM RATINGS

| SYMBOL | PARAMETER | RATING | UNIT | NOTES |
|---------------------|---------------------------------------|-----------------------------|------|-------|
| V _{DD} | Power Supply Voltage | -0.3~3.3 | V | |
| V _{DDQ} | Power Supply Voltage (for I/O buffer) | -0.3~V _{DD} + 0.3 | V | |
| V _{IN} | Input Voltage | -0.3~V _{DD} + 0.3 | V | |
| V _{OUT} | Output and I/O pin Voltage | -0.3~V _{DDQ} + 0.3 | V | |
| V _{REF} | Input Reference Voltage | -0.3~V _{DD} + 0.3 | V | |
| T _{opr} | Operating Temperature (Ambient) | 0~70 | °C | |
| T _{stg} | Storage Temperature | -55~150 | °C | |
| T _{solder} | Soldering Temperature (10 s) | 260 | °C | |
| P _D | Power Dissipation | 2 | W | |
| I _{OUT} | Short Circuit Output Current | ±50 | mA | |

Caution: Conditions outside the limits listed under "ABSOLUTE MAXIMUM RATINGS" may cause permanent damage to the device. The device is not meant to be operated under conditions outside the limits described in the operational section of this specification.

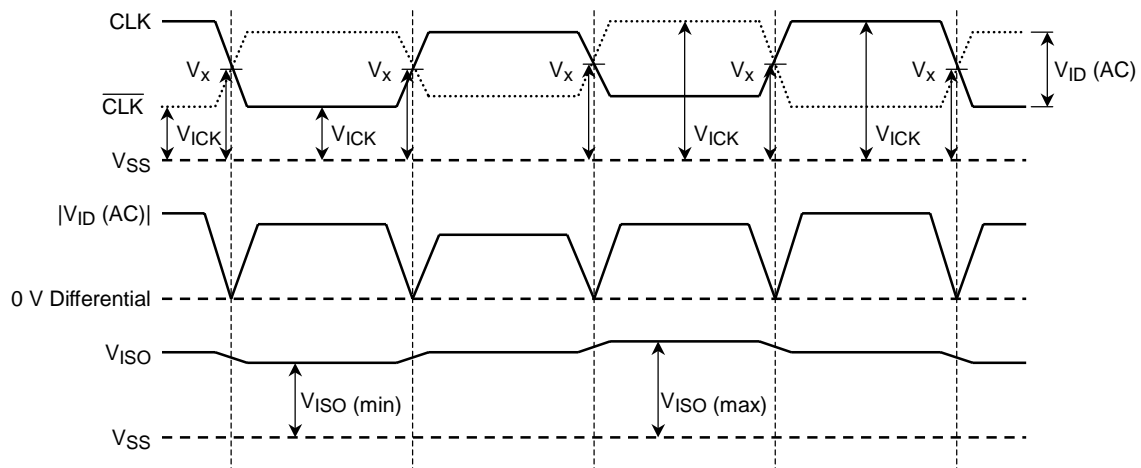
Exposure to "ABSOLUTE MAXIMUM RATINGS" conditions for extended periods may affect device reliability.

RECOMMENDED DC, AC OPERATING CONDITIONS (Notes: 1)(T_{CASE} = 0~85°C)

| SYMBOL | PARAMETER | MIN | TYP. | MAX | UNIT | NOTES |
|-----------------------|----------------------------------------------------------------------------|---------------------------|---------------------|----------------------------|------|-------|
| V _{DD} | Power Supply Voltage | 2.35 | 2.5 | 2.65 | V | |
| V _{DDQ} | Power Supply Voltage (for I/O buffer) | 2.35 | V _{DD} | V _{DD} | V | |
| V _{REF} | Input Reference Voltage | V _{DDQ} /2 × 96% | V _{DDQ} /2 | V _{DDQ} /2 × 104% | V | 2 |
| V _{IH} (DC) | Input DC High Voltage | V _{REF} + 0.2 | — | V _{DDQ} + 0.2 | V | 5 |
| V _{IL} (DC) | Input DC Low Voltage | -0.1 | — | V _{REF} - 0.2 | V | 5 |
| V _{ICK} (DC) | Differential Clock DC Input Voltage | -0.1 | — | V _{DDQ} + 0.1 | V | 10 |
| V _{ID} (DC) | Input Differential Voltage. CLK and $\overline{\text{CLK}}$ inputs (DC) | 0.4 | — | V _{DDQ} + 0.2 | V | 7, 10 |
| V _{IH} (AC) | Input AC High Voltage | V _{REF} + 0.35 | — | V _{DDQ} + 0.2 | V | 3, 6 |
| V _{IL} (AC) | Input AC Low Voltage | -0.1 | — | V _{REF} - 0.35 | V | 4, 6 |
| V _{ID} (AC) | Input Differential Voltage. CLK and $\overline{\text{CLK}}$ inputs (AC) | 0.7 | — | V _{DDQ} + 0.2 | V | 7, 10 |
| V _X (AC) | Differential AC Input Cross Point Voltage | V _{DDQ} /2 - 0.2 | — | V _{DDQ} /2 + 0.2 | V | 8, 10 |
| V _{ISO} (AC) | Differential Clock AC Middle Level | V _{DDQ} /2 - 0.2 | — | V _{DDQ} /2 + 0.2 | V | 9, 10 |

Note:

- (1) All voltages referenced to VSS, VSSQ.
- (2) VREF is expected to track variations in VDDQ DC level of the transmitting device.
Peak to peak AC noise on VREF may not exceed $\pm 2\%$ VREF (DC).
- (3) Overshoot limit: $V_{IH}(\max) = V_{DDQ} + 0.9 \text{ V}$ with a pulse width $\leq 5 \text{ ns}$.
- (4) Undershoot limit: $V_{IL}(\min) = -0.9 \text{ V}$ with a pulse width $\leq 5 \text{ ns}$.
- (5) $V_{IH}(\text{DC})$ and $V_{IL}(\text{DC})$ are levels to maintain the current logic state.
- (6) $V_{IH}(\text{AC})$ and $V_{IL}(\text{AC})$ are levels to change to the new logic state.
- (7) V_{ID} is magnitude of the difference between CLK input level and $\overline{\text{CLK}}$ input level.
- (8) The value of $V_X(\text{AC})$ is expected to equal $V_{DDQ}/2$ of the transmitting device.
- (9) V_{ISO} means $\{V_{ICK}(\text{CLK}) + V_{ICK}(\overline{\text{CLK}})\} / 2$
- (10) Refer to the figure below.



- (11) In the case of external termination, VTT (termination voltage) should be gone in the range of $V_{REF}(\text{DC}) \pm 0.04 \text{ V}$.

CAPACITANCE ($V_{DD} = 2.5\text{V}$, $V_{DDQ} = 2.5 \text{ V}$, $f = 1 \text{ MHz}$, $T_a = 25^\circ\text{C}$)

| SYMBOL | PARAMETER | MIN | MAX | Delta | UNIT |
|-----------|-------------------------------------------------------|-----|-----|-------|------|
| C_{IN} | Input pin Capacitance | 1.5 | 2.5 | 0.25 | pF |
| C_{INC} | Clock pin (CLK, $\overline{\text{CLK}}$) Capacitance | 1.5 | 2.5 | 0.25 | pF |
| $C_{I/O}$ | DQ, DQS, UDQS, LDQS Capacitance | 2.5 | 4.0 | 0.5 | pF |
| C_{NC} | NC pin Capacitance | — | 4.0 | — | pF |

Note: These parameters are periodically sampled and not 100% tested.

RECOMMENDED DC OPERATING CONDITIONS(V_{DD}=2.5V ± 0.15V, V_{DDQ}=2.5V ± 0.15V, T_{CASE} = 0~85°C)

| SYMBOL | PARAMETER | MAX | | | UNIT | NOTES |
|-------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|-----|-----|------|-------|
| | | -50 | -55 | -60 | | |
| I _{DD1S} | Operating Current t _{CK} = min; I _{RC} = min, Read/Write command cycling, 0 V ≤ V _{IN} ≤ V _{IL} (AC) (max), V _{IH} (AC) (min) ≤ V _{IN} ≤ V _{DDQ} , 1 bank operation, Burst length = 4, Address change up to 2 times during minimum I _{RC} . | TBD | TBD | TBD | mA | 1, 2 |
| I _{DD2N} | Standby Current t _{CK} = min, CS = V _{IH} , PD = V _{IH} , 0 V ≤ V _{IN} ≤ V _{IL} (AC) (max), V _{IH} (AC) (min) ≤ V _{IN} ≤ V _{DDQ} , All banks: inactive state, Other input signals are changed one time during 4 × t _{CK} . | TBD | TBD | TBD | | 1 |
| I _{DD2P} | Standby (power down) Current t _{CK} = min, CS = V _{IH} , PD = V _{IL} (power down), 0 V ≤ V _{IN} ≤ V _{DDQ} , All banks: inactive state | TBD | TBD | TBD | | 1 |
| I _{DD5} | Auto-Refresh Current t _{CK} = min; I _{REFC} = min, t _{REFI} = min, Auto-Refresh command cycling, 0 V ≤ V _{IN} ≤ V _{IL} (AC) (max), V _{IH} (AC) (min) ≤ V _{IN} ≤ V _{DDQ} , Address change up to 2 times during minimum I _{REFC} . | TBD | TBD | TBD | | 1 |
| I _{DD6} | Self-Refresh Current Self-Refresh mode PD = 0.2 V, 0 V ≤ V _{IN} ≤ V _{DDQ} | TBD | TBD | TBD | | |

| SYMBOL | PARAMETER | | MIN | MAX | UNIT | NOTES |
|----------------------|-----------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------|-----|-----|------|-------|
| I _{LI} | Input Leakage Current (0 V ≤ V _{IN} ≤ V _{DDQ} , all other pins not under test = 0 V) | | -5 | 5 | μA | |
| I _{LO} | Output Leakage Current (Output disabled, 0 V ≤ V _{OUT} ≤ V _{DDQ}) | | -5 | 5 | μA | |
| I _{REF} | V _{REF} Current | | -5 | 5 | μA | |
| I _{OH} (DC) | Normal Output Driver | Output Source DC Current V _{OH} = V _{DDQ} - 0.4V | -10 | — | mA | 3 |
| I _{OL} (DC) | | Output Sink DC Current V _{OL} = 0.4V | 10 | — | | 3 |
| I _{OH} (DC) | Strong Output Driver | Output Source DC Current V _{OH} = V _{DDQ} - 0.4V | -11 | — | | 3 |
| I _{OL} (DC) | | Output Sink DC Current V _{OL} = 0.4V | 11 | — | | 3 |
| I _{OH} (DC) | Weaker Output Driver | Output Source DC Current V _{OH} = V _{DDQ} - 0.4V | -8 | — | | 3 |
| I _{OL} (DC) | | Output Sink DC Current V _{OL} = 0.4V | 8 | — | | 3 |
| I _{OH} (DC) | Weakest Output Driver | Output Source DC Current V _{OH} = V _{DDQ} - 0.4V | -7 | — | | 3 |
| I _{OL} (DC) | | Output Sink DC Current V _{OL} = 0.4V | 7 | — | | 3 |

- Notes: 1. These parameters depend on the cycle rate and these values are measured at a cycle rate with the minimum values of t_{CK}, t_{RC} and I_{RC}.
2. These parameters depend on the output loading. The specified values are obtained with the output open.
3. Refer to output driver characteristics for the detail. Output Driver Strength is selected by Extended Mode Register.

AC CHARACTERISTICS AND OPERATING CONDITIONS (Notes: 1, 2)**($V_{DD} = 2.5V \pm 0.15V$, $V_{DDQ} = 2.5V \pm 0.15V$, $T_{CASE} = 0 \sim 85^{\circ}C$)**

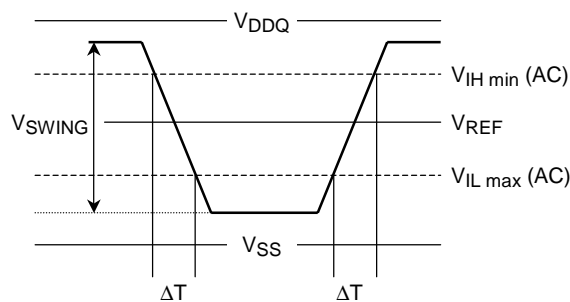
| SYMBOL | PARAMETER | | -50 | | -55 | | -60 | | UNIT | NOTES |
|--------------|----------------------------------------------------------|-----------|---------------------------|---------------------------|---------------------------|---------------------------|---------------------------|---------------------------|------|-------|
| | | | MIN | MAX | MIN | MAX | MIN | MAX | | |
| t_{RC} | Random Cycle Time | | 25 | — | 27.5 | — | 30 | — | ns | 3 |
| t_{CK} | Clock Cycle Time | $C_L = 3$ | 5.5 | 8.5 | 6.0 | 12.0 | 6.5 | 12.0 | | 3 |
| | | $C_L = 4$ | 5.0 | 8.5 | 5.5 | 12.0 | 6.0 | 12.0 | | 3 |
| t_{RAC} | Random Access Time | | — | 22.0 | — | 24.0 | — | 26.0 | | 3 |
| t_{CH} | Clock High Time | | $0.45 \times t_{CK}$ | — | $0.45 \times t_{CK}$ | — | $0.45 \times t_{CK}$ | — | | 3 |
| t_{CL} | Clock Low Time | | $0.45 \times t_{CK}$ | — | $0.45 \times t_{CK}$ | — | $0.45 \times t_{CK}$ | — | | 3 |
| t_{CKQS} | QS Access Time from CLK | | -0.65 | 0.65 | -0.75 | 0.75 | -0.85 | 0.85 | | 3, 8 |
| t_{QSQ} | Data Output Skew from DQS | | — | 0.4 | — | 0.45 | — | 0.55 | | 4 |
| t_{AC} | Data Access Time from CLK | | -0.65 | 0.65 | -0.75 | 0.75 | -0.85 | 0.85 | | 3, 8 |
| t_{OH} | Data Output Hold Time from CLK | | -0.65 | 0.65 | -0.75 | 0.75 | -0.85 | 0.85 | | 3, 8 |
| t_{QSPRE} | DQS (read) Preamble Pulse Width | | $0.9 \times t_{CK} - 0.2$ | $1.1 \times t_{CK} + 0.2$ | $0.9 \times t_{CK} - 0.2$ | $1.1 \times t_{CK} + 0.2$ | $0.9 \times t_{CK} - 0.2$ | $1.1 \times t_{CK} + 0.2$ | | 3, 8 |
| t_{HP} | CLK half period (minimum of Actual t_{CH} , t_{CL}) | | $\min(t_{CH}, t_{CL})$ | — | $\min(t_{CH}, t_{CL})$ | — | $\min(t_{CH}, t_{CL})$ | — | | 3 |
| t_{QSP} | DQS (read) Pulse Width | | $t_{HP} - t_{QHS}$ | — | $t_{HP} - t_{QHS}$ | — | $t_{HP} - t_{QHS}$ | — | | 4, 8 |
| t_{QSQV} | Data Output Valid Time from DQS | | $t_{HP} - t_{QHS}$ | — | $t_{HP} - t_{QHS}$ | — | $t_{HP} - t_{QHS}$ | — | | 4, 8 |
| t_{QHS} | DQ Hold Skew factor | | — | 0.55 | — | 0.6 | — | 0.65 | | |
| t_{DQSS} | DQS (write) Low to High Setup Time | | $0.75 \times t_{CK}$ | $1.25 \times t_{CK}$ | $0.75 \times t_{CK}$ | $1.25 \times t_{CK}$ | $0.75 \times t_{CK}$ | $1.25 \times t_{CK}$ | | 3 |
| t_{DSPRE} | DQS (write) Preamble Pulse Width | | $0.4 \times t_{CK}$ | — | $0.4 \times t_{CK}$ | — | $0.4 \times t_{CK}$ | — | | 4 |
| t_{DSPRES} | DQS First Input Setup Time | | 0 | — | 0 | — | 0 | — | | 3 |
| t_{DSPREH} | DQS First Low Input Hold Time | | $0.25 \times t_{CK}$ | — | $0.25 \times t_{CK}$ | — | $0.25 \times t_{CK}$ | — | | 3 |
| t_{DSP} | DQS High or Low Input Pulse Width | | $0.45 \times t_{CK}$ | $0.55 \times t_{CK}$ | $0.45 \times t_{CK}$ | $0.55 \times t_{CK}$ | $0.45 \times t_{CK}$ | $0.55 \times t_{CK}$ | | 4 |
| t_{DSS} | DQS Input Falling Edge to Clock Setup Time | $C_L = 3$ | 1.3 | — | 1.4 | — | 1.5 | — | | 3, 4 |
| | | $C_L = 4$ | 1.3 | — | 1.4 | — | 1.5 | — | | 3, 4 |
| t_{DSPST} | DQS (write) Postamble Pulse Width | | $0.45 \times t_{CK}$ | — | $0.45 \times t_{CK}$ | — | $0.45 \times t_{CK}$ | — | | 4 |
| t_{DSPSTH} | DQS (write) Postamble Hold Time | $C_L = 3$ | 1.3 | — | 1.4 | — | 1.5 | — | | 3, 4 |
| | | $C_L = 4$ | 1.3 | — | 1.4 | — | 1.5 | — | | 3, 4 |
| t_{DSSK} | UDQS – LDQS Skew (X16) | | $-0.5 \times t_{CK}$ | $0.5 \times t_{CK}$ | $-0.5 \times t_{CK}$ | $0.5 \times t_{CK}$ | $-0.5 \times t_{CK}$ | $0.5 \times t_{CK}$ | | |
| t_{DS} | Data Input Setup Time from DQS | | 0.5 | — | 0.5 | — | 0.6 | — | | 4 |
| t_{DH} | Data Input Hold Time from DQS | | 0.5 | — | 0.5 | — | 0.6 | — | | 4 |
| t_{IS} | Command/Address Input Setup Time | | 0.9 | — | 0.9 | — | 1.0 | — | | 3 |
| t_{IH} | Command/Address Input Hold Time | | 0.9 | — | 0.9 | — | 1.0 | — | | 3 |

AC CHARACTERISTICS AND OPERATING CONDITIONS (Notes: 1, 2) (continued)

