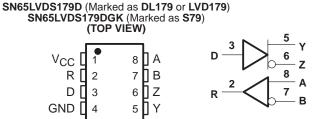
#### SLLS301G - APRIL 1998 - REVISED MARCH 2000

- Meets or Exceeds the Requirements of ANSI TIA/EIA-644-1995 Standard
- Signaling Rates up to 400 Mbit/s
- Bus-Terminal ESD Exceeds 12 kV
- Operates from a Single 3.3-V Supply
- Low-Voltage Differential Signaling With Typical Output Voltages of 350 mV and a 100 Ω Load
- Propagation Delay Times
   Drivery 4.7 no Type
  - Driver: 1.7 ns TypReceiver: 3.7 ns Typ
- Power Dissipation at 200 MHz
  - Driver: 25 mW Typical
  - Receiver: 60 mW Typical
- LVTTL Input Levels are 5 V Tolerant
- Driver is High Impedance When Disabled or With V<sub>CC</sub> < 1.5 V</li>
- Receiver has Open-Circuit Fail Safe
- Surface-Mount Packaging
   D Package (SOIC)
  - DGK Package (MSOP) ('LVDS79 Only)

### description

The SN65LVDS179, SN65LVDS180, SN65LVDS050, and SN65LVDS051 are differential line drivers and receivers that use low-voltage differential signaling (LVDS) to achieve signaling rates as high as 400 Mbps. The TIA/EIA-644 standard compliant electrical interface provides a minimum differential output voltage magnitude of 247 mV into a 100  $\Omega$  load and receipt of 100 mV signals with up to 1 V of ground potential difference between a transmitter and receiver.

The intended application of this device and signaling technique is for point-to-point baseband data transmission over controlled impedance media of approximately 100  $\Omega$  characteristic impedance. The transmission media may be printed-circuit board traces, backplanes, or cables. (Note: The ultimate rate and distance of data transfer is dependent upon the attenuation characteristics of the media, the noise coupling to the environment, and other application specific characteristics).





$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	D [ GND [
---	--------------

SN65LVDS05	OD (Marke (TOP VIE)	0) 1D	$14 \frac{14}{13} 1Y$	
1B [ 1A [ 1R [	2 1	6 ] V <sub>CC</sub> 5 ] 1D 4 ] 1Y	DE <u>12</u> 2D	$ \begin{array}{c}                                     $
RE [ 2R [ 2A [ 2B [ GND ]	4 1 5 1 6 1 7 1	3]1Z 2]DE	$1R \frac{3}{RE} \frac{4}{5}$ $2R \frac{5}{5}$	$ \begin{array}{c} 2 \\ 1 \\ 1 \\ 1B \\ 6 \\ 7 \\ 2B \\ 2B$

SN65LVDS051D (Marked as LVDS051) (TOP VIEW) 14 1Y 15 1D 13 1Z 16 VCC 1B 1DE 2 1A 🛙 2 15 🛛 1D **1**A 3 14 1Y 1 1R 🛙 3 1R 1B 1DE 4 13 ] 1Z 10 2R 🛛 5 12 2DE 2Y 11 2Z 2D 11 2A 👖 6 2Z 12 2B 7 10 2Y 2DE 6 9 2D GND 👖 8 2A 5 7 2R 2B



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#### description (continued)

	PACH	AGE				
TA	SMALL OUTLINE (D)	SMALL OUTLINE (DGK)				
	SN65LVDS050D	—				
-40°C to 85°C	SN65LVDS051D	—				
-40 C 10 85 C	SN65LVDS179D	SN65LVDS179DGK				
	SN65LVDS180D	_				

#### AVAILABLE OPTIONS

#### NOTE:

The ultimate rate and distance of data transfer is dependent upon the attenuation characteristics of the media, the noise coupling to the environment, and other application specific characteristics.

The SN65LVDS179, SN65LVDS180, SN65LVDS050, and SN65LVDS051 are characterized for operation from −40°C to 85°C.

#### **Function Tables**

#### SN65LVDS179 RECEIVER

INPUTS	OUTPUT
$V_{ID} = V_A - V_B$	R
$V_{ID} \ge 100 \text{ mV}$	Н
–100 MV < V <sub>ID</sub> < 100 mV	?
$V_{ID} \le -100 \text{ mV}$	L
Open	Н

H = high level, L = low level, ? = indeterminate

#### SN65LVDS179 DRIVER

INPUT	OUTPUTS				
D	Y	Z			
L	L	Н			
Н	Н	L			
Open	L	Н			
H = high level. L = low level					

nigh level, L = low level

#### SN65LVDS180, SN65LVDS050, and SN65LVDS051 RECEIVER

INPUTS		OUTPUT
$V_{ID} = V_A - V_B$	RE	R
$V_{ID} \ge 100 \text{ mV}$	L	Н
–100 MV < V <sub>ID</sub> < 100 mV	L	?
$V_{ID} \le -100 \text{ mV}$	L	L
Open	L	Н
X	н	7

