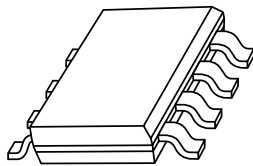


# DATA SHEET



## **KMZ43T** Magnetic field sensor

Product specification  
Supersedes data of 2003 Mar 26

2003 Sep 15

# Magnetic field sensor

# KMZ43T

## DESCRIPTION

The KMZ43T is a sensitive magnetic field sensor, employing the magnetoresistive effect of thin-film permalloy. The sensor contains two galvanic separated Wheatstone bridges, at a relative angle of 45° to one another.

A rotating magnetic field in the x-y plane will produce two independent sinusoidal output signals, one a function of  $+\cos(2\alpha)$  and the second a function of  $+\sin(2\alpha)$ ,  $\alpha$  being the angle between sensor and field direction (see Fig.3). Unlike the KMZ41<sup>(1)</sup>, which needs a saturation field strength of 100 kA/m, the KMZ43T is suited to high precision angle measurement applications under low field conditions (saturation field strength 25 kA/m).

The sensor can be operated at any frequency between DC and 1 MHz.

The information in application notes AN00023 (Contactless Angle Measurement Using KMZ41 and UZZ9000) and AN00004 (Contactless Angle Measurement Using KMZ41 and UZZ9001) is applicable to the KMZ43T, but one should be aware of the difference in the bridge 1 output.

## PINNING

PIN	SYMBOL	DESCRIPTION
1	-V <sub>O1</sub>	output voltage bridge 1
2	-V <sub>O2</sub>	output voltage bridge 2
3	V <sub>CC2</sub>	supply voltage bridge 2
4	V <sub>CC1</sub>	supply voltage bridge 1
5	+V <sub>O1</sub>	output voltage bridge 1
6	+V <sub>O2</sub>	output voltage bridge 2
7	GND2	ground 2
8	GND1	ground 1

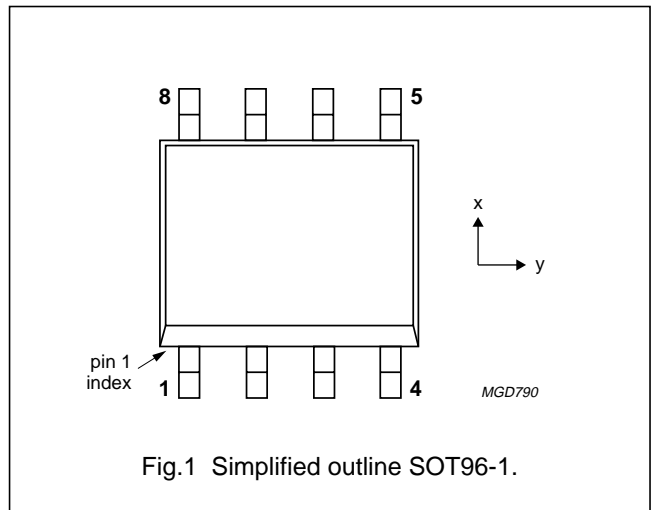


Fig.1 Simplified outline SOT96-1.

(1) The KMZ41 delivers a  $+\sin(2\alpha)$  and a  $-\cos(2\alpha)$  signal.