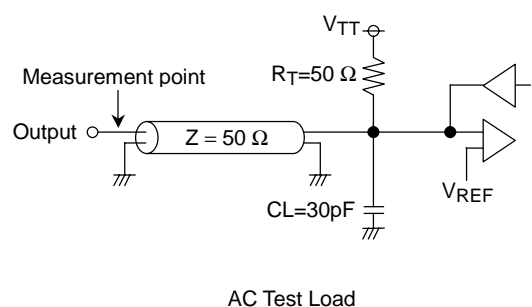
| SYMBOL | PARAMETER | | -50 | | -55 | | -60 | | UNIT | NOTES |
|--------------------|----------------------------------------------------------------|--------------------|------------------------|------|------------------------|------|------------------------|------|-------|-------|
| | | | MIN | MAX | MIN | MAX | MIN | MAX | | |
| t _{LZ} | Data-out Low Impedance Time from CLK | | -0.65 | — | -0.75 | — | -0.85 | — | | 3,6,8 |
| t _{HZ} | Data-out High Impedance Time from CLK | | — | 0.65 | — | 0.75 | — | 0.85 | | 3,7,8 |
| t _{QSLZ} | DQS-out Low Impedance Time from CLK | | -0.65 | — | -0.75 | — | -0.85 | — | | 3,6,8 |
| t _{QSHZ} | DQS-out High Impedance Time from CLK | | -0.65 | 0.65 | -0.75 | 0.75 | -0.85 | 0.85 | | 3,7,8 |
| t _{QPDH} | Last output to $\overline{\text{PD}}$ High Hold Time | | 0 | — | 0 | — | 0 | — | ns | |
| t _{PDEX} | Power Down Exit Time | | 0.9 | — | 0.9 | — | 1.0 | — | | 3 |
| t _T | Input Transition Time | | 0.1 | 1 | 0.1 | 1 | 0.1 | 1 | | |
| t _{FPDL} | $\overline{\text{PD}}$ Low Input Window for Self-Refresh Entry | | -0.5 × t _{CK} | 5 | -0.5 × t _{CK} | 5 | -0.5 × t _{CK} | 5 | | 3 |
| t _{REFI} | Auto-Refresh Average Interval | | 0.4 | 7.8 | 0.4 | 7.8 | 0.4 | 7.8 | μs | 5 |
| t _{PAUSE} | Pause Time after Power-up | | 200 | — | 200 | — | 200 | — | | |
| I _{RC} | Random Read/Write Cycle Time (applicable to same bank) | C _L = 3 | 5 | — | 5 | — | 5 | — | cycle | |
| | | C _L = 4 | 5 | — | 5 | — | 5 | — | | |
| I _{RCD} | RDA/WRA to LAL Command Input Delay (applicable to same bank) | | 1 | 1 | 1 | 1 | 1 | 1 | | |
| I _{RAS} | LAL to RDA/WRA Command Input Delay (applicable to same bank) | C _L = 3 | 4 | — | 4 | — | 4 | — | | |
| | | C _L = 4 | 4 | — | 4 | — | 4 | — | | |
| I _{RBD} | Random Bank Access Delay (applicable to other bank) | | 2 | — | 2 | — | 2 | — | | |
| I _{RWD} | LAL following RDA to WRA Delay (applicable to other bank) | B _L = 2 | 2 | — | 2 | — | 2 | — | | |
| | | B _L = 4 | 3 | — | 3 | — | 3 | — | | |
| I _{WRD} | LAL following WRA to RDA Delay (applicable to other bank) | | 1 | — | 1 | — | 1 | — | | |
| I _{RSC} | Mode Register Set Cycle Time | C _L = 3 | 5 | — | 5 | — | 5 | — | | |
| | | C _L = 4 | 5 | — | 5 | — | 5 | — | | |
| I _{PD} | $\overline{\text{PD}}$ Low to Inactive State of Input Buffer | | — | 1 | — | 1 | — | 1 | | |
| I _{PDA} | $\overline{\text{PD}}$ High to Active State of Input Buffer | | — | 1 | — | 1 | — | 1 | | |
| I _{PDV} | Power down mode valid from REF command | C _L = 3 | 15 | — | 15 | — | 15 | — | | |
| | | C _L = 4 | 18 | — | 18 | — | 18 | — | | |
| I _{REFC} | Auto-Refresh Cycle Time | C _L = 3 | 15 | — | 15 | — | 15 | — | | |
| | | C _L = 4 | 18 | — | 18 | — | 18 | — | | |
| I _{CKD} | REF Command to Clock Input Disable at Self-Refresh Entry | | 16 | — | 16 | — | 16 | — | | |
| I _{LOCK} | DLL Lock-on Time (applicable to RDA command) | | 200 | — | 200 | — | 200 | — | | |

AC TEST CONDITIONS

| SYMBOL | PARAMETER | VALUE | UNIT | NOTES |
|------------------------|---------------------------------------------|--------------------|------|-------|
| $V_{IH} \text{ (min)}$ | Input High Voltage (minimum) | $V_{REF} + 0.35$ | V | |
| $V_{IL} \text{ (max)}$ | Input Low Voltage (maximum) | $V_{REF} - 0.35$ | V | |
| V_{REF} | Input Reference Voltage | $V_{DDQ}/2$ | V | |
| V_{TT} | Termination Voltage | V_{REF} | V | |
| V_{SWING} | Input Signal Peak to Peak Swing | 1.0 | V | |
| V_r | Differential Clock Input Reference Level | $V_X \text{ (AC)}$ | V | |
| $V_{ID} \text{ (AC)}$ | Input Differential Voltage | 1.5 | V | |
| SLEW | Input Signal Minimum Slew Rate | 1.0 | V/ns | |
| V_{OTR} | Output Timing Measurement Reference Voltage | $V_{DDQ}/2$ | V | 9 |



$$SLEW = (V_{IH \text{ min (AC)}} - V_{IL \text{ max (AC)}}) / \Delta T$$



AC Test Load

Note:

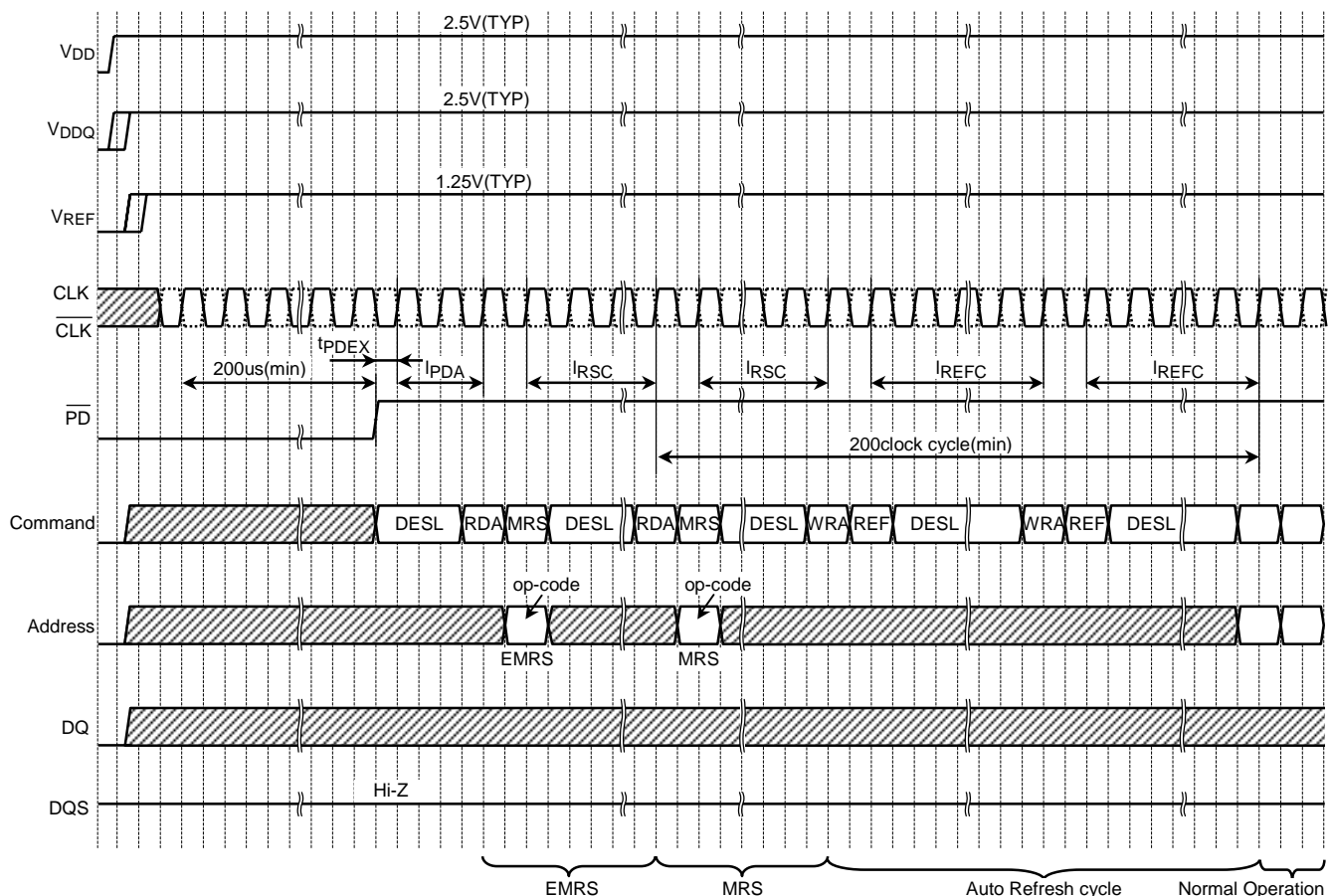
- (1) Transition times are measured between $V_{IH \text{ min (DC)}}$ and $V_{IL \text{ max (DC)}}$.
Transition (rise and fall) of input signals have a fixed slope.
- (2) If the result of nominal calculation with regard to t_{CK} contains more than one decimal place, the result is rounded up to the nearest decimal place.
(i.e., $t_{DQSS} = 0.75 \times t_{CK}$, $t_{CK} = 5 \text{ ns}$, $0.75 \times 5 \text{ ns} = 3.75 \text{ ns}$ is rounded up to 3.8 ns.)
- (3) These parameters are measured from the differential clock (CLK and \overline{CLK}) AC cross point.
- (4) These parameters are measured from signal transition point of DS crossing V_{REF} level.
- (5) The $t_{REFI} \text{ (max)}$ applies to equally distributed refresh method.
The $t_{REFI} \text{ (min)}$ applies to both burst refresh method and distributed refresh method.
In such case, the average interval of eight consecutive Auto-Refresh commands has to be more than 400 ns always. In other words, the number of Auto-Refresh cycles which can be performed within 3.2 μs ($8 \times 400 \text{ ns}$) is to 8 times in the maximum.
- (6) Low Impedance State is specified at $V_{DDQ}/2 \pm 0.2 \text{ V}$ from steady state.
- (7) High Impedance State is specified where output buffer is no longer driven.
- (8) These parameters depend on the clock jitter. These parameters are measured at stable clock.
- (9) Output timing is measured by using Normal driver strength.

POWER UP SEQUENCE

- (1) As for \overline{PD} , being maintained by the low state ($\leq 0.2\text{ V}$) is desirable before a power-supply injection.
- (2) Apply V_{DD} before or at the same time as V_{DDQ} .
- (3) Apply V_{DDQ} before or at the same time as V_{REF} .
- (4) Start clock (CLK, \overline{CLK}) and maintain stable condition for $200\text{ }\mu\text{s}$ (min).
- (5) After stable power and clock, apply DESL and take $\overline{PD} = \text{H}$.
- (6) Issue EMRS to enable DLL and to define driver strength. (Note: 1)
- (7) Issue MRS for set \overline{CAS} latency (CL), Burst Type (BT), and Burst Length (BL). (Note: 1)
- (8) Issue two or more Auto-Refresh commands (Note: 1).
- (9) Ready for normal operation after 200 clocks from Extended Mode Register programming.

Notes:

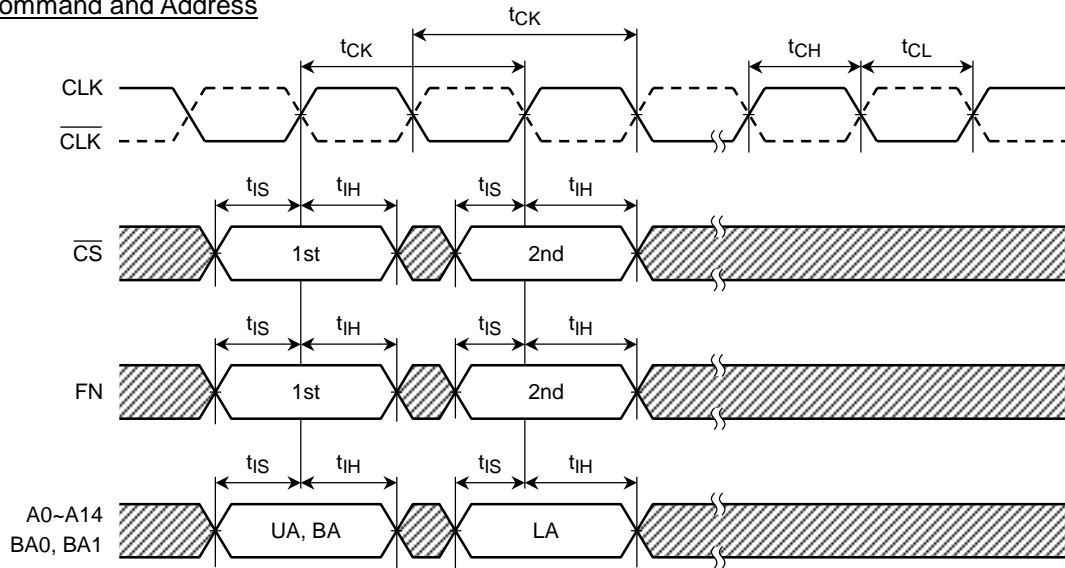
- (1) Sequence 6, 7 and 8 can be issued in random order.
- (2) L = Logic Low, H = Logic High



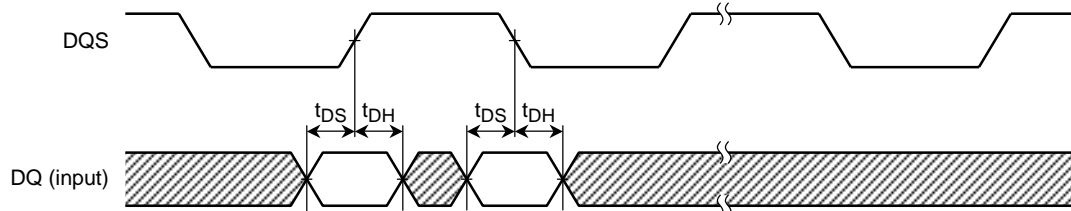
TIMING DIAGRAMS

Input Timing

Command and Address

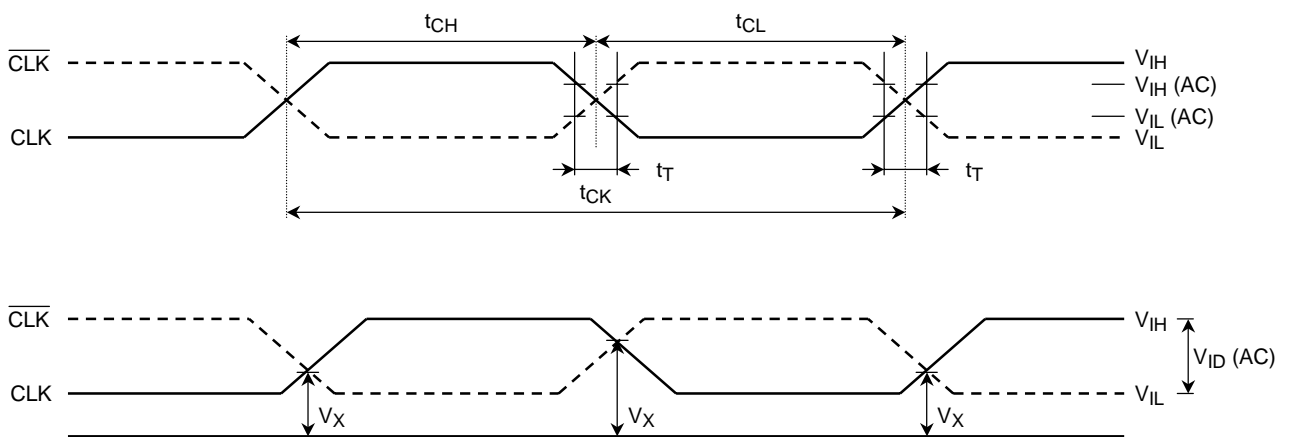


Data

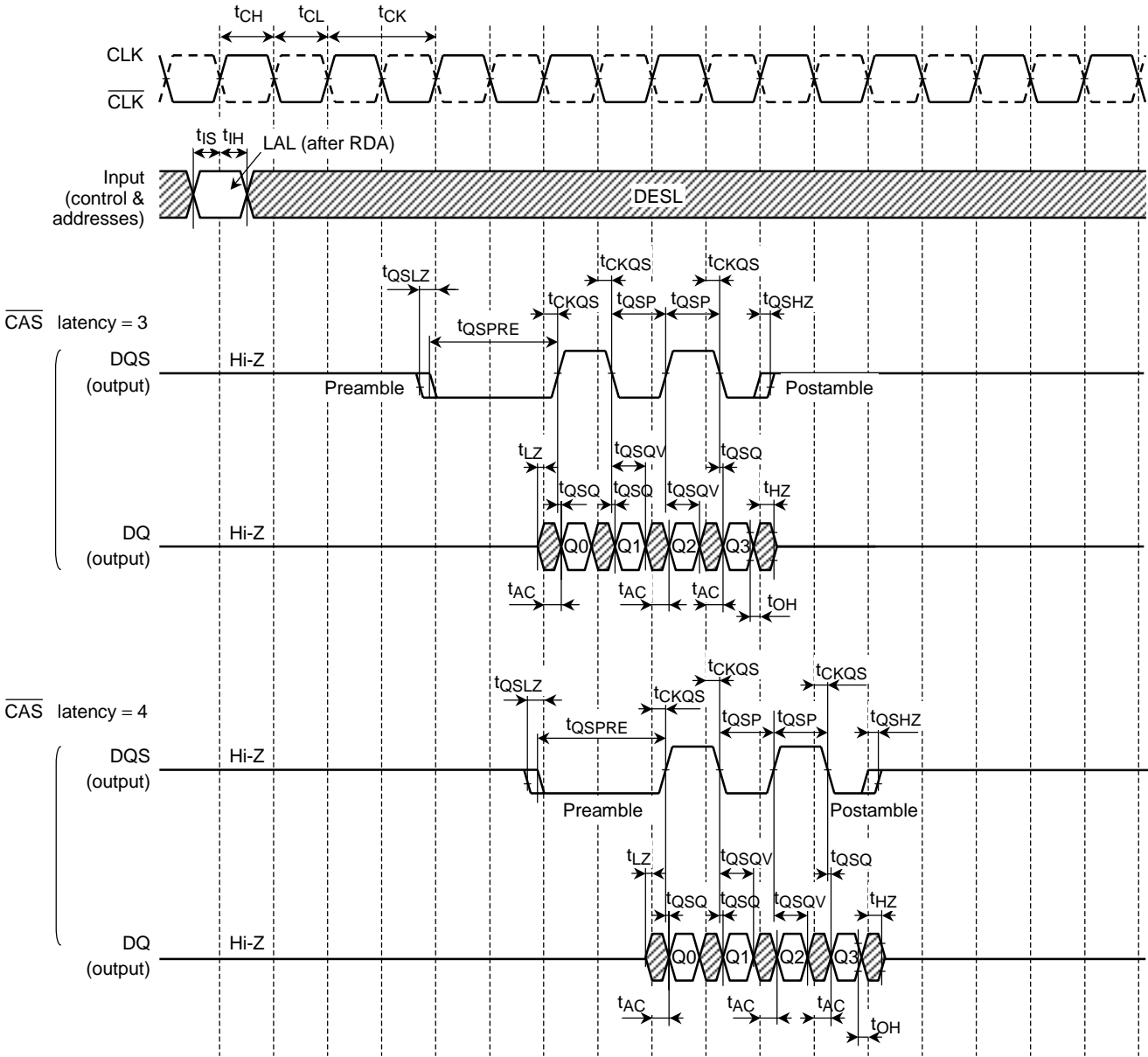


Refer to the Command Truth Table.