H = high level, L = low level, Z = high impedance,X = don't care



SLLS301G - APRIL 1998 - REVISED MARCH 2000

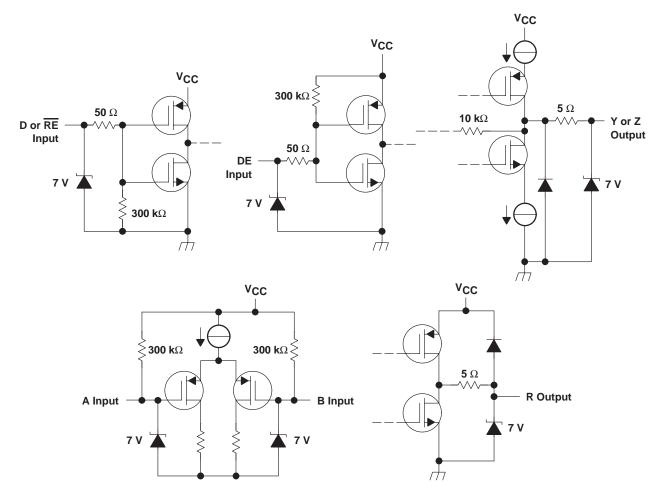
SN65LVDS051 DRIVER							
INPU	JTS	OUTI	PUTS				
D	DE	Y	Z				
L	Н	L	Н				
Н	Н	Н	L				
Open	Н	L	Н				
Х	L	Z	Z				

SN65LVDS180, SN65LVDS050, and

H = high level, L = low level, Z = high impedance,

X = don't care

### equivalent input and output schematic diagrams





#### SLLS301G - APRIL 1998 - REVISED MARCH 2000

### absolute maximum ratings over operating free-air temperature (unless otherwise noted)<sup>†</sup>

Supply voltage range, V <sub>CC</sub> (see Note 1)	–0.5 V to 4 V
Voltage range (D, R, DE, RE)	–0.5 V to 6 V
Electrostatic discharge: Y, Z, A, B, and GND (see Note 2)	CLass 3, A:12 kV, B:600 V
All	Class 3, A:7 kV, B:500 V
Continuous power dissipation	see dissipation rating table
Storage temperature range	–65°C to 150°C
Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds	250°C

<sup>+</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTES: 1. All voltage values, except differential I/O bus voltages are with respect to network ground terminal.

2. Tested in accordance with MIL-STD-883C Method 3015.7.

DISSIPATION RATING TABLE							
PACKAGE	T <sub>A</sub> ≤ 25°C POWER RATING	DERATING FACTOR ABOVE T <sub>A</sub> = 25°C <sup>†</sup>	T <sub>A</sub> = 85°C POWER RATING				
D8	725 mW	5.8 mW/°C	377 mW				
D14 or D16	950 mW	7.8 mW/°C	494 mW				
DGK	424 mW	3.4 mW/°C	220 mW				

<sup>†</sup>This is the inverse of the junction-to-ambient thermal resistance when board-mounted and with no air flow.

#### recommended operating conditions

	MIN	NOM	MAX	UNIT
Supply voltage, V <sub>CC</sub>	3	3.3	3.6	V
High-level input voltage, VIH	2			V
Low-level input voltage, VIL			0.8	V
Magnitude of differential input voltage, $V_{\text{ID}}$	0.1		0.6	V
Common–mode input voltage, V <sub>IC</sub> (see Figure 6)	$\frac{\left V_{\text{ID}}\right }{2}$		$2.4 - \frac{ V_{ D } }{2}$	V
Operating free–air temperature, T <sub>A</sub>	-40		V <sub>CC</sub> -0.8 85	°C

# device electrical characteristics over recommended operating conditions (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYPŤ	MAX	UNIT	
	SN65LVDS179	No receiver load, Driver $R_L = 100 \Omega$		9	12	mA	
		Driver and receiver enabled, No receiver load, Driver RL = 100 $\Omega$		9	12		
		Driver enabled, Receiver disabled, $R_L = 100 \Omega$		5	7	٣A	
	3N03LVD3100	Driver disabled, Receiver enabled, No load		1.5	2	mA	
		Disabled		0.5	1		
ICC current	10 $10$ $10$ $10$ $10$ $10$ $10$ $10$	Drivers and receivers enabled, No receiver loads, Driver RL = 100 $\Omega$		12	20	16	
		Drivers enabled, Receivers disabled, $R_L$ = 100 $\Omega$		10	16		
			3	6	mA		
			0.5	1			
			Drivers enabled, No receiver loads, Driver R <sub>L</sub> = 100 $\Omega$		12	20	٣A
	31032703051	Drivers disabled, No loads		3	6	mA	
	Supply urrent	SN65LVDS180	$Supply$ urrent $SN65LVDS180 = \frac{Driver and receiver enabled, No receiver load, Driver R_{L} = 100 \Omega}{Driver enabled, Receiver disabled, R_{L} = 100 \Omega}{Driver disabled, Receiver enabled, No load}$ $Driver disabled, Receiver enabled, No load$ $Drivers and receivers enabled, No receiver loads, Driver R_{L} = 100 \Omega}{Drivers enabled, Receivers disabled, R_{L} = 100 \Omega}{Drivers enabled, Receivers disabled, R_{L} = 100 \Omega}$ $Drivers enabled, Receivers disabled, R_{L} = 100 \Omega}{Drivers enabled, Receivers disabled, R_{L} = 100 \Omega}$ $Drivers enabled, Receivers enabled, No loads$ $Disabled$ $Drivers enabled, No receiver loads, Driver R_{L} = 100 \Omega$ $Drivers enabled, No receiver loads, Driver R_{L} = 100 \Omega$	$ \begin{array}{c} \text{SN65LVDS180} & \begin{array}{c} \text{Driver and receiver enabled, No receiver load, Driver R_L = 100 } \Omega \\ \hline \text{Driver and receiver enabled, Receiver disabled, R_L = 100 } \Omega \\ \hline \text{Driver disabled, Receiver enabled, No load} \\ \hline \text{Driver disabled, Receiver enabled, No load} \\ \hline \text{Disabled} \\ \hline \text{SN65LVDS050} & \begin{array}{c} \begin{array}{c} \text{Drivers and receivers enabled, No receiver loads, Driver R_L = 100 } \Omega \\ \hline \text{Drivers enabled, Receivers disabled, R_L = 100 } \Omega \\ \hline \text{Drivers enabled, Receivers disabled, R_L = 100 } \Omega \\ \hline \text{Drivers disabled, Receivers disabled, R_L = 100 } \Omega \\ \hline \text{Drivers disabled, Receivers enabled, No loads} \\ \hline \text{Drivers disabled, Receivers enabled, No loads} \\ \hline \text{Disabled} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \begin{array}{c} \text{SN65LVDS051} \\ \hline \text{Drivers enabled, No receiver loads, Driver R_L = 100 } \Omega \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array}$	$ \begin{array}{c c} SN65LVDS180 & \hline Driver and receiver enabled, No receiver load, Driver R_L = 100 \ \Omega & 9 \\ \hline Driver enabled, Receiver disabled, R_L = 100 \ \Omega & 5 \\ \hline Driver disabled, Receiver enabled, No load & 1.5 \\ \hline Disabled & 0.5 \\ \hline Drivers and receivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, Receivers disabled, R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, Receivers disabled, R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, Receivers disabled, R_L = 100 \ \Omega & 10 \\ \hline Drivers disabled, Receivers enabled, No loads & 3 \\ \hline Disabled & 0.5 \\ \hline SN65LVDS050 & \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers disabled, Receivers enabled, No loads & 3 \\ \hline Disabled & 0.5 \\ \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled, No receiver loads, Driver R_L = 100 \ \Omega & 12 \\ \hline Drivers enabled & 0.5 \\$	$ Supply \\ urrent \\ SN65LVDS180 \\ \hline \begin{array}{c} Driver and receiver enabled, No receiver load, Driver R_L = 100 \Omega \\ \hline Driver and receiver enabled, Receiver alsold, R_L = 100 \Omega \\ \hline Driver and receiver and $	

† All typical values are at 25°C and with a 3.3-V supply.