Timing of the CLK, $\overline{\text{CLK}}$



Read Timing (Burst Length = 4)

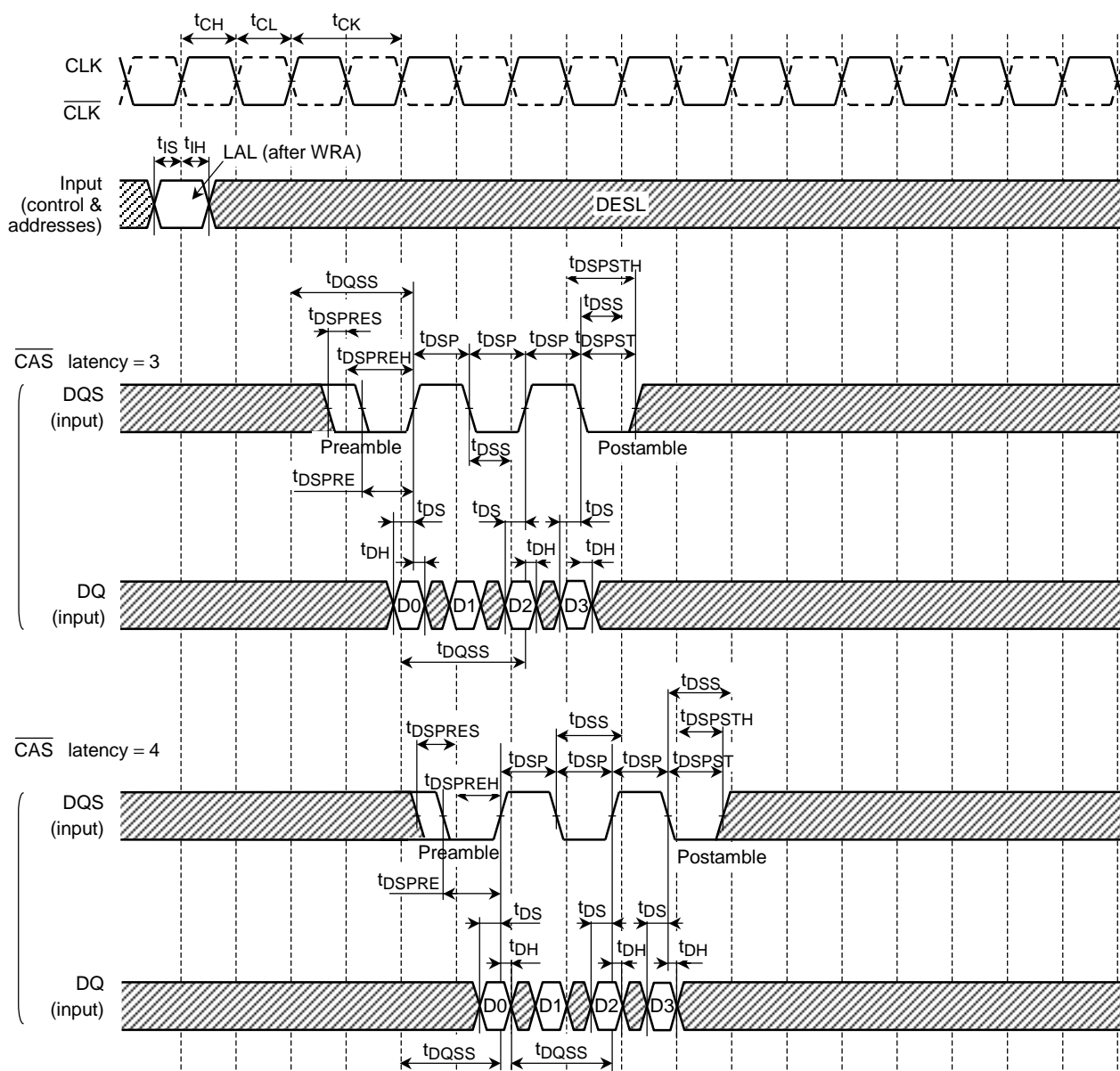


Note: DQ0 to DQ15 are aligned with DQS or LDQS/UDQS.

The correspondence of LDQS, UDQS to DQ. (TC59LM913AMB)

| | |
|------|----------|
| LDQS | DQ0~DQ7 |
| UDQS | DQ8~DQ15 |

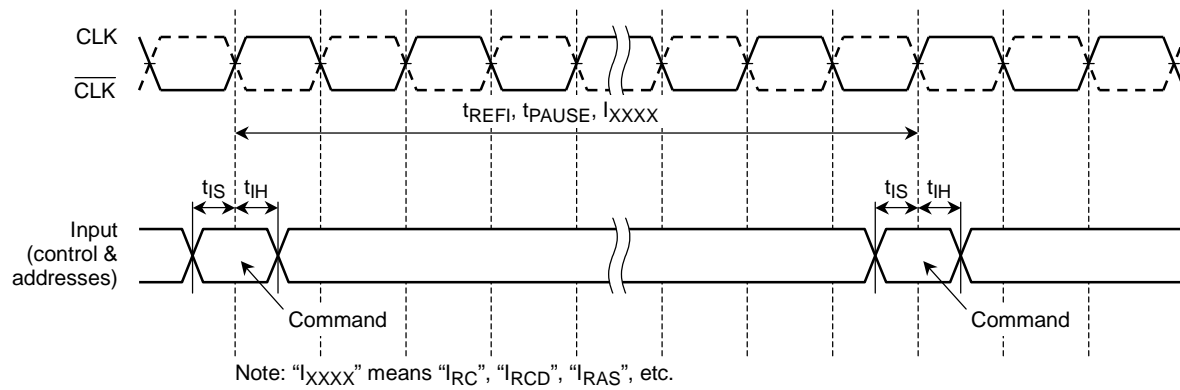
Write Timing (Burst Length = 4)



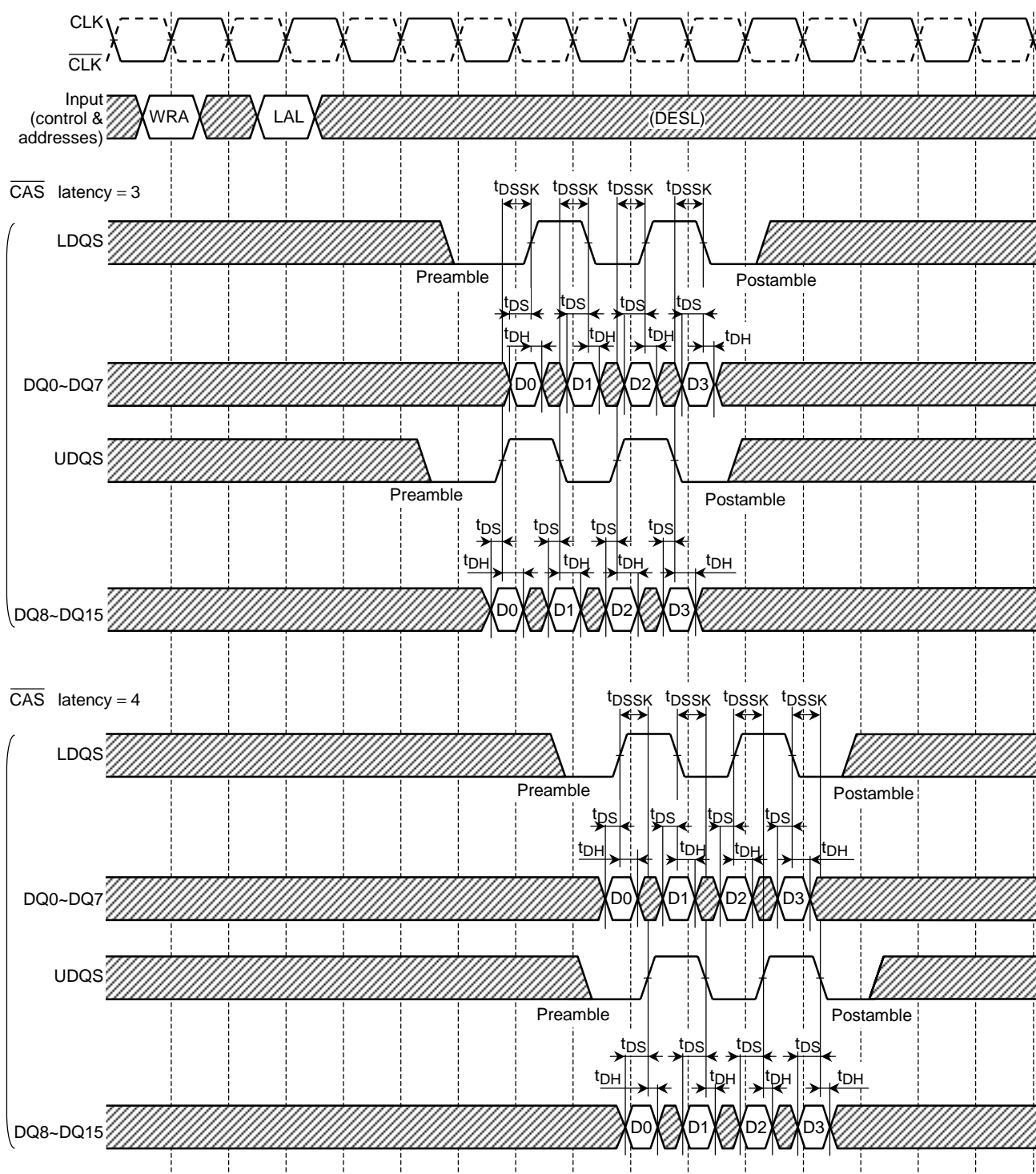
Note: DQ0 to DQ15 are sampled at both edges of DQS or LDQS / UDQS.

The correspondence of LDQS, UDQS to DQ. (TC59LM913AMB)

| | |
|------|----------|
| LDQS | DQ0~DQ7 |
| UDQS | DQ8~DQ15 |

tREFI, tPAUSE, I_{XXXX} Timing


Write Timing (x16 device) (Burst Length =4)



FUNCTION TRUTH TABLE (Notes: 1, 2, 3)

Command Truth Table (Notes: 4)

• The First Command

| SYMBOL | FUNCTION | \overline{CS} | FN | BA1~BA0 | A14~A9 | A8 | A7 | A6~A0 |
|--------|-----------------------|-----------------|----|---------|--------|----|----|-------|
| DESL | Device Deselect | H | × | × | × | × | × | × |
| RDA | Read with Auto-close | L | H | BA | UA | UA | UA | UA |
| WRA | Write with Auto-close | L | L | BA | UA | UA | UA | UA |

• The Second Command (The next clock of RDA or WRA command)

| SYMBOL | FUNCTION | \overline{CS} | FN | BA1~BA0 | A14, A13 | A12~A11 | A10~A9 | A8 | A7 | A6~A0 |
|--------|---------------------------|-----------------|----|---------|----------|---------|--------|----|----|-------|
| LAL | Lower Address Latch (x16) | H | × | × | V | V | × | × | LA | LA |
| LAL | Lower Address Latch (x8) | H | × | × | V | × | × | LA | LA | LA |
| REF | Auto-Refresh | L | × | × | × | × | × | × | × | × |
| MRS | Mode Register Set | L | × | V | L | L | L | L | V | V |

- Notes: 1. L = Logic Low, H = Logic High, × = either L or H, V = Valid (specified value), BA = Bank Address, UA = Upper Address, LA = Lower Address
2. All commands are assumed to issue at a valid state.
3. All inputs for command (excluding SELFEX and PDEX) are latched on the crossing point of differential clock input where CLK goes to High.
4. Operation mode is decided by the combination of 1st command and 2nd command. Refer to "STATE DIAGRAM" and the command table below.

Read Command Table

| COMMAND (SYMBOL) | \overline{CS} | FN | BA1~BA0 | A14~A9 | A8 | A7 | A6~A0 | NOTES |
|------------------|-----------------|----|---------|--------|----|----|-------|-------|
| RDA (1st) | L | H | BA | UA | UA | UA | UA | |
| LAL (2nd) | H | × | × | × | LA | LA | LA | 5 |

Note 5 : For x16 device, A8 is "X" (either L or H).

Write Command Table

• TC59LM913AMB

| COMMAND(SYMBOL) | \overline{CS} | FN | BA1~BA0 | A14 | A13 | A12 | A11 | A10~A9 | A8 | A7 | A6~A0 |
|-----------------|-----------------|----|---------|------|------|------|------|--------|----|----|-------|
| WRA (1st) | L | L | BA | UA | UA | UA | UA | UA | UA | UA | UA |
| LAL (2nd) | H | × | × | LVW0 | LVW1 | UVW0 | UVW1 | × | × | LA | LA |

• TC59LM905AMB

| COMMAND(SYMBOL) | \overline{CS} | FN | BA1~BA0 | A14 | A13 | A12 | A11 | A10~A9 | A8 | A7 | A6~A0 |
|-----------------|-----------------|----|---------|-----|-----|-----|-----|--------|----|----|-------|
| WRA (1st) | L | L | BA | UA | UA | UA | UA | UA | UA | UA | UA |
| LAL (2nd) | H | × | × | VW0 | VW1 | × | × | × | LA | LA | LA |

Notes: 6. A14 ~ A11 are used for Variable Write Length (VW) control at Write Operation.

FUNCTION TRUTH TABLE (continued)VW Truth Table

| Burst Length | Function | VW0 | VW1 |
|--------------|-----------------------|-----|-----|
| BL=2 | Write All Words | L | × |
| | Write First One Word | H | × |
| BL=4 | Reserved | L | L |
| | Write All Words | H | L |
| | Write First Two Words | L | H |
| | Write First One Word | H | H |

Note 7 : For x16 device, LVW0 and LVW1 control DQ0~DQ7.

UVW0 and UVW1 control DQ8~DQ15.

Mode Register Set Command Table

| COMMAND (SYMBOL) | \overline{CS} | FN | BA1~BA0 | A14~A9 | A8 | A7 | A6~A0 | NOTES |
|------------------|-----------------|----|---------|--------|----|----|-------|-------|
| RDA (1st) | L | H | × | × | × | × | × | |
| MRS (2nd) | L | × | V | V | V | V | V | 8 |

Notes: 8. Refer to "MODE REGISTER TABLE".

Auto-Refresh Command Table

| FUNCTION | COMMAND (SYMBOL) | CURRENT STATE | \overline{PD} | | \overline{CS} | FN | BA1~BA0 | A14~A9 | A8 | A7 | A6~A0 | NOTES |
|--------------|------------------|---------------|-----------------|---|-----------------|----|---------|--------|----|----|-------|-------|
| | | | n-1 | n | | | | | | | | |
| Active | WRA (1st) | Standby | H | H | L | L | × | × | × | × | × | |
| Auto-Refresh | REF (2nd) | Active | H | H | L | × | × | × | × | × | × | |

Self-Refresh Command Table

| FUNCTION | COMMAND (SYMBOL) | CURRENT STATE | \overline{PD} | | \overline{CS} | FN | BA1~BA0 | A14~A9 | A8 | A7 | A6~A0 | NOTES |
|-----------------------|------------------|---------------|-----------------|---|-----------------|----|---------|--------|----|----|-------|-------|
| | | | n-1 | n | | | | | | | | |
| Active | WRA (1st) | Standby | H | H | L | L | × | × | × | × | × | |
| Self-Refresh Entry | REF (2nd) | Active | H | L | L | × | × | × | × | × | × | 9, 10 |
| Self-Refresh Continue | — | Self-Refresh | L | L | × | × | × | × | × | × | × | |
| Self-Refresh Exit | SELFEX | Self-Refresh | L | H | H | × | × | × | × | × | × | 11 |

Power Down Table

| FUNCTION | COMMAND (SYMBOL) | CURRENT STATE | \overline{PD} | | \overline{CS} | FN | BA1~BA0 | A14~A9 | A8 | A7 | A6~A0 | NOTES |
|---------------------|------------------|---------------|-----------------|---|-----------------|----|---------|--------|----|----|-------|-------|
| | | | n-1 | n | | | | | | | | |
| Power Down Entry | PDEN | Standby | H | L | H | × | × | × | × | × | × | 10 |
| Power Down Continue | — | Power Down | L | L | × | × | × | × | × | × | × | |
| Power Down Exit | PDEX | Power Down | L | H | H | × | × | × | × | × | × | 11 |

Notes: 9. \overline{PD} has to be brought to Low within $t_{F\overline{PD}}$ from REF command.

10. \overline{PD} should be brought to Low after DQ's state turned high impedance.

11. When \overline{PD} is brought to High from Low, this function is executed asynchronously.

FUNCTION TRUTH TABLE (continued)

| CURRENT STATE | PD | | \overline{CS} | FN | ADDRESS | COMMAND | ACTION | NOTES |
|-------------------------|-----|---|-----------------|----|---------|-------------------|-----------------------------------------------------|-------|
| | n-1 | n | | | | | | |
| Idle | H | H | H | x | x | DESL | NOP | |
| | H | H | L | H | BA, UA | RDA | Row activate for Read | |
| | H | H | L | L | BA, UA | WRA | Row activate for Write | |
| | H | L | H | x | x | PDEN | Power Down Entry | 12 |
| | H | L | L | x | x | — | Illegal | |
| | L | x | x | x | x | — | Refer to Power Down State | |
| Row Active for Read | H | H | H | x | LA | LAL | Begin Read | |
| | H | H | L | x | Op-code | MRS/EMRS | Access to Mode Register | |
| | H | L | H | x | x | PDEN | Illegal | |
| | H | L | L | x | x | MRS/EMRS | Illegal | |
| | L | x | x | x | x | — | Invalid | |
| Row Active for Write | H | H | H | x | LA | LAL | Begin Write | |
| | H | H | L | x | x | REF | Auto-Refresh | |
| | H | L | H | x | x | PDEN | Illegal | |
| | H | L | L | x | x | REF (self) | Self-Refresh Entry | |
| | L | x | x | x | x | — | Invalid | |
| Read | H | H | H | x | x | DESL | Continue Burst Read to End | |
| | H | H | L | H | BA, UA | RDA | Illegal | 13 |
| | H | H | L | L | BA, UA | WRA | Illegal | 13 |
| | H | L | H | x | x | PDEN | Illegal | |
| | H | L | L | x | x | — | Illegal | |
| | L | x | x | x | x | — | Invalid | |
| Write | H | H | H | x | x | DESL | Data Write & Continue Burst Write to End | |
| | H | H | L | H | BA, UA | RDA | Illegal | 13 |
| | H | H | L | L | BA, UA | WRA | Illegal | 13 |
| | H | L | H | x | x | PDEN | Illegal | |
| | H | L | L | x | x | — | Illegal | |
| | L | x | x | x | x | — | Invalid | |
| Auto-Refreshing | H | H | H | x | x | DESL | NOP → Idle after I _{REFC} | |
| | H | H | L | H | BA, UA | RDA | Illegal | |
| | H | H | L | L | BA, UA | WRA | Illegal | |
| | H | L | H | x | x | PDEN | Self-Refresh Entry | 14 |
| | H | L | L | x | x | — | Illegal | |
| | L | x | x | x | x | — | Refer to Self-Refreshing State | |
| Mode Register Accessing | H | H | H | x | x | DESL | NOP → Idle after I _{RSC} | |
| | H | H | L | H | BA, UA | RDA | Illegal | |
| | H | H | L | L | BA, UA | WRA | Illegal | |
| | H | L | H | x | x | PDEN | Illegal | |
| | H | L | L | x | x | — | Illegal | |
| | L | x | x | x | x | — | Invalid | |
| Power Down | H | x | x | x | x | — | Invalid | |
| | L | L | x | x | x | — | Maintain Power Down Mode | |
| | L | H | H | x | x | PDEX | Exit Power Down Mode → Idle after t _{PDEX} | |
| | L | H | L | x | x | — | Illegal | |
| Self-Refreshing | H | x | x | x | x | — | Invalid | |
| | L | L | x | x | x | — | Maintain Self-Refresh | |
| | L | H | H | x | x | SELF _X | Exit Self-Refresh → Idle after I _{REFC} | |
| | L | H | L | x | x | — | Illegal | |

Notes: 12. Illegal if any bank is not idle.

13. Illegal to bank in specified states; Function may be legal in the bank indicated by Bank Address (BA).

14. Illegal if t_{FPDL} is not satisfied.

MODE REGISTER TABLE

Regular Mode Register (Notes: 1)

| ADDRESS | BA1 ^{*1} | BA0 ^{*1} | A14~A8 | A7 ^{*3} | A6~A4 | A3 | A2~A0 |
|----------|-------------------|-------------------|--------|------------------|-------|----|-------|
| Register | 0 | 0 | 0 | TE | CL | BT | BL |

| A7 | TEST MODE (TE) |
|----|-------------------|
| 0 | Regular (default) |
| 1 | Test Mode Entry |

| A3 | BURST TYPE (BT) |
|----|-----------------|
| 0 | Sequential |
| 1 | Interleave |

| A6 | A5 | A4 | CAS LATENCY (CL) |
|----|----|----|------------------------|
| 0 | 0 | × | Reserved ^{*2} |
| 0 | 1 | 0 | Reserved ^{*2} |
| 0 | 1 | 1 | 3 |
| 1 | 0 | 0 | 4 |
| 1 | 0 | 1 | Reserved ^{*2} |
| 1 | 1 | 0 | Reserved ^{*2} |
| 1 | 1 | 1 | Reserved ^{*2} |

| A2 | A1 | A0 | BURST LENGTH (BL) |
|----|----|----|------------------------|
| 0 | 0 | 0 | Reserved ^{*2} |
| 0 | 0 | 1 | 2 |
| 0 | 1 | 0 | 4 |
| 0 | 1 | 1 | Reserved ^{*2} |
| 1 | × | × | |

Extended Mode Register (Notes: 4)

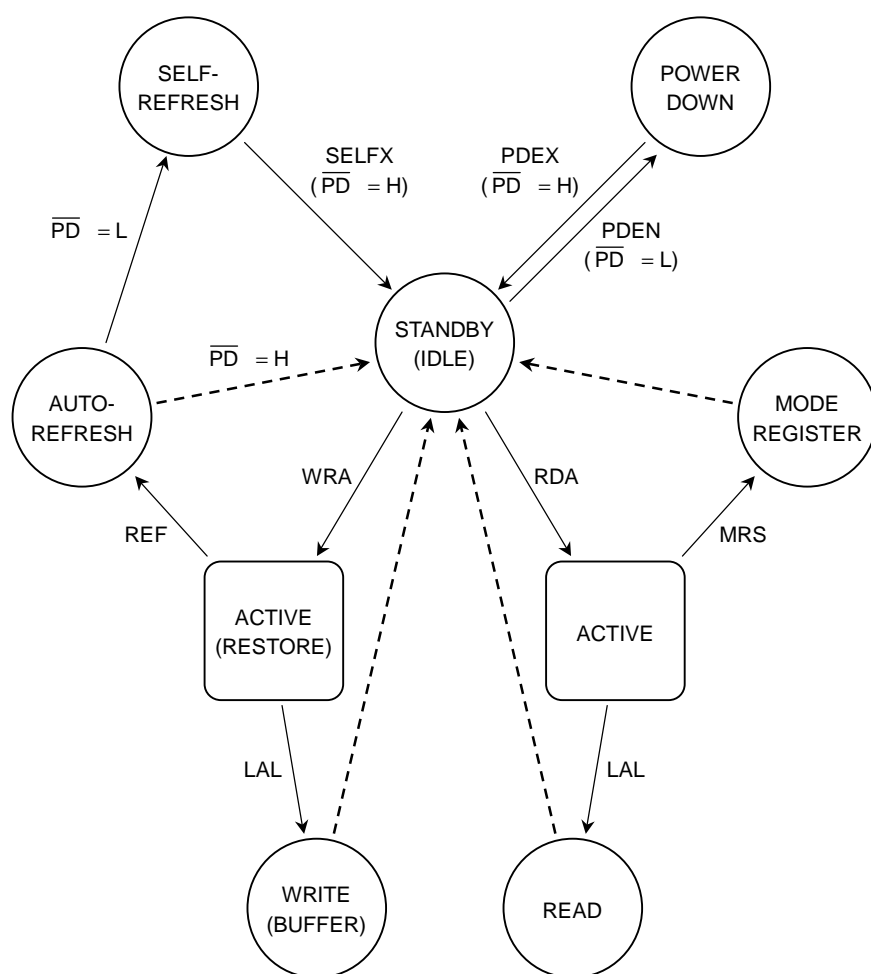
| ADDRESS | BA1 ^{*4} | BA0 ^{*4} | A14~A12 | A11 | A10~A7 | A6 | A5~A2 | A1 | A0 ^{*5} |
|----------|-------------------|-------------------|---------|-----|--------|-----|-------|-----|------------------|
| Register | 0 | 1 | 0 | 0 | 0 | DIC | 0 | DIC | DS |

| A6 | A1 | OUTPUT DRIVE IMPEDANCE CONTROL (DIC) |
|----|----|--------------------------------------|
| 0 | 0 | Normal Output Driver |
| 0 | 1 | Strong Output Driver |
| 1 | 0 | Weaker Output Driver |
| 1 | 1 | Weakest Output Driver |

| A0 | DLL SWITCH (DS) |
|----|-----------------|
| 0 | DLL Enable |
| 1 | DLL Disable |

- Notes: 1. Regular Mode Register is chosen using the combination of BA0 = 0 and BA1 = 0.
2. "Reserved" places in Regular Mode Register should not be set.
3. A7 in Regular Mode Register must be set to "0" (low state).
Because Test Mode is specific mode for supplier.
4. Extended Mode Register is chosen using the combination of BA0 = 1 and BA1 = 0.
5. A0 in Extended Mode Register must be set to "0" to enable DLL for normal operation.

STATE DIAGRAM

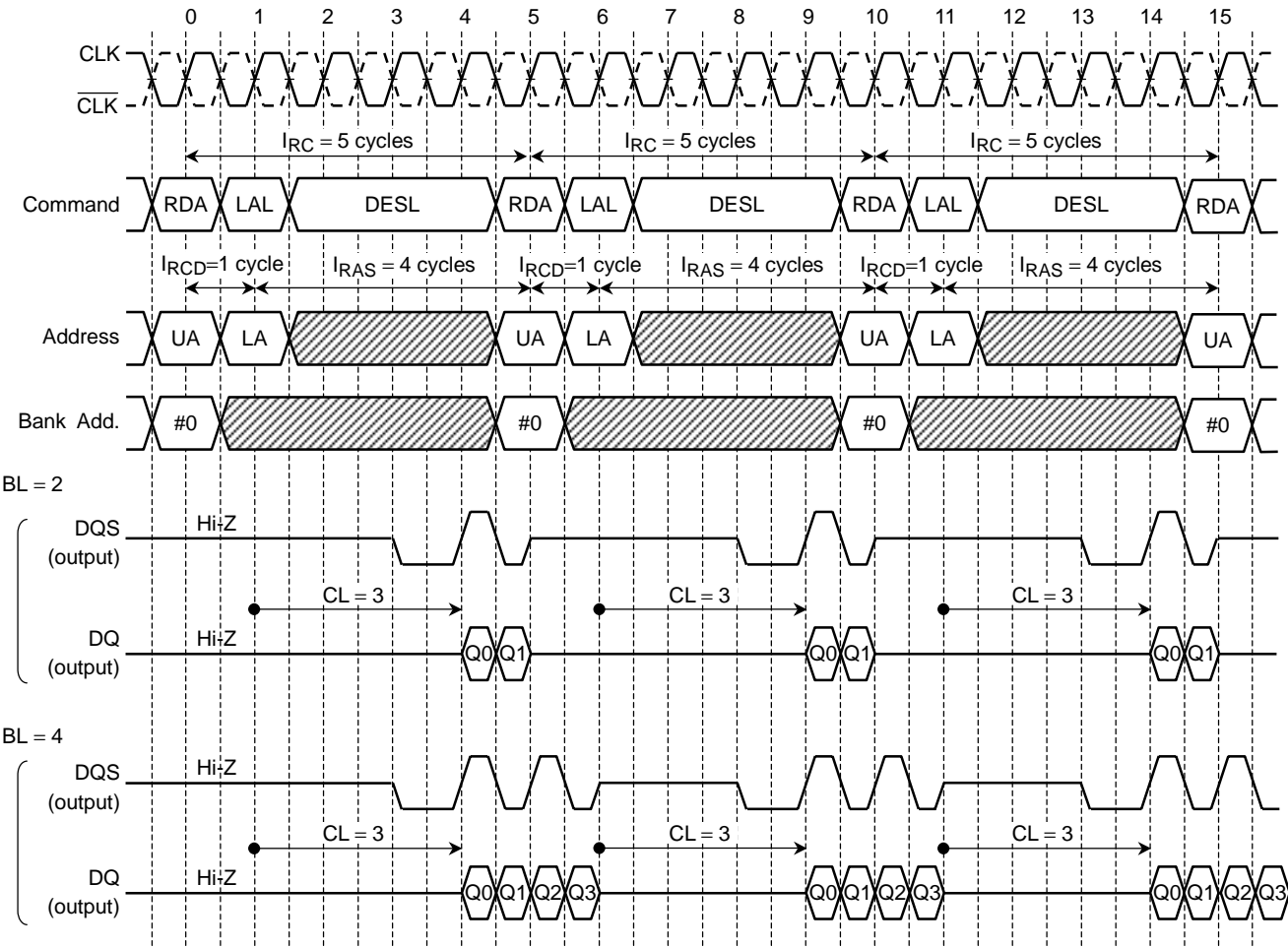


—→ Command input
 - - -→ Automatic return

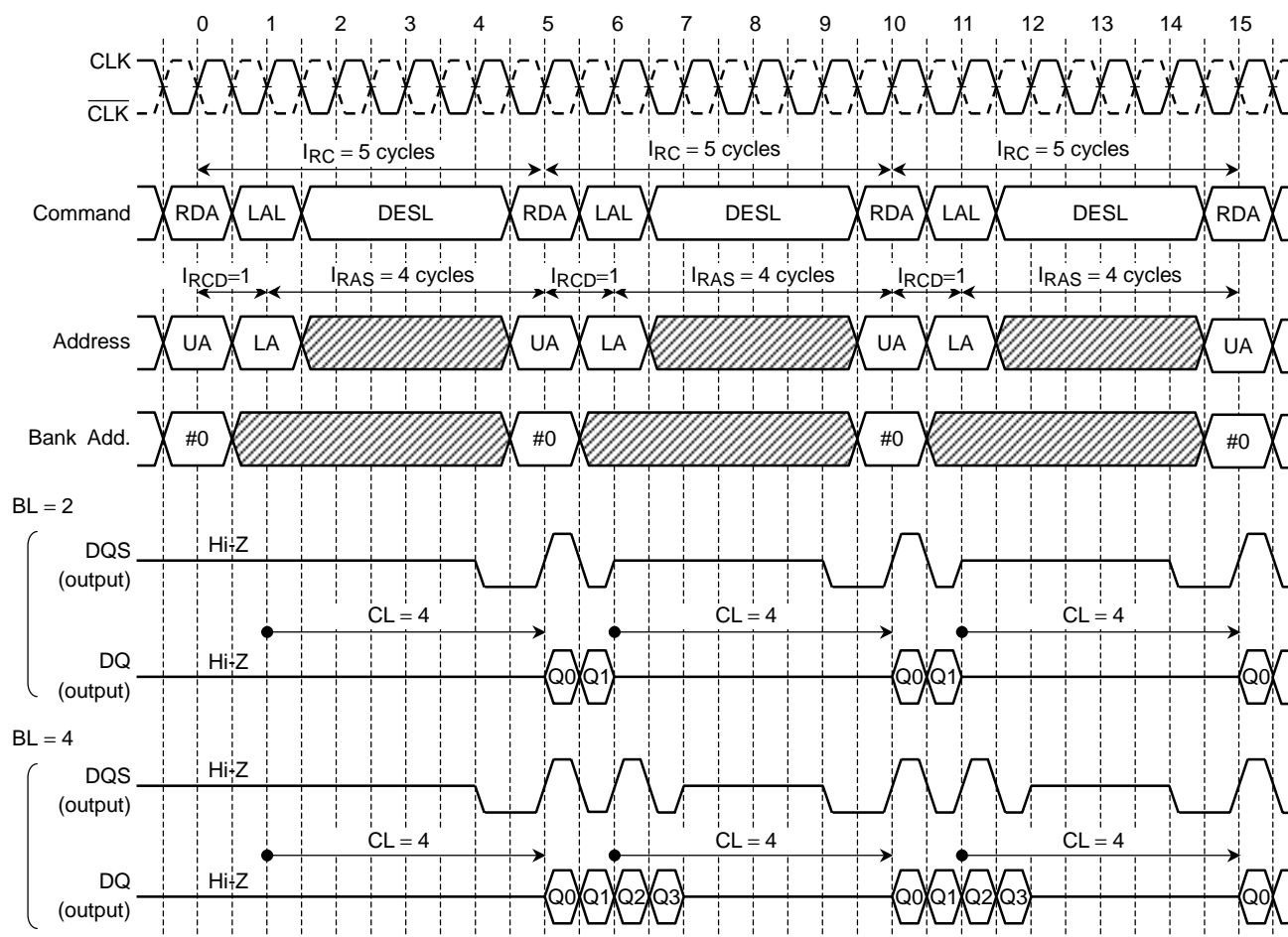
The second command at Active state must be issued 1 clock after RDA or WRA command input.

TIMING DIAGRAMS

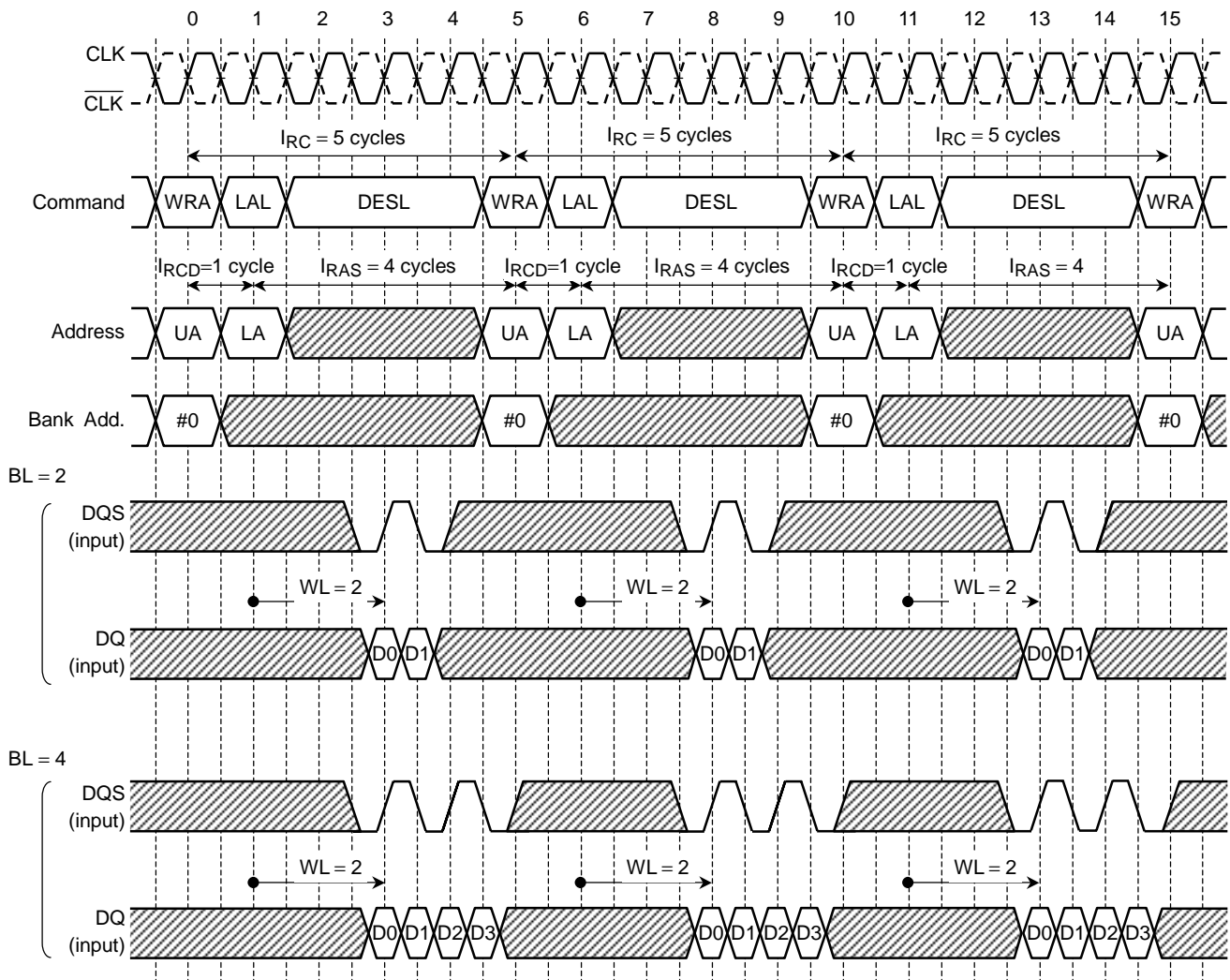
SINGLE BANK READ TIMING (CL = 3)



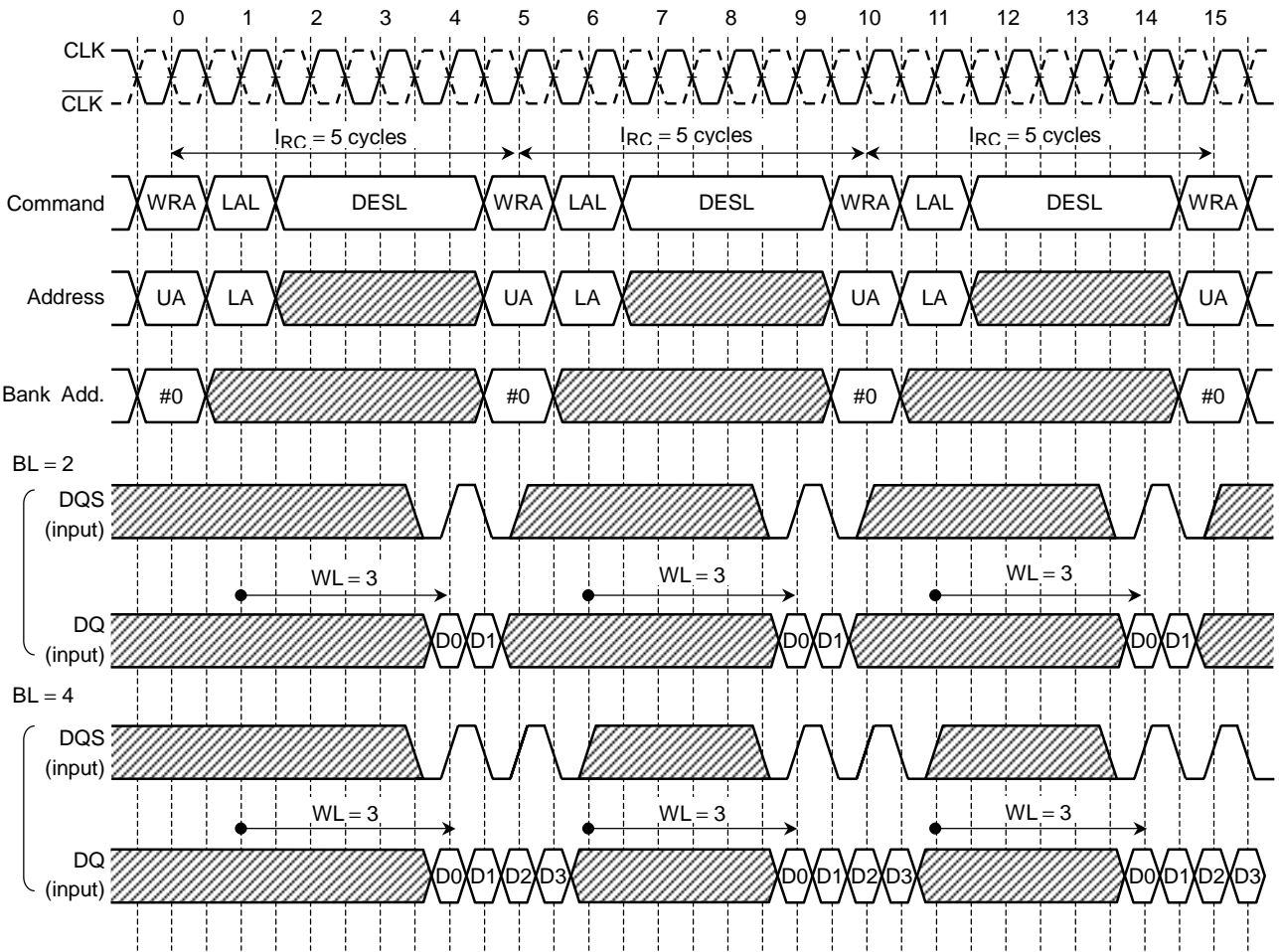
SINGLE BANK READ TIMING (CL = 4)