SLLS301G - APRIL 1998 - REVISED MARCH 2000

## driver electrical characteristics over recommended operating conditions (unless otherwise noted)

	PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>OD</sub>	Differential output voltage magnitude		$R_{I} = 100\Omega$	247	340	454	
∆ V <sub>OD</sub>	Change in differential output voltage magnitude betwee states	een logic	See Figure 1 and Figure 2	-50		50	mV
VOC(SS)	Steady-state common-mode output voltage			1.125	1.2	1.375	V
$\Delta VOC(SS)$	Change in steady-state common-mode output voltage logic states	between	See Figure 3	-50		50	mV
VOC(PP)	Peak-to-peak common-mode output voltage				50	150	mV
I	H High-level input current	DE	V <sub>IH</sub> = 5 V		-0.5	-20	۸
ЧН		D VIH = 5 V		2	20	μA	
1	DE V/v 0.0		V <sub>II</sub> = 0.8 V		-0.5	-10	μA
۱	Low-level input current	D	VIL - 0.0 V		2	10	μΑ
	Short-circuit output current		VOA or $AOZ = 0 A$		3	10	mA
los	Short-circuit ouput current		$V_{OD} = 0 V$		3	10	IIIA
	High impodence output ourrept		V <sub>OD</sub> = 600 mV			±1	
νΟΖ	I <sub>OZ</sub> High-impedance output current		$V_{O} = 0 V \text{ or } V_{CC}$			±1	μA
lO(OFF)	Power-off output current		$V_{CC} = 0 V, V_{O} = 3.6 V$			±1	μA
CIN	Input capacitance				3		pF

# receiver electrical characteristics over recommended operating conditions (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	түр†	MAX	UNIT
V <sub>ITH+</sub>	Positive-going differential input voltage threshold	See Figure 5 and Table 1			100	mV
VITH-	Negative-going differential input voltage threshold	See Figure 5 and Table 1	-100			IIIV
VOH	High-level output voltage	I <sub>OH</sub> = -8 mA	2.4			V
VOL	Low-level output voltage	I <sub>OL</sub> = 8 mA			0.4	V
łı	Input current (A or B inputs)	V <sub>1</sub> = 0	-2	-11	-20	μΑ
		V <sub>I</sub> = 2.4 V	-1.2	-3		
II(OFF)	Power-off input current (A or B inputs)	$V_{CC} = 0$			±20	μΑ
IIН	High-level input current (enables)	V <sub>IH</sub> = 5 V			±10	μΑ
Ι <sub>ΙL</sub>	Low-level input current (enables)	V <sub>IL</sub> = 0.8 V			±10	μΑ
IOZ	High-impedance output current	$V_{O} = 0 \text{ or } 5 V$			±10	μΑ
Cl	Input capacitance			5		pF

<sup>†</sup> All typical values are at 25°C and with a 3.3-V supply.



#### SLLS301G - APRIL 1998 - REVISED MARCH 2000

# driver switching characteristics over recommended operating conditions (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP†	MAX	UNIT
tplh	Propagation delay time, low-to-high-level output			1.7	2.7	ns
<sup>t</sup> PHL	Propagation delay time, high-to-low-level output	$R_L = 100\Omega$ , $C_L = 10 pF$ , See Figure 6		1.7	2.7	ns
t <sub>r</sub>	Differential output signal rise time			0.8	1	ns
t <sub>f</sub>	Differential output signal fall time			0.8	1	ns
<sup>t</sup> sk(p)	Pulse skew ( t <sub>pHL</sub> – t <sub>pLH</sub>  )‡			300		ps
<sup>t</sup> sk(o)	Channel-to-channel output skew§	1		150		ps
<sup>t</sup> PZH	Propagation delay time, high-impedance-to-high-level output			4.3	10	ns
t <sub>PZL</sub>	Propagation delay time, high-impedance-to-low-level output	Coo Figure 7		4.6	10	ns
<sup>t</sup> PHZ	Propagation delay time, high-level-to-high-impedance output	See Figure 7		3.1	10	ns
<sup>t</sup> pLZ	Propagation delay time, low-level-to-high-impedance output	7		3.4	10	ns

<sup>†</sup> All typical values are at 25°C and with a 3.3-V.

<sup>‡</sup> t<sub>sk(p)</sub> is the magnitude of the time difference between the high-to-low and low-to-high propagation delay times at an output.

§ tsk(0) is the magnitude of the time difference between the outputs of a single device with all of their inputs connected together.

Itsk(pp) is the magnitude of the time difference in propagation delay times between any specified terminals of two devices when both devices operate with the same supply voltages, same temperature, and have identical packages and test circuits.

# receiver switching characteristics over recommended operating conditions (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP†	MAX	UNIT
<sup>t</sup> PLH	Propagation delay time, low-to-high-level output			3.7	4.5	ns
<sup>t</sup> PHL	Propagation delay time, high-to-low-level output			3.7	4.5	ns
<sup>t</sup> sk(p)	Pulse skew ( t <sub>pHL</sub> – t <sub>pLH</sub>  ) <sup>‡</sup>	$C_L = 10 \text{ pF}$ , See Figure 6		0.3		ns
t <sub>r</sub>	Output signal rise time			0.7	1.5	ns
t <sub>f</sub>	Output signal fall time			0.9	1.5	ns
<sup>t</sup> PZH	Propagation delay time, high-level-to-high-impedance output			2.5		ns
<sup>t</sup> PZL	Propagation delay time, low-level-to-low-impedance output	See Figure 7		2.5		ns
<sup>t</sup> PHZ	Propagation delay time, high-impedance-to-high-level output	See Figure 7		7		ns
<sup>t</sup> PLZ	Propagation delay time, low-impedance-to-high-level output		4			ns

<sup>†</sup> All typical values are at 25°C and with a 3.3-V.