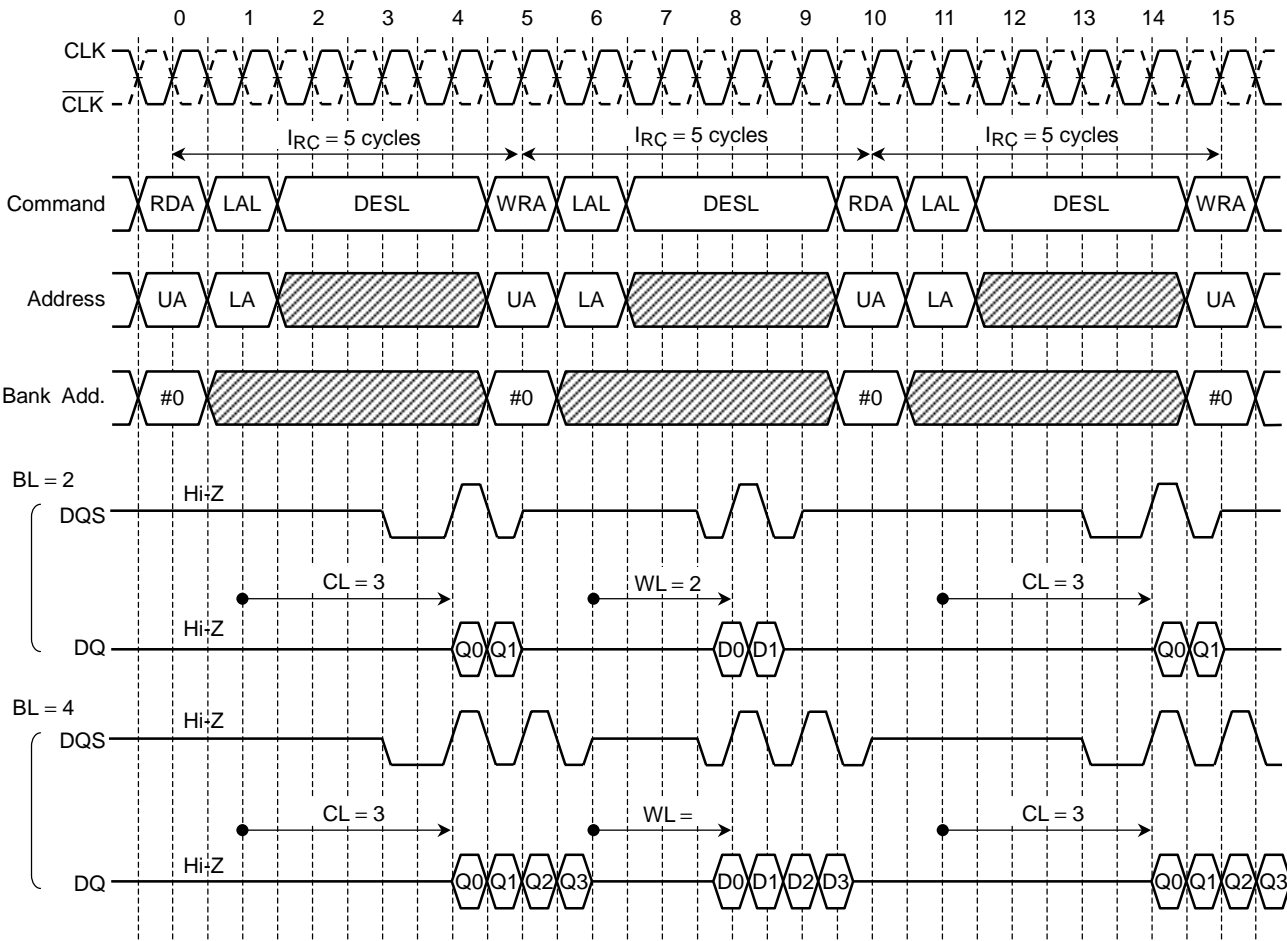
SINGLE BANK WRITE TIMING (CL = 3)



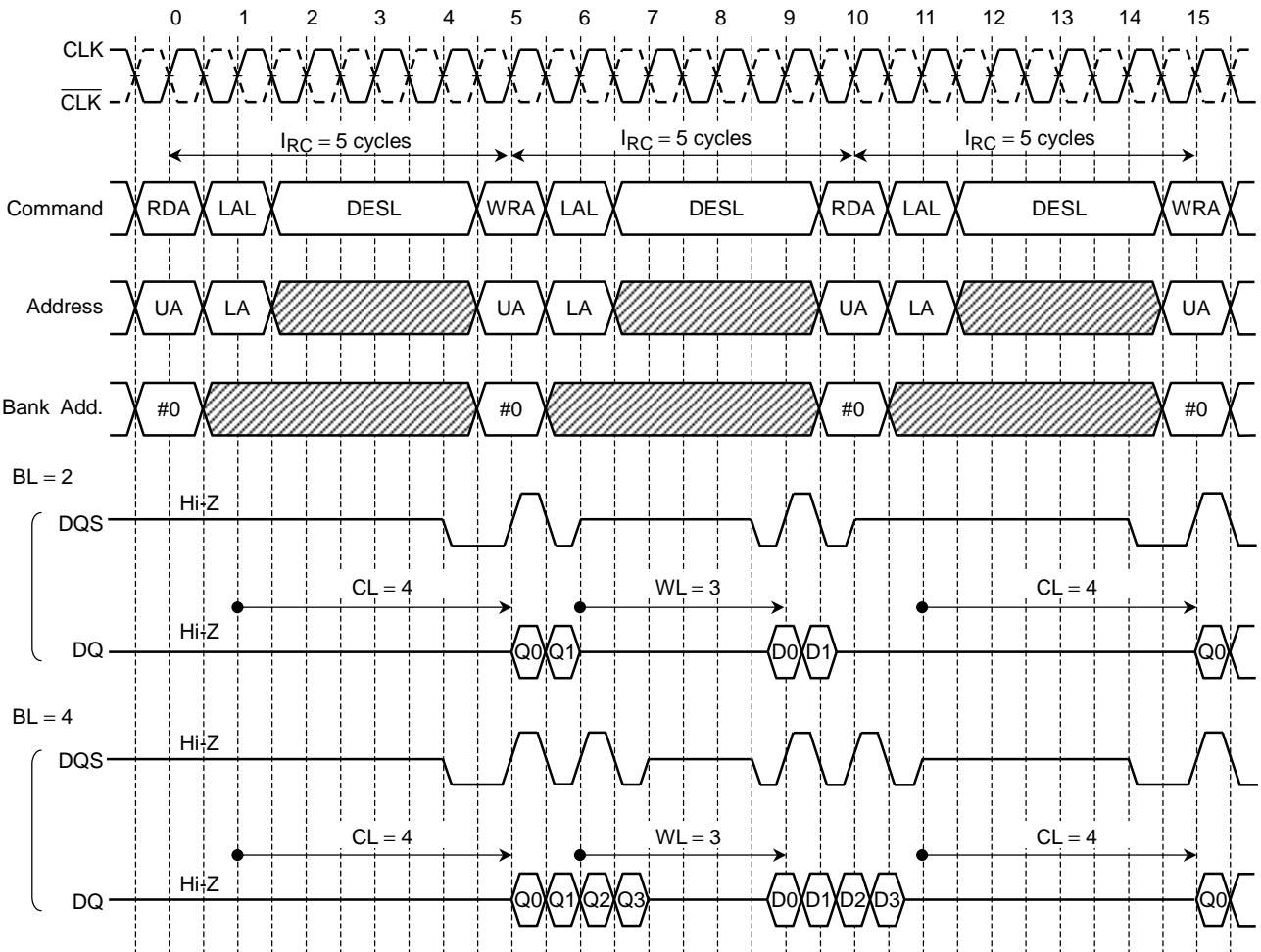
SINGLE BANK WRITE TIMING (CL = 4)



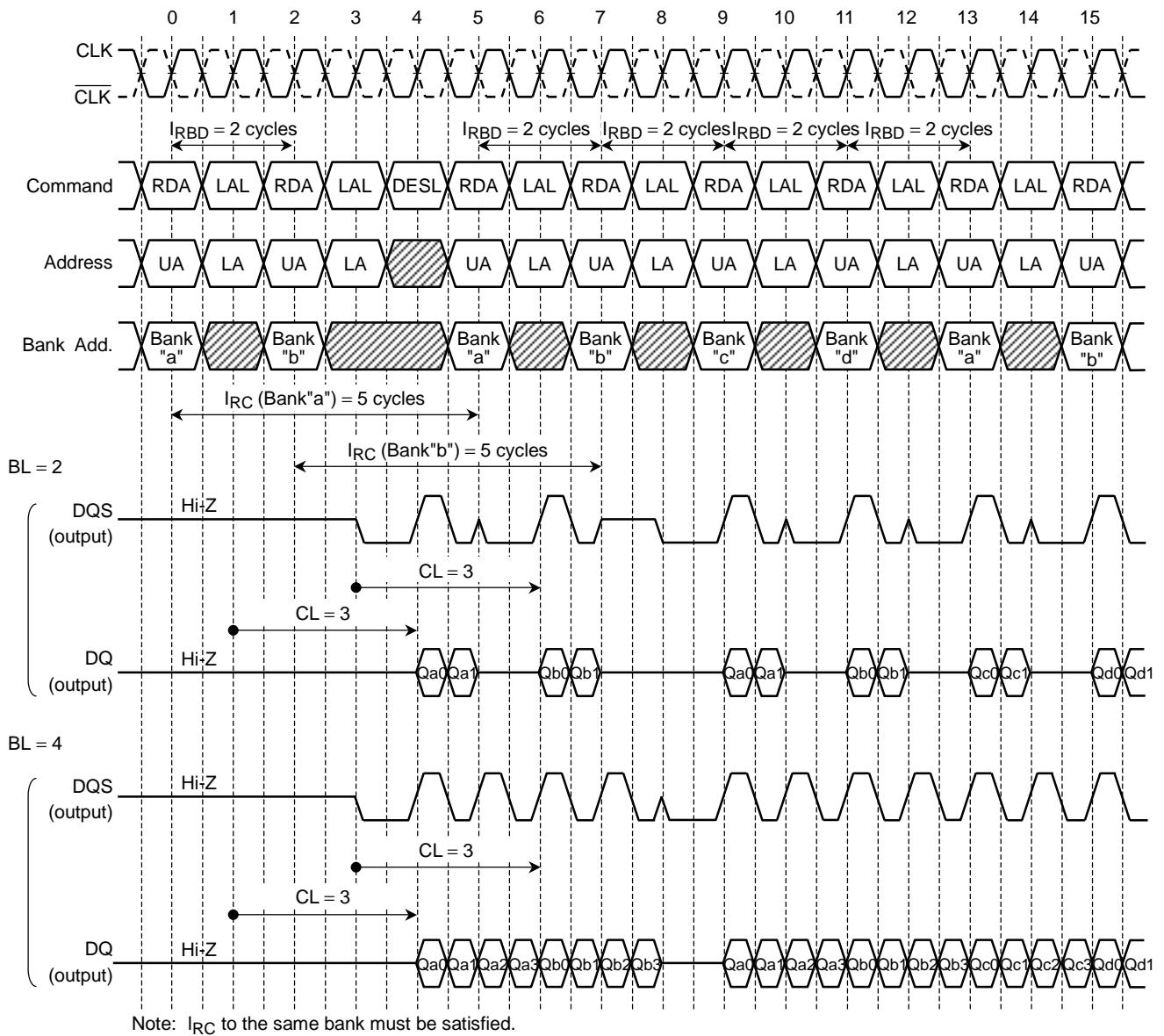
SINGLE BANK READ-WRITE TIMING (CL = 3)



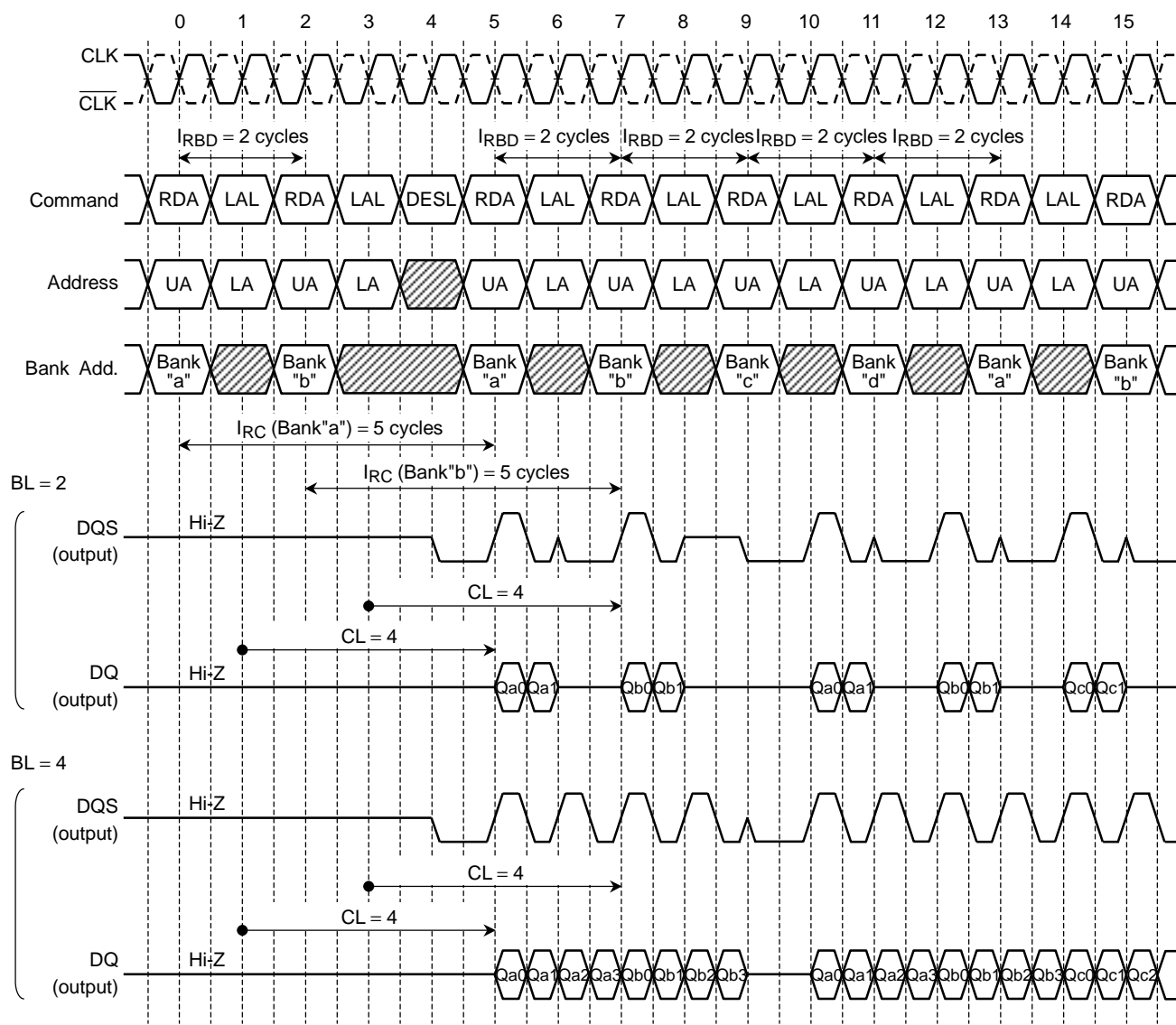
SINGLE BANK READ-WRITE TIMING (CL = 4)



MULTIPLE BANK READ TIMING (CL = 3)

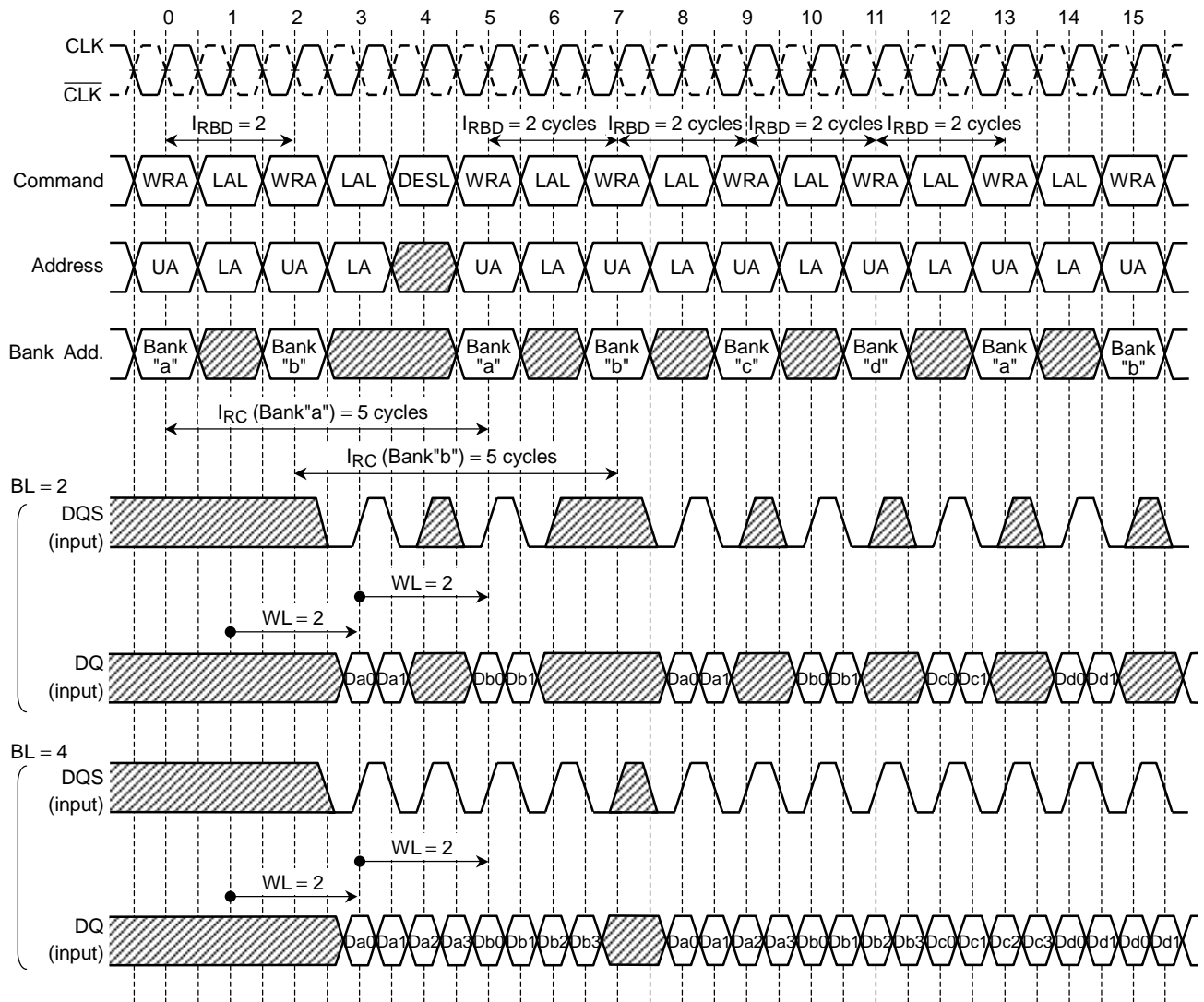


MULTIPLE BANK READ TIMING (CL = 4)



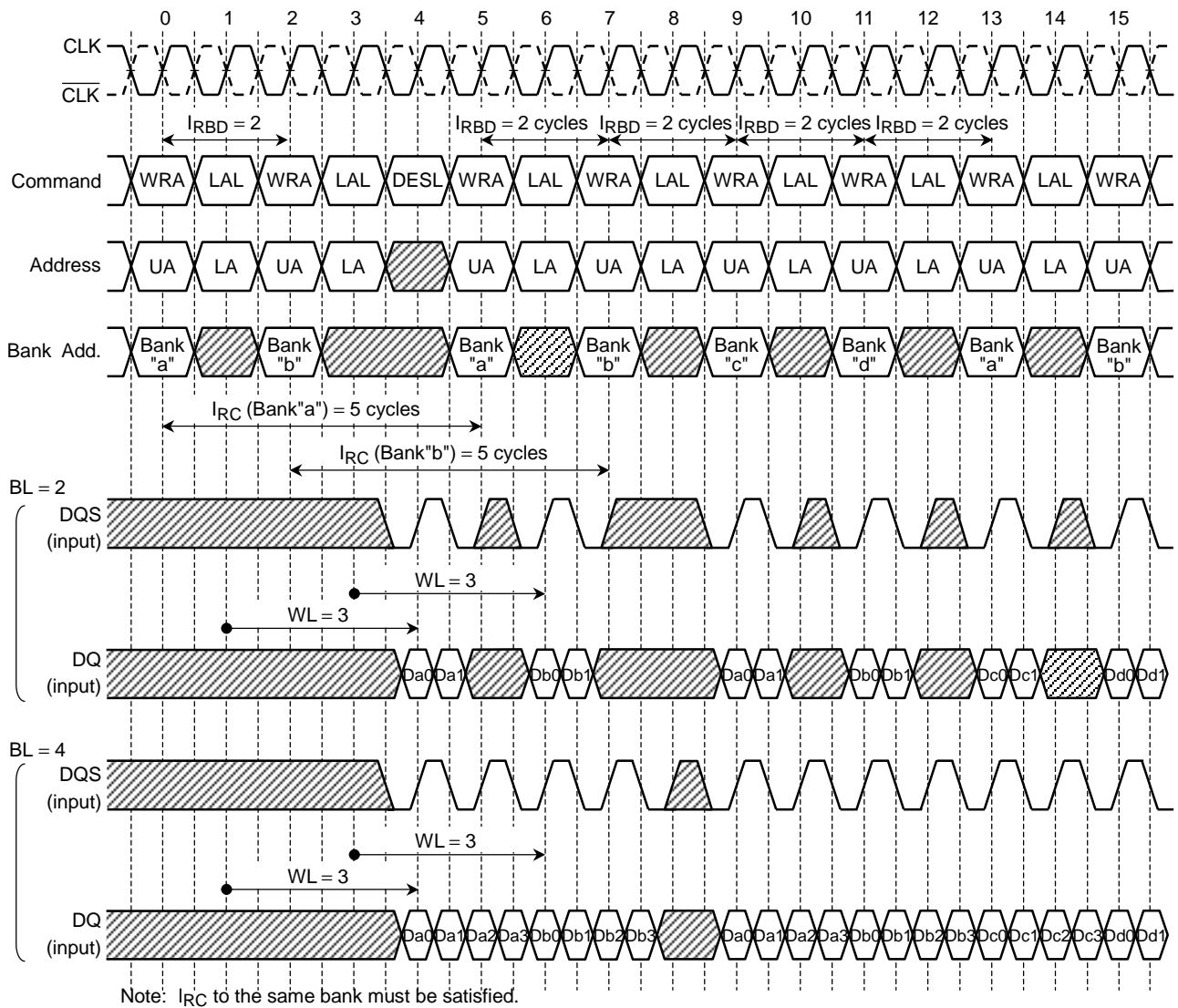
Note: I_{RC} to the same bank must be satisfied.