‡t<sub>sk(p)</sub> is the magnitude of the time difference between the high-to-low and low-to-high propagation delay times at an output.

§ tsk(0) is the magnitude of the time difference between the outputs of a single device with all of their inputs connected together.

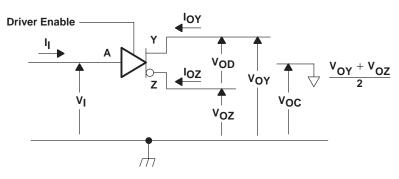
It sk(pp) is the magnitude of the time difference in propagation delay times between any specified terminals of two devices when both devices operate with the same supply voltages, same temperature, and have identical packages and test circuits.

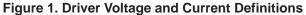


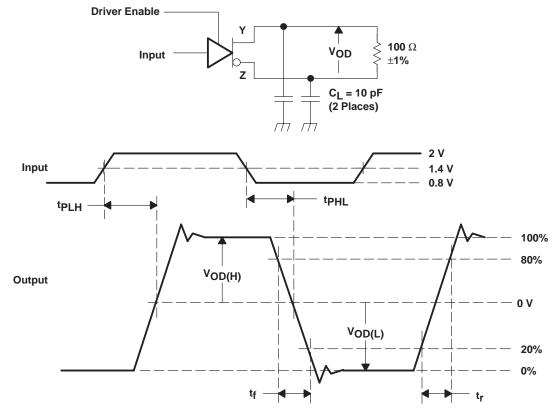
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## PARAMETER MEASUREMENT INFORMATION

driver







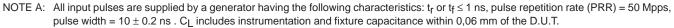
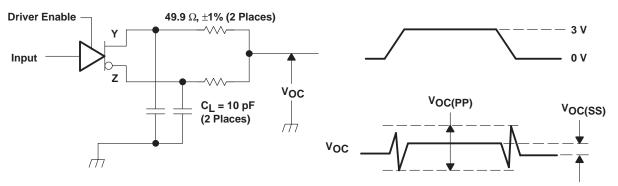


Figure 2. Test Circuit, Timing, and Voltage Definitions for the Differential Output Signal



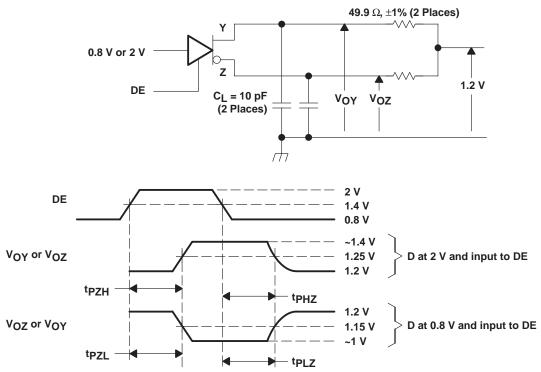
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### PARAMETER MEASUREMENT INFORMATION



NOTE A: All input pulses are supplied by a generator having the following characteristics:  $t_r$  or  $t_f \le 1$  ns, pulse repetition rate (PRR) = 50 Mpps, pulse width = 10±0.2 ns. CL includes instrumentation and fixture capacitance within 0,06 mm of the D.U.T. The measurement of VOC(PP) is made on test equipment with a -3 dB bandwidth of at least 300 MHz.

Figure 3. Test Circuit and Definitions for the Driver Common-Mode Output Voltage



NOTE A: All input pulses are supplied by a generator having the following characteristics:  $t_r$  or  $t_f \le 1$  ns, pulse repetition rate (PRR) = 0.5 Mpps, pulse width = 500 ± 10 ns . C<sub>L</sub> includes instrumentation and fixture capacitance within 0,06 mm of the D.U.T.

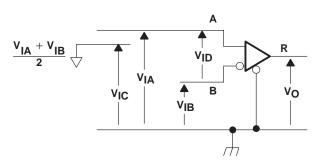
Figure 4. Enable and Disable Time Circuit and Definitions



SLLS301G - APRIL 1998 - REVISED MARCH 2000

## PARAMETER MEASUREMENT INFORMATION

receiver



**Figure 5. Receiver Voltage Definitions** 

	VOLTAGES V)	RESULTING DIFFERENTIAL INPUT VOLTAGE (mV)	RESULTING COMMON- MODE INPUT VOLTAGE (V)		
VIA	VIB	V <sub>ID</sub>	VIC		
1.25	1.15	100	1.2		
1.15	1.25	-100	1.2		
2.4	2.3	100	2.35		
2.3	2.4	-100	2.35		
0.1	0	100	0.05		
0	0.1	-100	0.05		
1.5	0.9	600	1.2		
0.9	1.5	-600	1.2		
2.4	1.8	600	2.1		
1.8	2.4	-600	2.1		
0.6	0	600	0.3		
0	0.6	-600	0.3		

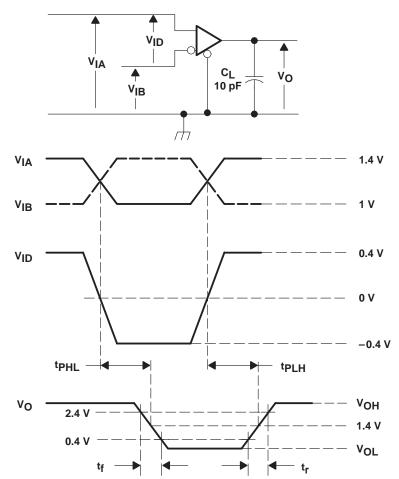
#### Table 1. Receiver Minimum and Maximum Input Threshold Test Voltages



SLLS301G - APRIL 1998 - REVISED MARCH 2000

## PARAMETER MEASUREMENT INFORMATION

## receiver (continued)



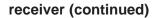
NOTE A: All input pulses are supplied by a generator having the following characteristics:  $t_r$  or  $t_f \le 1$  ns, pulse repetition rate (PRR) = 50 Mpps, pulse width = 10 ± 0.2 ns. CL includes instrumentation and fixture capacitance within 0,06 m of the D.U.T.

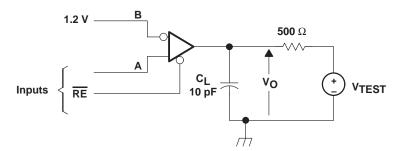
Figure 6. Timing Test Circuit and Waveforms



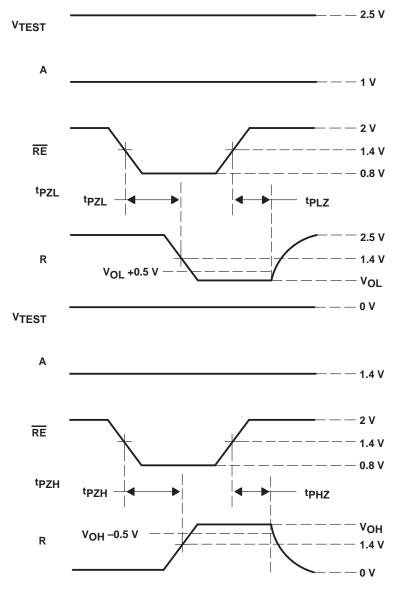
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## PARAMETER MEASUREMENT INFORMATION





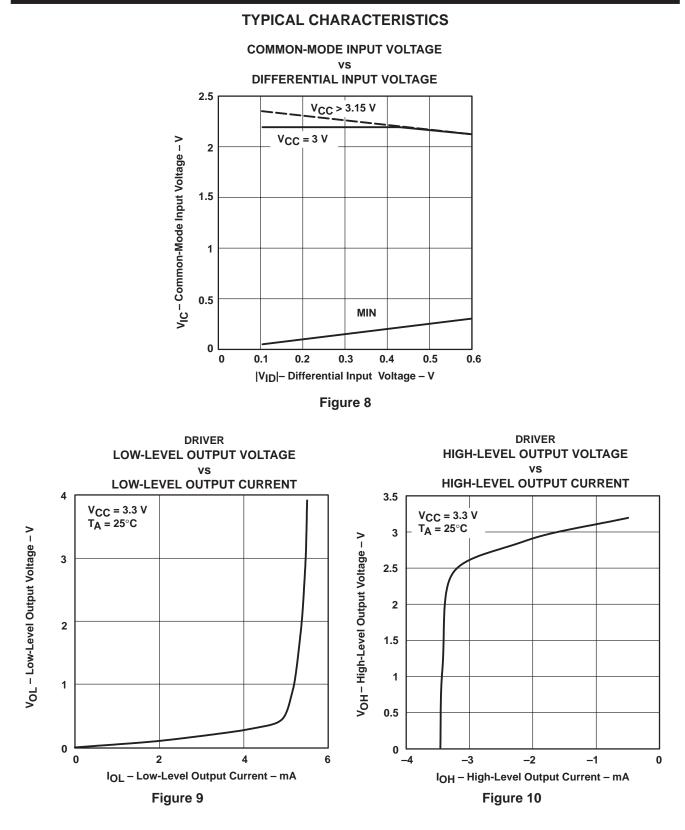
NOTE A: All input pulses are supplied by a generator having the following characteristics:  $t_r$  or  $t_f \le 1$  ns, pulse repetition rate (PRR) = 0.5 Mpps, pulse width = 500 ± 10 ns. C<sub>L</sub> includes instrumentation and fixture capacitance within 0,06 m of the D.U.T.