MULTIPLE BANK WRITE TIMING (CL = 3)

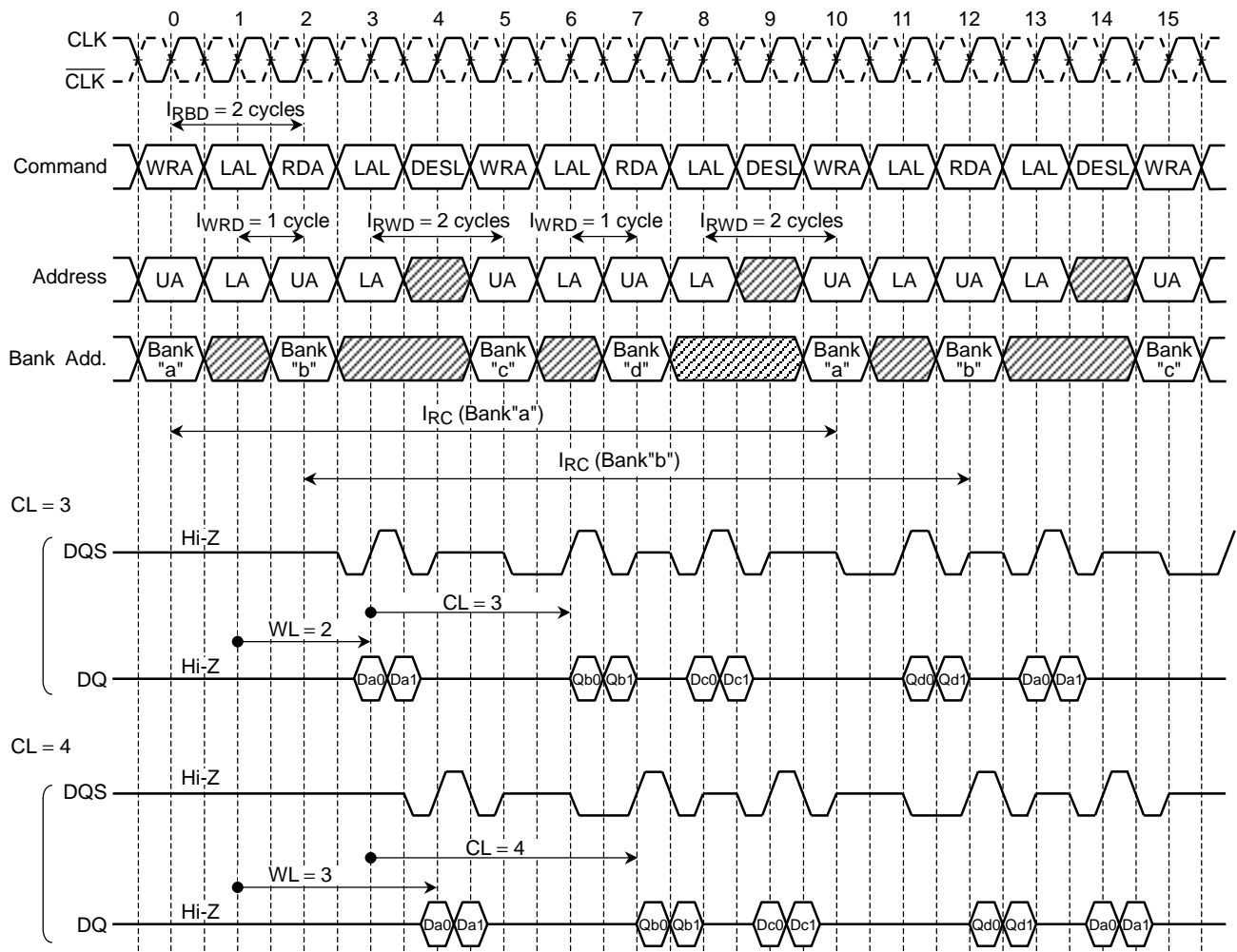


Note: I_{RC} to the same bank must be satisfied.

MULTIPLE BANK WRITE TIMING (CL = 4)

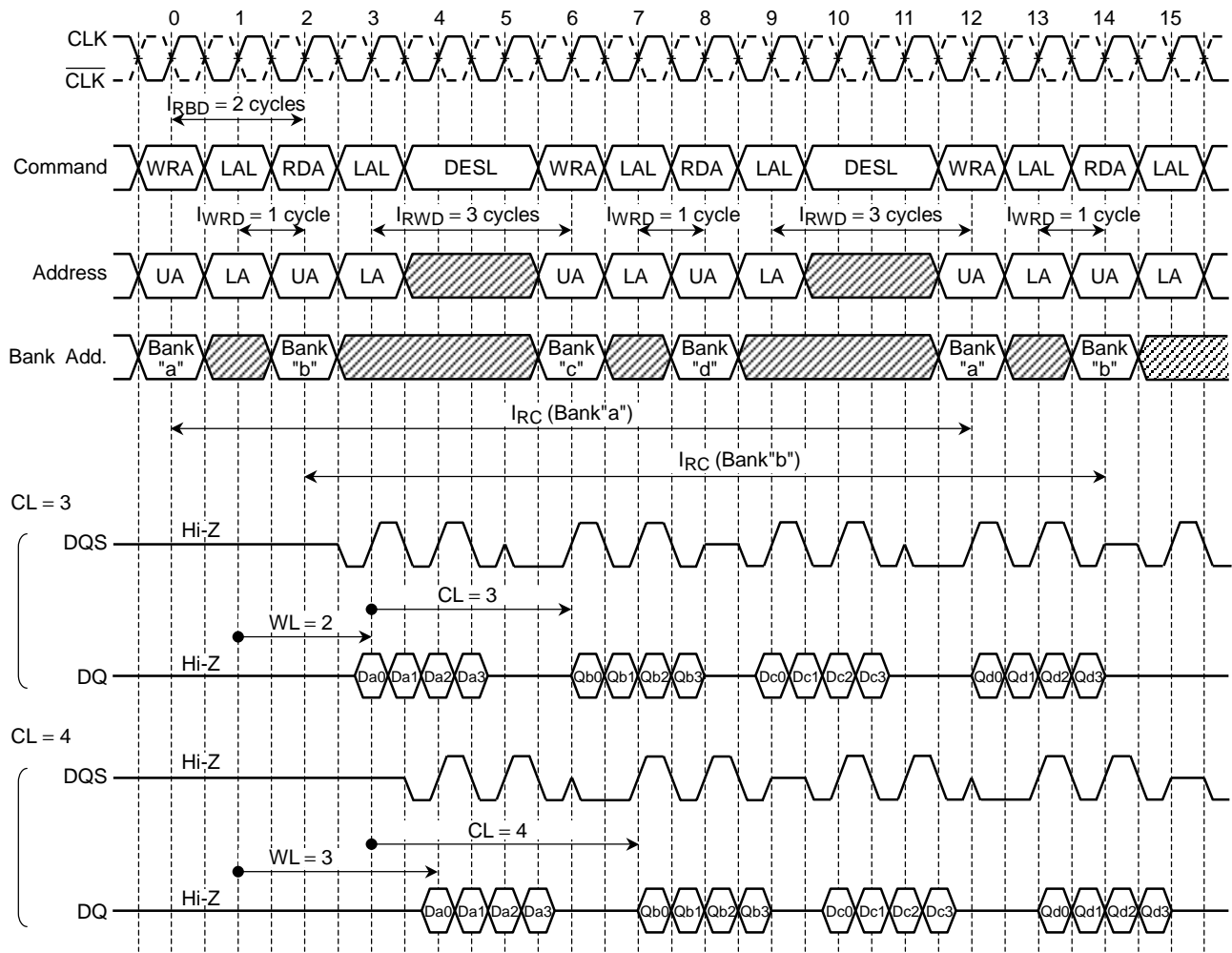


MULTIPLE BANK READ-WRITE TIMING (BL = 2)



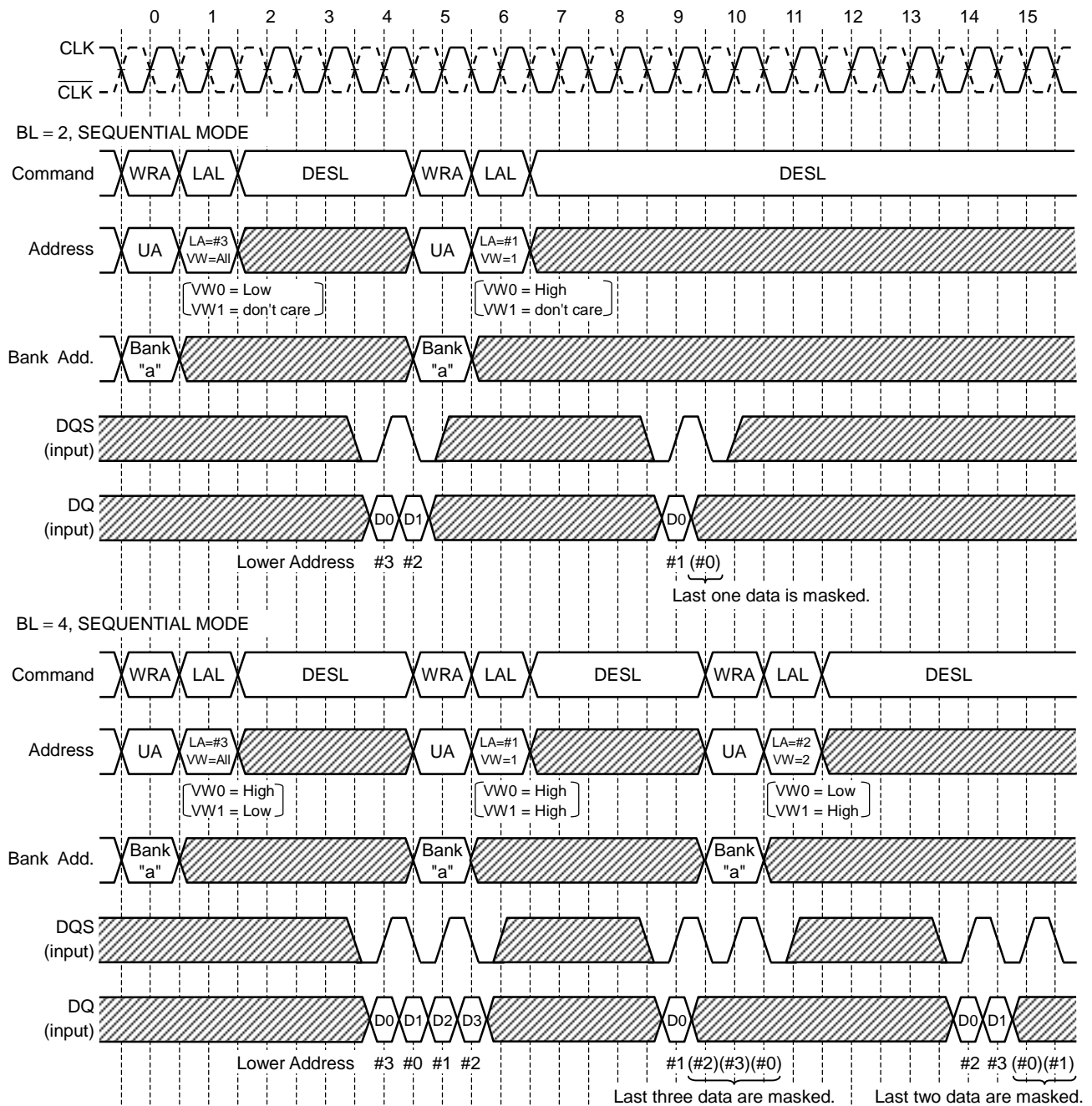
Note: I_{RC} to the same bank must be satisfied.

MULTIPLE BANK READ-WRITE TIMING (BL = 4)



Note: I_{RC} to the same bank must be satisfied.

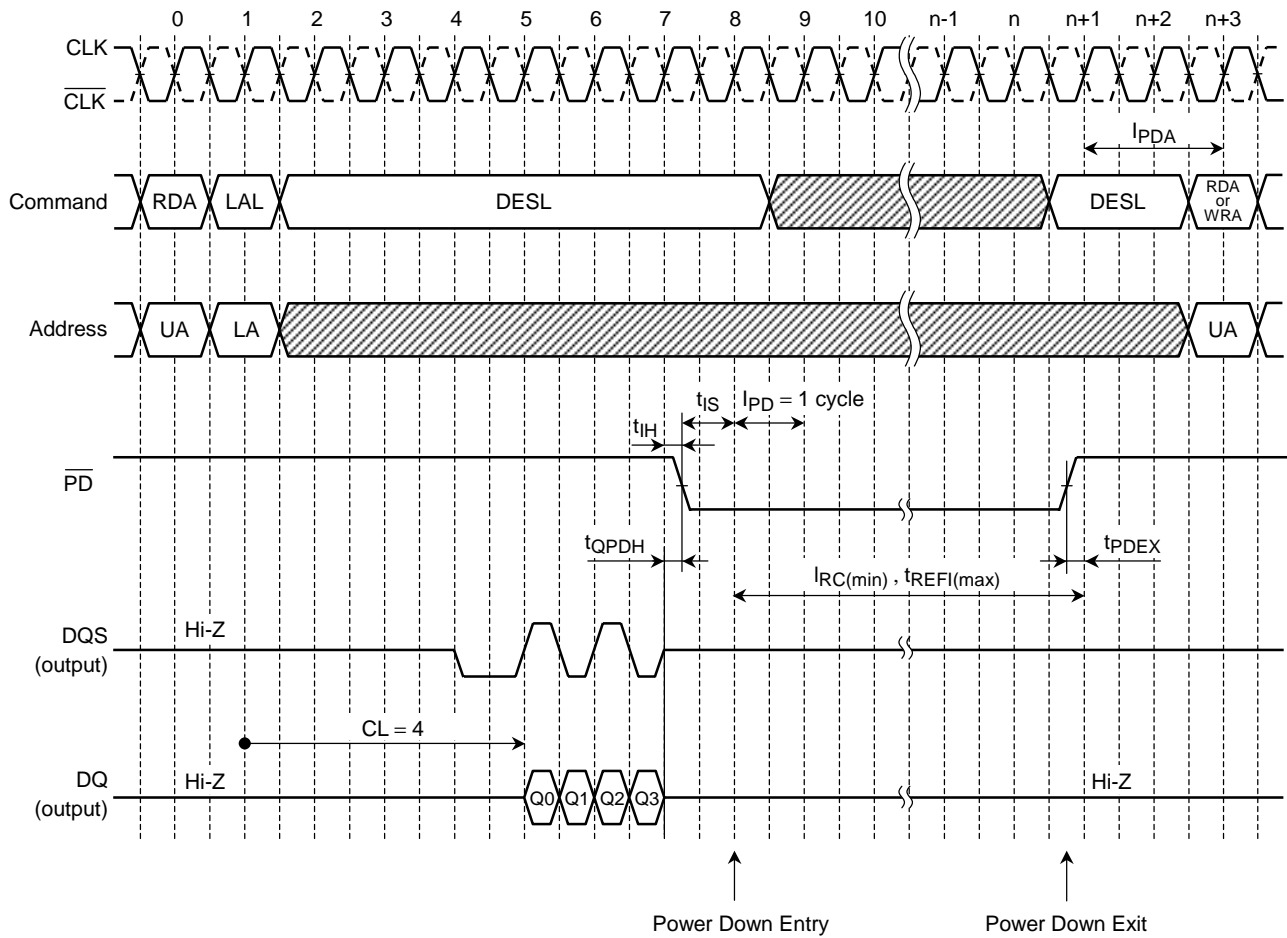
WRITE with VARIABLE WRITE LENGTH (VW) CONTROL (CL = 4)



Note: DQS input must be continued till end of burst count even if some of later data is masked.

POWER DOWN TIMING (CL = 4, BL = 4)

Read cycle to Power Down Mode



Note: \overline{PD} must be kept "High" level until end of Burst data output.