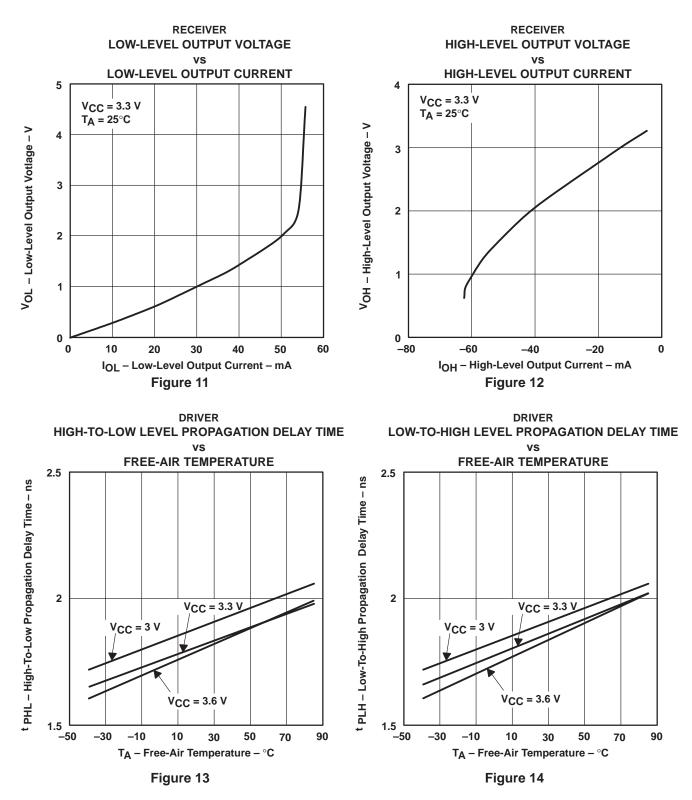


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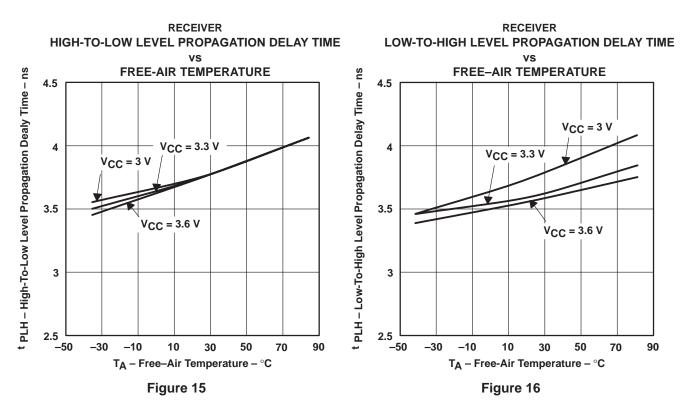
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#### **TYPICAL CHARACTERISTICS**



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**TYPICAL CHARACTERISTICS** 



SLLS301G - APRIL 1998 - REVISED MARCH 2000

#### **APPLICATION INFORMATION**

The devices are generally used as building blocks for high-speed point-to-point data transmission. Ground differences are less than 1 V with a low common–mode output and balanced interface for very low noise emissions. Devices can interoperate with RS-422, PECL, and IEEE-P1596. Drivers/Receivers maintain ECL speeds without the power and dual supply requirements.

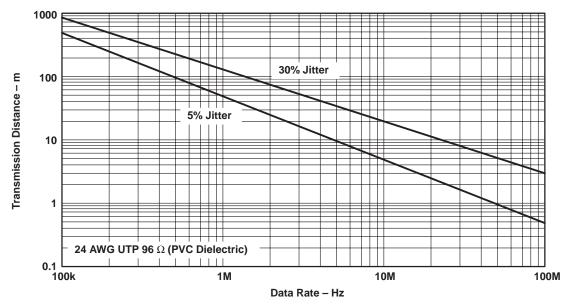


Figure 17. Data Transmission Distance Versus Rate



SLLS301G - APRIL 1998 - REVISED MARCH 2000

## **APPLICATION INFORMATION**

### fail safe

One of the most common problems with differential signaling applications is how the system responds when no differential voltage is present on the signal pair. The LVDS receiver is like most differential line receivers, in that its output logic state can be indeterminate when the differential input voltage is between -100 mV and 100 mV and within its recommended input common-mode voltage range. TI's LVDS receiver is different in how it handles the open-input circuit situation, however.

Open-circuit means that there is little or no input current to the receiver from the data line itself. This could be when the driver is in a high-impedance state or the cable is disconnected. When this occurs, the LVDS receiver will pull each line of the signal pair to near  $V_{CC}$  through 300-k $\Omega$  resistors as shown in Figure 11. The fail-safe feature uses an AND gate with input voltage thresholds at about 2.3 V to detect this condition and force the output to a high-level regardless of the differential input voltage.

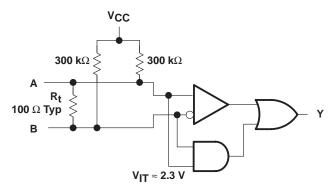


Figure 18. Open-Circuit Fail Safe of the LVDS Receiver

It is only under these conditions that the output of the receiver will be valid with less than a 100-mV differential input voltage magnitude. The presence of the termination resistor, Rt, does not affect the fail-safe function as long as it is connected as shown in the figure. Other termination circuits may allow a dc current to ground that could defeat the pullup currents from the receiver and the fail-safe feature.

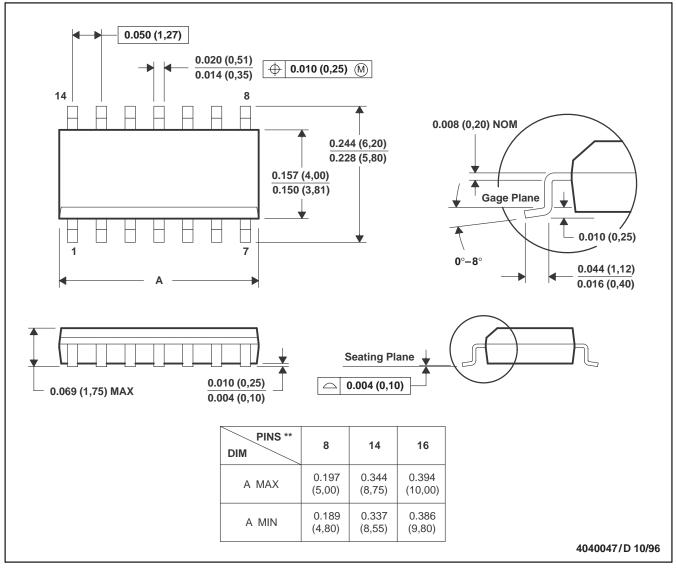


SLLS301G - APRIL 1998 - REVISED MARCH 2000

MECHANICAL DATA

#### PLASTIC SMALL-OUTLINE PACKAGE

#### D (R-PDSO-G\*\*) 14 PIN SHOWN



NOTES: A. All linear dimensions are in inches (millimeters).

B. This drawing is subject to change without notice.

C. Body dimensions do not include mold flash or protrusion, not to exceed 0.006 (0,15).

D. Falls within JEDEC MS-012

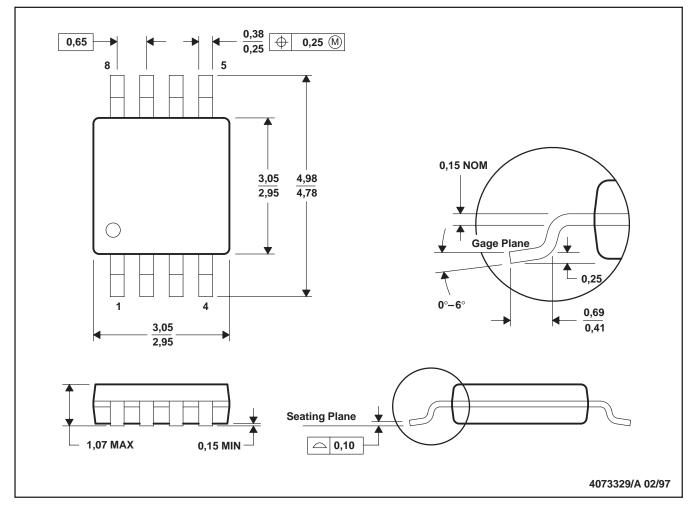


SLLS301G - APRIL 1998 - REVISED MARCH 2000

**MECHANICAL DATA** 

#### DGK (R-PDSO-G8)

PLASTIC SMALL-OUTLINE PACKAGE



NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion.
- D. Falls within JEDEC MO-187



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