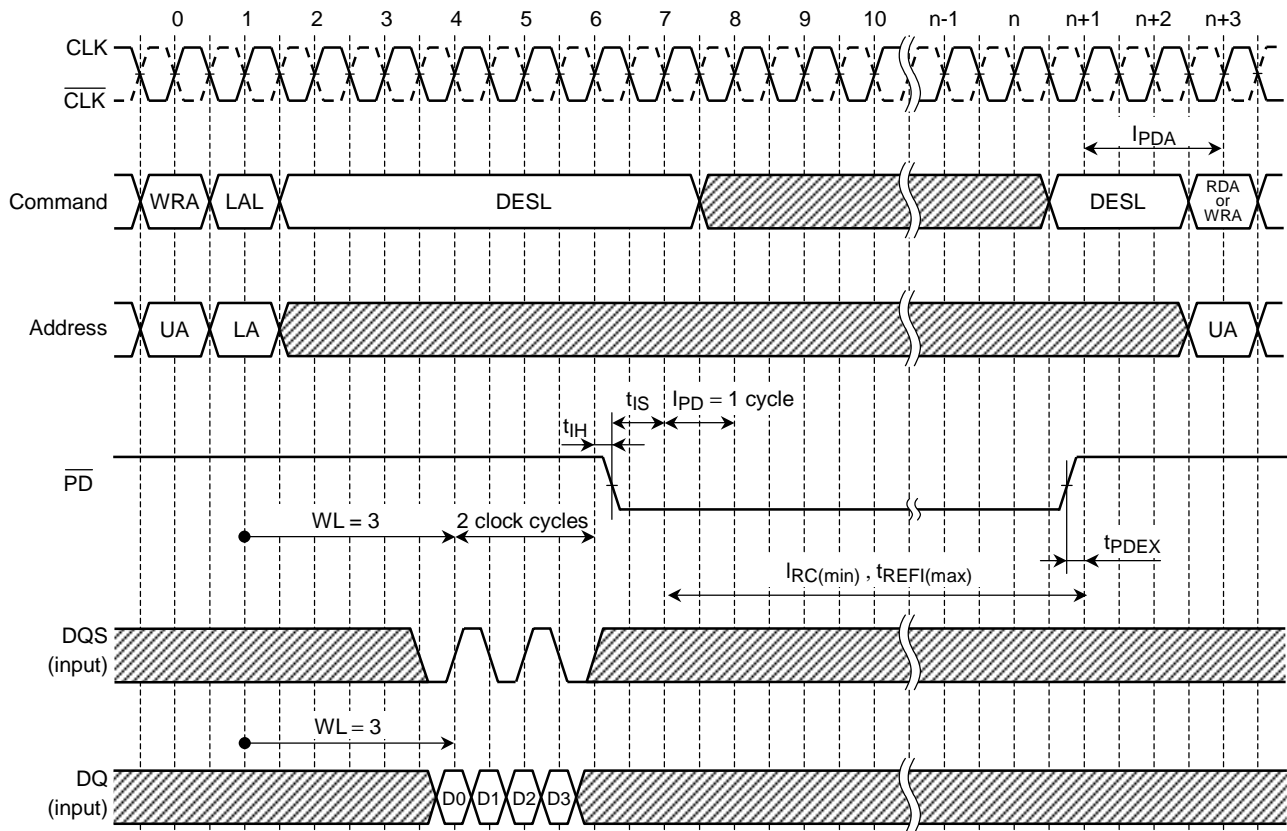
\overline{PD} should be brought to "High" within $t_{REFI(max)}$ to maintain the data written into cell.

In Power Down Mode, \overline{PD} "Low" and a stable clock signal must be maintained.

When \overline{PD} is brought to "High", a valid executable command may be applied I_{PDA} cycles later.

POWER DOWN TIMING (CL = 4, BL = 4)

Write cycle to Power Down Mode



Note: \overline{PD} must be kept "High" level until WL+2 clock cycles from LAL command.

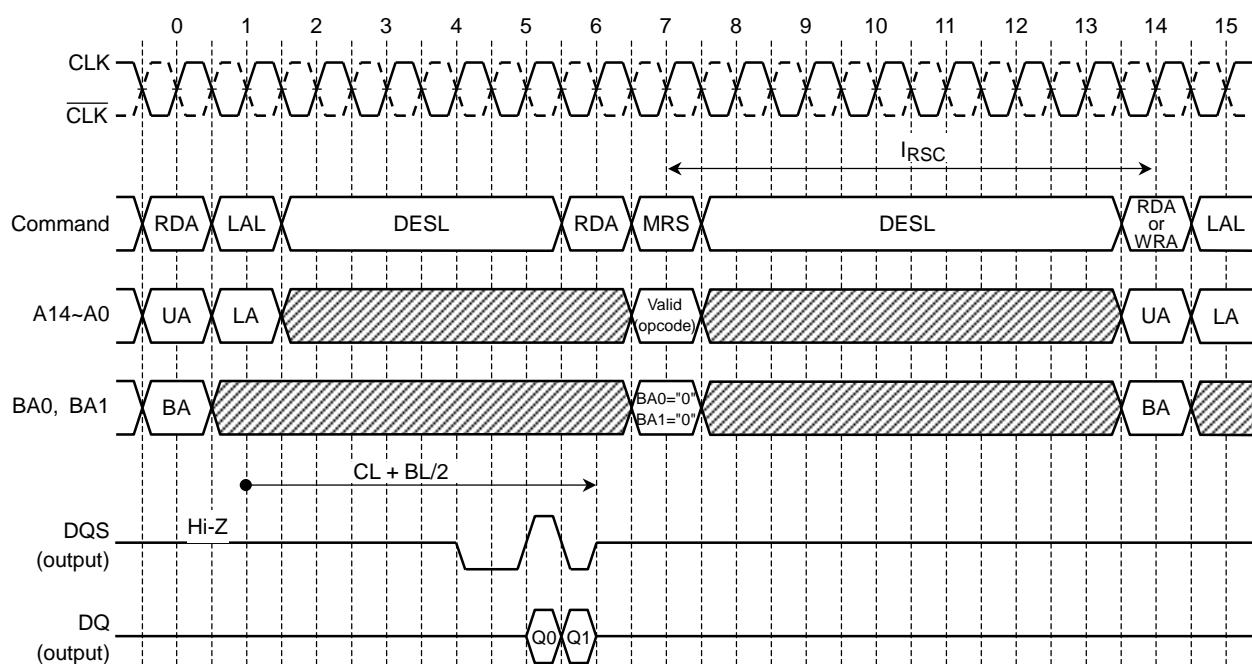
\overline{PD} should be brought to "High" within $t_{REFI(max)}$ to maintain the data written into cell.

In Power Down Mode, \overline{PD} "Low" and a stable clock signal must be maintained.

When \overline{PD} is brought to "High", a valid executable command may be applied I_{PDA} cycles later.

MODE REGISTER SET TIMING (CL = 4, BL = 2)

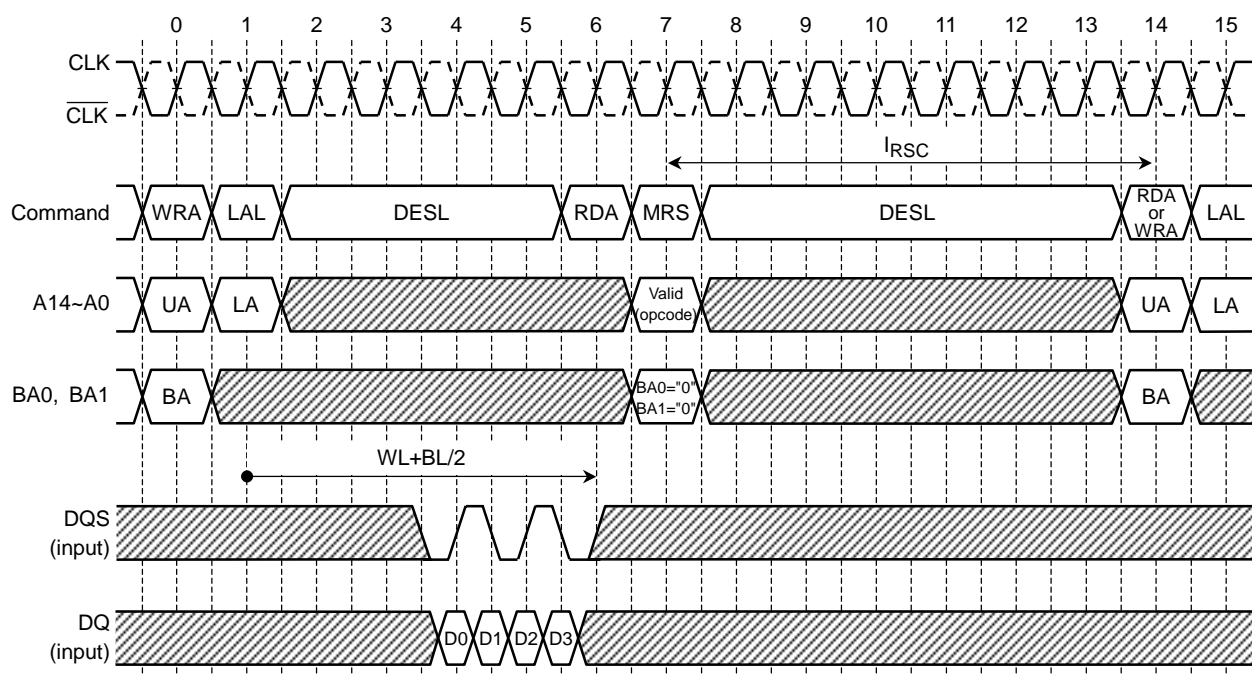
From Read operation to Mode Register Set operation.



Note: Minimum delay from LAL following RDA to RDA of MRS operation is CL+BL/2.

MODE REGISTER SET TIMING (CL = 4, BL = 4)

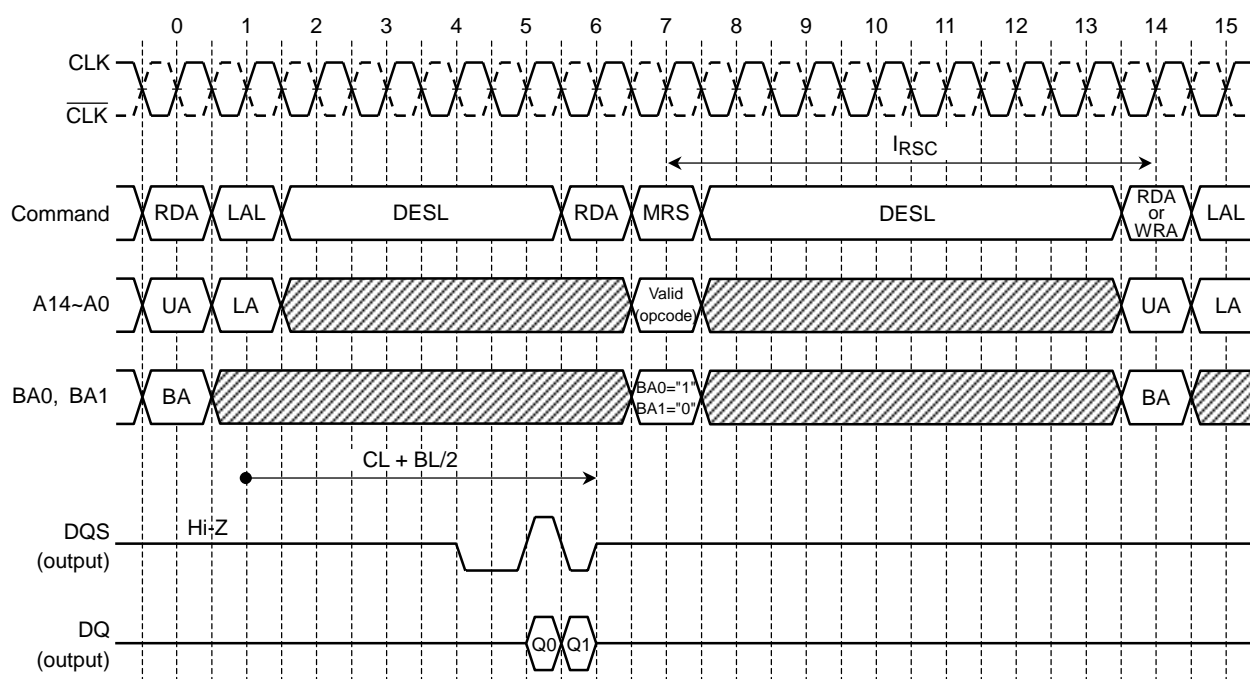
From Write operation to Mode Register Set operation.



Note: Minimum delay from LAL following WRA to RDA of MRS operation is WL+BL/2.

EXTENDED MODE REGISTER SET TIMING (CL = 4, BL = 2)

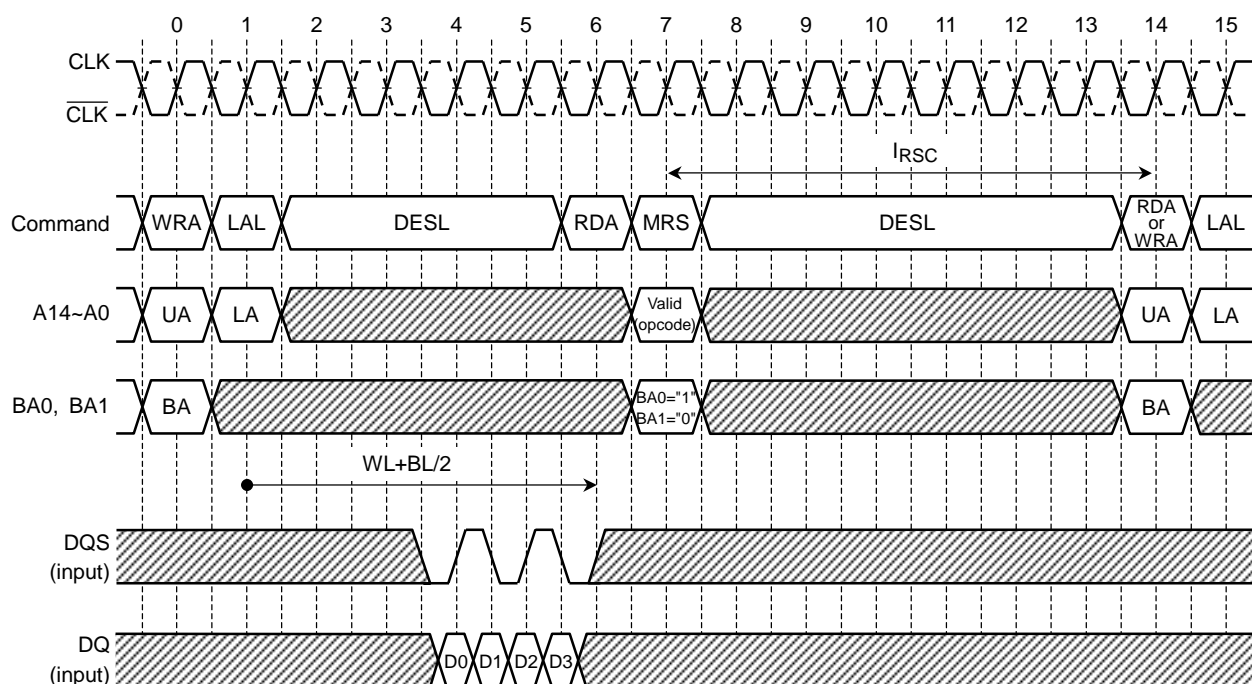
From Read operation to Extended Mode Register Set operation.



Note: Minimum delay from LAL following RDA to RDA of EMRS operation is CL+BL/2.
 DLL switch in Extended Mode Register must be set to enable mode for normal operation.
 DLL lock-on time is needed after initial EMRS operation. See Power Up Sequence.

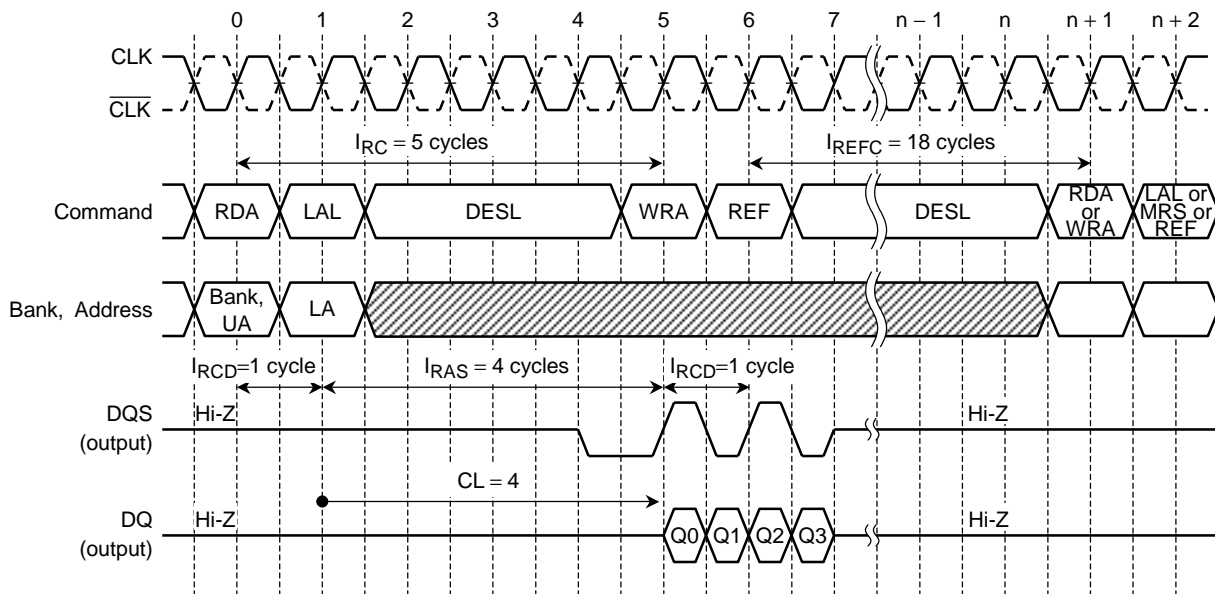
EXTENDED MODE REGISTER SET TIMING (CL = 4, BL = 4)

From Write operation to Extended Mode Register Set operation.



Note: DLL switch in Extended Mode Register must be set to enable mode for normal operation.
 DLL lock-on time is needed after initial EMRS operation. See Power Up Sequence.
 Minimum delay from LAL following WRA to RDA of EMRS operation is WL+BL/2.

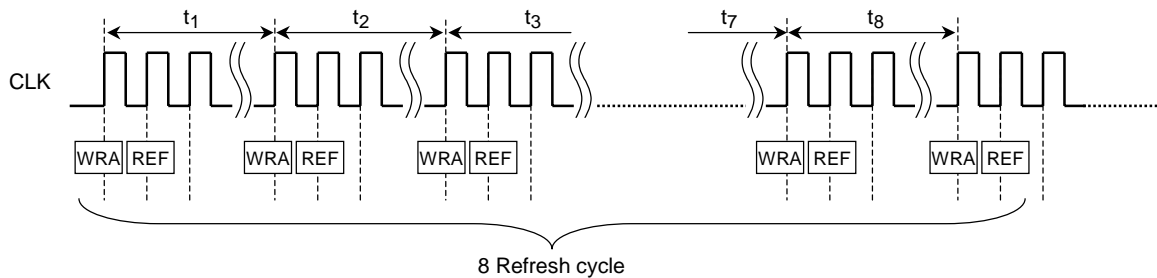
AUTO-REFRESH TIMING (CL = 4, BL = 4)



Note: In case of CL = 4, I_{REFC} must be meet 18 clock cycles.

When the Auto-Refresh operation is performed, the synthetic average interval of Auto-Refresh command specified by t_{REFI} must be satisfied.

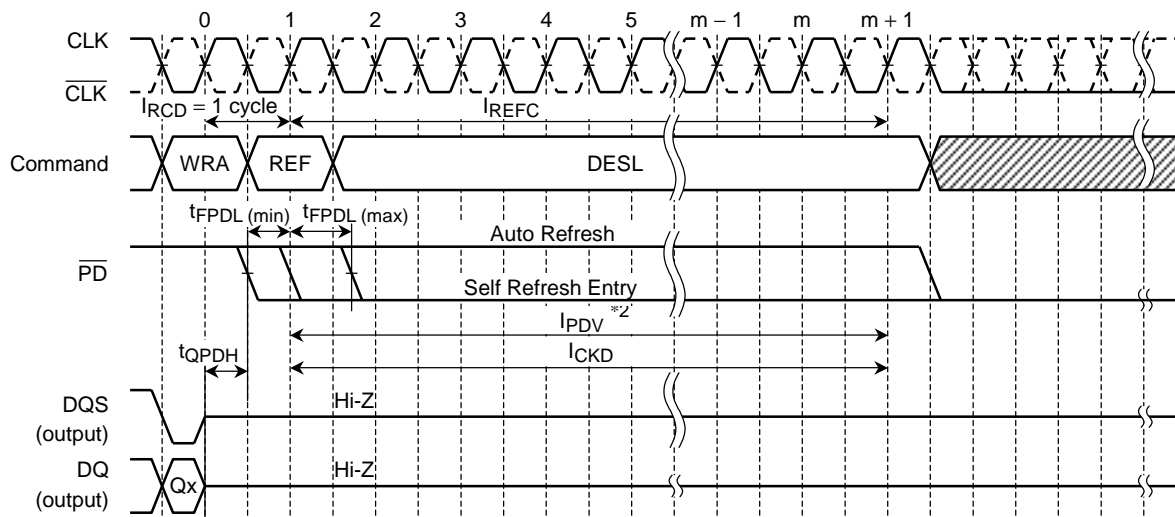
t_{REFI} is average interval time in 8 Refresh cycles that is sampled randomly.




$$t_{REFI} = \frac{\text{Total time of 8 Refresh cycle}}{8} = \frac{t_1 + t_2 + t_3 + t_4 + t_5 + t_6 + t_7 + t_8}{8}$$

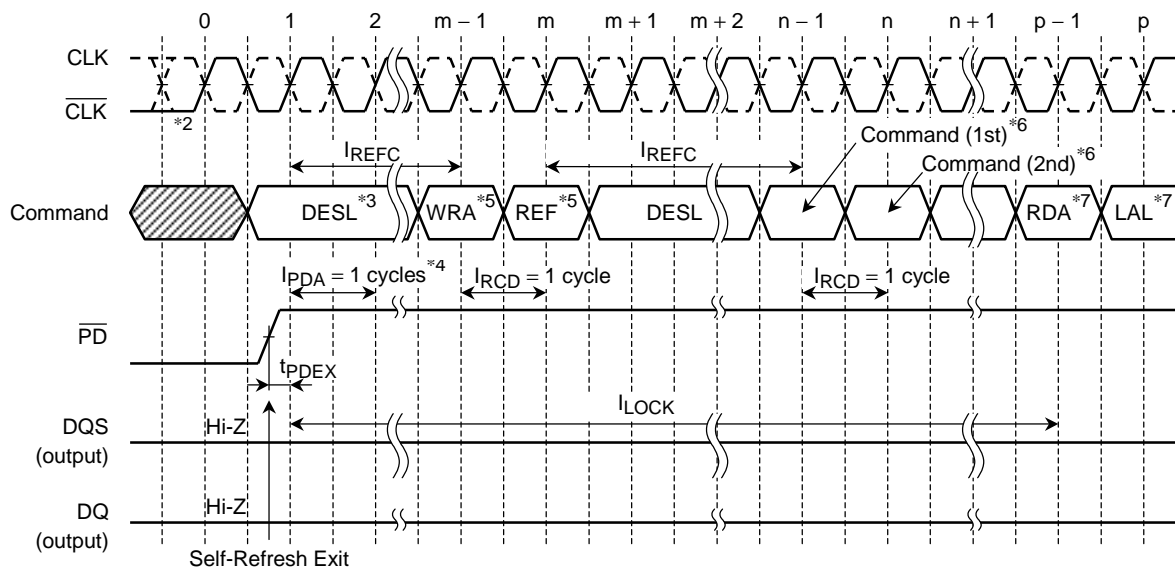
t_{REFI} is specified to avoid partly concentrated current of Refresh operation that is activated larger area than Read / Write operation.


SELF-REFRESH ENTRY TIMING



- Notes:
1.  is don't care.
 2. \overline{PD} must be brought to "Low" within the timing between $t_{FPDL(min)}$ and $t_{FPDL(max)}$ to Self Refresh mode. When \overline{PD} is brought to "Low" after I_{PDV} , TC59LM913/05AMB perform Auto Refresh and enter Power down mode. In case of \overline{PD} fall between $t_{FPDL(max)}$ and I_{PDV} , TC59LM913/05AMB will either entry Self-Refresh mode or Power down mode after Auto-Refresh operation. It can't be specified which mode TC59LM913/05AMB operates.
 3. It is desirable that clock input is continued at least I_{CKD} from REF command even though \overline{PD} is brought to "Low" for Self-Refresh Entry.
 4. In case of Self-Refresh entry after Write Operation, the delay time from the LAL command following WRA to the REF command is Write latency (WL)+3 clock cycles minimum.

SELF-REFRESH EXIT TIMING



- Notes:
1.  is don't care.
 2. Clock should be stable prior to $\overline{\text{PD}} = \text{"High"}$ if clock input is suspended in Self-Refresh mode.
 3. DESL command must be asserted during I_{REFC} after $\overline{\text{PD}}$ is brought to "High".
 4. I_{PDA} is defined from the first clock rising edge after $\overline{\text{PD}}$ is brought to "High".
 5. It is desirable that one Auto-Refresh command is issued just after Self-Refresh Exit before any other operation.
 6. Any command (except Read command) can be issued after I_{REFC} .
 7. Read command ($\text{RDA} + \text{LAL}$) can be issued after I_{LOCK} .

FUNCTIONAL DESCRIPTION

Network FCRAMTM

FCRAMTM is an acronym of Fast Cycle Random Access Memory. The Network FCRAMTM is competent to perform fast random core access, low latency and high-speed data transfer.

PIN FUNCTIONS

CLOCK INPUTS: CLK & $\overline{\text{CLK}}$

The CLK and $\overline{\text{CLK}}$ inputs are used as the reference for synchronous operation. CLK is master clock input. The $\overline{\text{CS}}$, FN and all address input signals are sampled on the crossing of the positive edge of CLK and the negative edge of $\overline{\text{CLK}}$. The DQS and DQ output are aligned to the crossing point of CLK and $\overline{\text{CLK}}$. The timing reference point for the differential clock is when the CLK and $\overline{\text{CLK}}$ signals cross during a transition.

POWER DOWN: $\overline{\text{PD}}$

The PD input controls the entry to the Power Down or Self-Refresh modes. The $\overline{\text{PD}}$ input does not have a Clock Suspend function like a CKE input of a standard SDRAMs, therefore it is illegal to bring $\overline{\text{PD}}$ pin into low state if any Read or Write operation is being performed.

CHIP SELECT & FUNCTION CONTROL: $\overline{\text{CS}}$ & FN

The $\overline{\text{CS}}$ and FN inputs are a control signal for forming the operation commands on FCRAMTM. Each operation mode is decided by the combination of the two consecutive operation commands using the $\overline{\text{CS}}$ and FN inputs.

BANK ADDRESSES: BA0~BA1

The BA0 to BA1 inputs are latched at the time of assertion of the RDA or WRA command and are selected the bank to be used for the operation. BA0 and BA1 also define which mode register is loaded during the Mode Register Set command (MRS or EMRS).

| | BA0 | BA1 |
|---------|-----|-----|
| Bank #0 | 0 | 0 |
| Bank #1 | 1 | 0 |
| Bank #2 | 0 | 1 |
| Bank #3 | 1 | 1 |

8 bank operation can be performed using A14 as follows.

| | BA0 | BA1 | A14 (BA2) |
|---------|-----|-----|-----------|
| Bank #0 | 0 | 0 | 0 |
| Bank #1 | 1 | 0 | 0 |
| Bank #2 | 0 | 1 | 0 |
| Bank #3 | 1 | 1 | 0 |
| Bank #4 | 0 | 0 | 1 |
| Bank #5 | 1 | 0 | 1 |
| Bank #6 | 0 | 1 | 1 |
| Bank #7 | 1 | 1 | 1 |

ADDRESS INPUTS: A0~A14

Address inputs are used to access the arbitrary address of the memory cell array within each bank. The Upper Addresses with Bank addresses are latched at the RDA or WRA command and the Lower Addresses are latched at the LAL command. The A0 to A14 inputs are also used for setting the data in the Regular or Extended Mode Register set cycle.

| | UPPER ADDRESS | LOWER ADDRESS |
|--------------|---------------|---------------|
| TC59LM905AMB | A0~A14 | A0~A8 |
| TC59LM913AMB | A0~A14 | A0~A7 |

DATA INPUT/OUTPUT: DQ0~DQ7 or DQ15

The input data of DQ0 to DQ15 are taken in synchronizing with the both edges of DQS input signal. The output data of DQ0 to DQ15 are outputted synchronizing with the both edges of DQS signal.

DATA STROBE: DQS, LDQS / UDQS

The DQS is bi-directional signal. Both edge of DQS are used as the reference of data input or output. In write operation, the DQS used as an input signal is utilized for a latch of write data. In read operation, the DQS is an output signal provides the read data strobe.

POWER SUPPLY: V_{DD}, V_{DDQ}, V_{SS}, V_{SSQ}

V_{DD} and V_{SS} are power supply pins for memory core and peripheral circuits.

V_{DDQ} and V_{SSQ} are power supply pins for the output buffer.

REFERENCE VOLTAGE: V_{REF}

V_{REF} is reference voltage for all input signals.

COMMAND FUNCTIONS and OPERATIONS

TC59LM913/05AMB are introduced the two consecutive command input method. Therefore, except for Power Down mode, each operation mode decided by the combination of the first command and the second command from stand-by states of the bank to be accessed.

Read Operation (1st command + 2nd command = RDA + LAL)

Issuing the RDA command with Bank Addresses and Upper Addresses to the idle bank puts the bank designated by Bank Address in a read mode. When the LAL command with Lower Addresses is issued at the next clock of the RDA command, the data is read out sequentially synchronizing with the both edges of DQS output signal (Burst Read Operation). The initial valid read data appears after $\overline{\text{CAS}}$ latency from the issuing of the LAL command. The valid data is outputted for a burst length. The $\overline{\text{CAS}}$ latency, the burst length of read data and the burst type must be set in the Mode Register beforehand. The read operated bank goes back automatically to the idle state after IRC.

Write Operation (1st command + 2nd command = WRA + LAL)

Issuing the WRA command with Bank Addresses and Upper Addresses to the idle bank puts the bank designated by Bank Address in a write mode. When the LAL command with Lower Addresses is issued at the next clock of the WRA command, the input data is latched sequentially synchronizing with the both edges of DQS input signal (Burst Write Operation). The data and DQS inputs have to be asserted in keeping with clock input after $\overline{\text{CAS}}$ latency-1 from the issuing of the LAL command. The DQS has to be provided for a burst length. The $\overline{\text{CAS}}$ latency and the burst type must be set in the Mode Register beforehand. The write operated bank goes back automatically to the idle state after IRC. Write Burst Length is controlled by VW0 and VW1 inputs with LAL command. See VW truth table.

Auto-Refresh Operation (1st command + 2nd command = WRA + REF)

TC59LM913/05AMB are required to refresh like a standard SDRAM. The Auto-Refresh operation is begun with the REF command following to the WRA command. The Auto-Refresh mode can be effective only when all banks are in the idle state and all outputs are in Hi-Z states. In a point to notice, the write mode started with the WRA command is canceled by the REF command having gone into the next clock of the WRA command instead of the LAL command. The minimum period between the Auto-Refresh command and the next command is specified by IREFC. However, about a synthetic average interval of Auto-Refresh command, it must be careful. In case of equally distributed refresh, Auto-Refresh command has to be issued within once for every 7.8 μs by the maximum. In case of burst refresh or random distributed refresh, the average interval of eight consecutive Auto-Refresh commands has to be more than 400 ns always. In other words, the number of Auto-Refresh cycles that can be performed within 3.2 μs ($8 \times 400 \text{ ns}$) is to 8 times in the maximum.

Self-Refresh Operation (1st command + 2nd command = WRA + REF with $\overline{\text{PD}}$ "L")

In case of Self-Refresh operation, refresh operation can be performed automatically by using an internal timer. When all banks are in the idle state and all outputs are in Hi-Z states, the TC59LM913/05AMB become Self-Refresh mode by issuing the Self-Refresh command. $\overline{\text{PD}}$ has to be brought to "Low" within tFPDL from the REF command following to the WRA command for a Self-Refresh mode entry. In order to satisfy the refresh period, the Self-Refresh entry command should be asserted within 7.8 μs after the latest Auto-Refresh command. Once the device enters Self-Refresh mode, the DESL command must be continued for IREFC period. In addition, it is desirable that clock input is kept in ICKD period. The device is in Self-Refresh mode as long as $\overline{\text{PD}}$ held "Low". During Self-Refresh mode, all input and output buffers are disabled except for $\overline{\text{PD}}$, therefore the power dissipation lowers. Regarding a Self-Refresh mode exit, $\overline{\text{PD}}$ has to be changed over from "Low" to "High" along with the DESL command, and the DESL command has to be continuously issued in the number of clocks specified by IREFC. The Self-Refresh exit function is asynchronous operation. It is required that one Auto-Refresh command is issued to avoid the violation of the refresh period just after IREFC from Self-Refresh exit.

Power Down Mode ($\overline{\text{PD}}$ "L")

When all banks are in the idle state and DQ outputs are in Hi-Z states, the TC59LM913/05AMB become Power Down Mode by asserting $\overline{\text{PD}}$ is "Low". When the device enters the Power Down Mode, all input and output buffers are disabled after specified time except for $\overline{\text{PD}}$. Therefore, the power dissipation lowers. To exit the Power Down Mode, $\overline{\text{PD}}$ has to be brought to "High" and the DESL command has to be issued for two clocks cycle after $\overline{\text{PD}}$ goes high. The Power Down exit function is asynchronous operation.

Mode Register Set (1st command + 2nd command = RDA + MRS)

When all banks are in the idle state, issuing the MRS command following to the RDA command can program the Mode Register. In a point to notice, the read mode started with the RDA command is canceled by the MRS command having gone into the next clock of the RDA command instead of the LAL command. The data to be set in the Mode Register is transferred using A0 to A14, BA0 to BA1 address inputs. The TC59LM913/05AMB have two mode registers. These are Regular and Extended Mode Register. The Regular or Extended Mode Register is chosen by BA0 and BA1 in the MRS command. The Regular Mode Register designates the operation mode for a read or write cycle. The Regular Mode Register has four function fields.

The four fields are as follows:

- (R-1) Burst Length field to set the length of burst data
- (R-2) Burst Type field to designate the lower address access sequence in a burst cycle
- (R-3) $\overline{\text{CAS}}$ Latency field to set the access time in clock cycle
- (R-4) Test Mode field to use for supplier only.

The Extended Mode Register has four function fields.

The three fields are as follows:

- (E-1) DLL Switch field to choose either DLL enable or DLL disable
- (E-2) Output Driver Impedance Control field.
- (E-3) DQS enable field.

Once those fields in the Mode Register are set up, the register contents are maintained until the Mode Register is set up again by another MRS command or power supply is lost. The initial value of the Regular or Extended Mode Register after power-up is undefined, therefore the Mode Register Set command must be issued before proper operation.

- Regular Mode Register/Extended Mode Register change bits (BA0, BA1).
These bits are used to choose either Regular MRS or Extended MRS

| BA1 | BA0 | A14~A0 |
|-----|-----|--------------------|
| 0 | 0 | Regular MRS Cycle |
| 0 | 1 | Extended MRS Cycle |
| 1 | × | Reserved |

Regular Mode Register Fields

(R-1) Burst Length field (A2 to A0)

This field specifies the data length for column access using the A2 to A0 pins and sets the Burst Length to be 2 or 4 words.

| A2 | A1 | A0 | BURST LENGTH |
|----|----|----|--------------|
| 0 | 0 | 0 | Reserved |
| 0 | 0 | 1 | 2 words |
| 0 | 1 | 0 | 4 words |
| 0 | 1 | 1 | Reserved |
| 1 | × | × | Reserved |

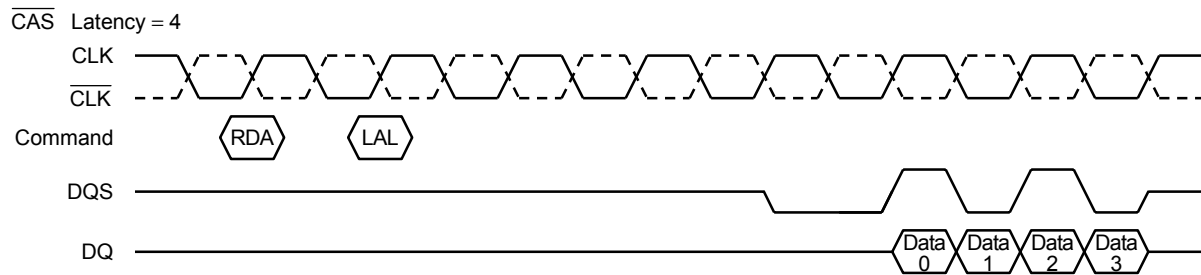
(R-2) Burst Type field (A3)

The Burst Type can be chosen Interleave mode or Sequential mode. When the A3 bit is "0", Sequential mode is selected. When the A3 bit is "1", Interleave mode is selected. Both burst types support burst length of 2 and 4 words.

| A3 | BURST TYPE |
|----|------------|
| 0 | Sequential |
| 1 | Interleave |

• Addressing sequence of Sequential mode (A3)

A column access is started from the inputted lower address and is performed by incrementing the lower address input to the device.



Addressing sequence for Sequential mode

| DATA | ACCESS ADDRESS | BURST LENGTH |
|--------|----------------|----------------------------------------------------------------|
| Data 0 | n | 2 words (address bits is LA0) not carried from LA0~LA1 |
| Data 1 | n + 1 | |
| Data 2 | n + 2 | 4 words (address bits is LA1, LA0) not carried from LA1~LA2 |
| Data 3 | n + 3 | |

• Addressing sequence of Interleave mode

A column access is started from the inputted lower address and is performed by interleaving the address bits in the sequence shown as the following.

Addressing sequence for Interleave mode

| DATA | ACCESS ADDRESS | BURST LENGTH |
|--------|-----------------------------------------------------------------------|--------------|
| Data 0 | ...A8 A7 A6 A5 A4 A3 A2 A1 A0 | 2 words |
| Data 1 | ...A8 A7 A6 A5 A4 A3 A2 A1 $\overline{\text{A0}}$ | |
| Data 2 | ...A8 A7 A6 A5 A4 A3 A2 $\overline{\text{A1}}$ A0 | 4 words |
| Data 3 | ...A8 A7 A6 A5 A4 A3 A2 $\overline{\text{A1}}$ $\overline{\text{A0}}$ | |

(R-3) $\overline{\text{CAS}}$ Latency field (A6 to A4)

This field specifies the number of clock cycles from the assertion of the LAL command following the RDA command to the first data read. The minimum values of $\overline{\text{CAS}}$ Latency depends on the frequency of CLK. In a write mode, the place of clock that should input write data is $\overline{\text{CAS}}$ Latency cycles – 1.

| A6 | A5 | A4 | $\overline{\text{CAS}}$ LATENCY |
|----|----|----|---------------------------------|
| 0 | 0 | 0 | Reserved |
| 0 | 0 | 1 | Reserved |
| 0 | 1 | 0 | Reserved |
| 0 | 1 | 1 | 3 |
| 1 | 0 | 0 | 4 |
| 1 | 0 | 1 | Reserved |
| 1 | 1 | 0 | Reserved |
| 1 | 1 | 1 | Reserved |

(R-4) Test Mode field (A7)

This bit is used to enter Test Mode for supplier only and must be set to “0” for normal operation.

(R-5) Reserved field in the Regular Mode Register

• Reserved bits (A8 to A14)

These bits are reserved for future operations. They must be set to “0” for normal operation.

Extended Mode Register fields

(E-1) DLL Switch field (A0)

This bit is used to enable DLL. When the A0 bit is set “0”, DLL is enabled. This bit must be set to “0” for normal operation.

(E-2) Output Driver Impedance Control field (A1, A6)

This field is used to choose Output Driver Strength. Four types of Driver Strength are supported.

| A6 | A1 | OUTPUT DRIVER IMPEDANCE CONTROL |
|----|----|---------------------------------|
| 0 | 0 | Normal Output Driver |
| 0 | 1 | Strong Output Driver |
| 1 | 0 | Weaker Output Driver |
| 1 | 1 | Weakest Output Driver |

(E-3) $\overline{\text{DQS}}$ enable (A10)

$\overline{\text{DQS}}$ is not supported. This bit must be always set “0”.

(E-4) Reserved field (A2 to A5, A7 to A9, A11 to A14)

These bits are reserved for future operations and must be set to “0” for normal operation.

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000707EBA

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