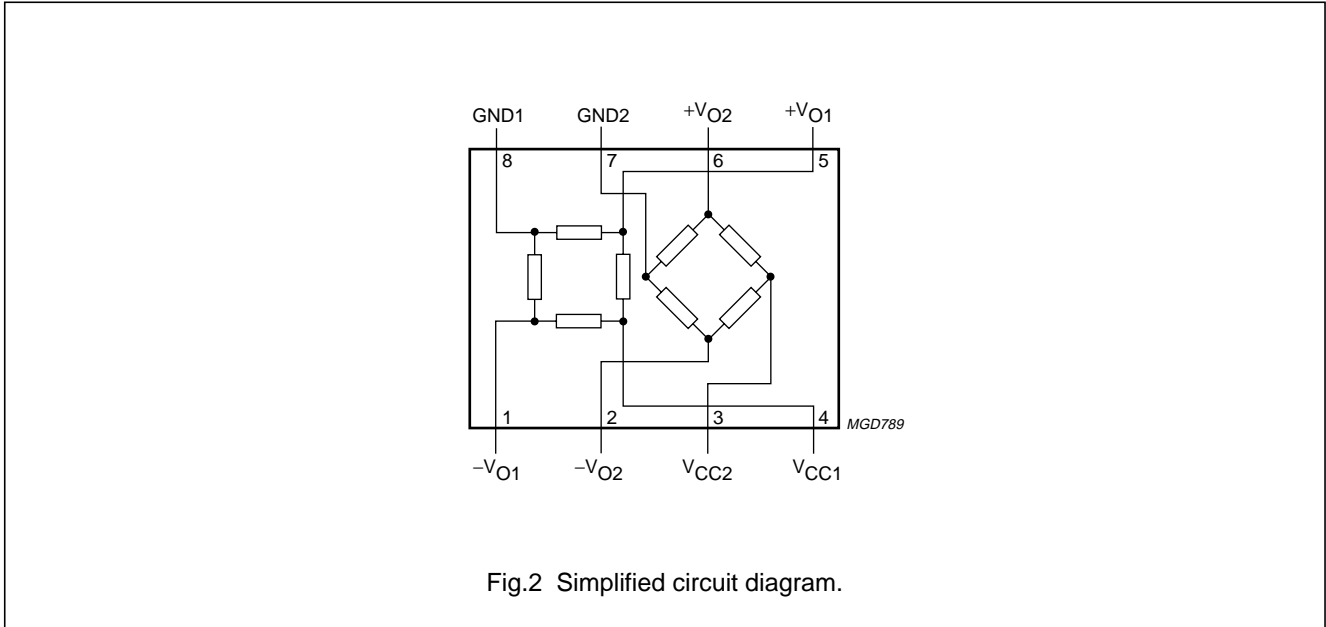
## QUICK REFERENCE DATA

SYMBOL	PARAMETER	MIN.	TYP.	MAX.	UNIT
<b>Per bridge</b>					
V <sub>CC</sub>	supply voltage	-	5	9	V
S	sensitivity ( $\alpha_2 = 0^\circ$ ; $\alpha_1 = 135^\circ$ )	2.1	2.35	2.6	mV/°
V <sub>offset</sub>	offset voltage per supply voltage	-2	-	+2	mV/V
R <sub>bridge</sub>	bridge resistance per bridge	2.7	3.2	3.7	kΩ

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CIRCUIT DIAGRAM



LIMITING VALUES

In accordance with the Absolute Maximum Rating System (IEC 60134).

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
V <sub>CC1</sub>	supply voltage bridge 1		-	9	V
V <sub>CC2</sub>	supply voltage bridge 2		-	9	V
T <sub>stg</sub>	storage temperature		-65	+150	°C
T <sub>amb</sub>	operating ambient temperature		-40	+150	°C

STIMULATING FIELD STRENGTH

CONDITIONS	MIN.	CONDITIONS	MIN.	MAX.	UNIT
H <sub>ext</sub>	magnetic field strength	note 1	25	-	kA/m

Note

- The minimum stimulating magnetic field in the x-y plane to ensure minimum angular inaccuracy specified in note 11 to Characteristics table.

THERMAL CHARACTERISTICS

SYMBOL	PARAMETER	VALUE	UNIT
R <sub>th j-a</sub>	thermal resistance from junction to ambient	155	K/W

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## CHARACTERISTICS

$T_{amb} = 25\text{ °C}$  and  $H_{ext} = 25\text{ kA/m}$ ;  $V_{CC1} = 5\text{ V}$ ;  $V_{CC2} = 5\text{ V}$ ; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
$\omega$	operating angular velocity		0	–	1	MHz
k	amplitude synchronism	note 9	99.5	100	100.5	%
$TC_k$	temperature coefficient of amplitude synchronism	$T_{amb} = -40\text{ to }+150\text{ °C}$ ; note 10	-0.01	0	-0.01	%/K
$\Delta\alpha$	angular inaccuracy	note 11	0	0.05	0.1	deg
<b>Per bridge</b>						
$V_{CC}$	supply voltage		–	5	9	V
$V_{offset}$	offset voltage per supply voltage	see Fig.3	-2	0	+2	mV/V
S	sensitivity	open circuit; note 1 $\alpha_1 = 135^\circ$ (bridge 1) $\alpha_2 = 0^\circ$ (bridge 2)	2.1 2.1	2.35 2.35	2.6 2.6	mV/° mV/°
$TC_S$	temperature coefficient of sensitivity	$T_{amb} = -40\text{ to }+150\text{ °C}$ ; note 2	-0.25	-0.29	-0.33	%/K
$V_{peak}$	peak output voltage	note 3; see Fig.3	60	67	75	mV
$TC_{V_{peak}}$	temperature coefficient of peak output voltage	$T_{amb} = -40\text{ to }+150\text{ °C}$ ; note 4	-0.25	-0.29	-0.33	%/K
$R_{bridge}$	bridge resistance	note 5	2.7	3.2	3.7	k $\Omega$
$TC_{R_{bridge}}$	temperature coefficient of bridge resistance	$T_{amb} = -40\text{ to }+150\text{ °C}$ ; note 6	0.28	0.32	0.35	%/K
$TC_{V_{offset}}$	temperature coefficient of offset voltage	$T_{amb} = -40\text{ to }+150\text{ °C}$ ; note 7; see Fig.3	-4	0	+4	( $\mu$ V/V)/K
FH	hysteresis of output voltage	note 8	0	0.05	0.18	%FS

## Notes

1. Sensitivity changes with angle due to sinusoidal output.

$$2. TC_S = 100 \times \frac{S_{T_2} - S_{T_1}}{S_{T_1} \times 190^\circ\text{C}} \text{ where } T_1 = -40\text{ °C}; T_2 = 150\text{ °C}.$$

3.  $V_{peak} = |(V_{out\ max} - V_{offset})|$ . Periodicity of  $V_{peak}$ :  $\sin(2\alpha)$  and  $\cos(2\alpha)$  respectively.

$$4. TC_{V_{peak}} = 100 \times \frac{V_{peak(T_2)} - V_{peak(T_1)}}{V_{peak(T_1)} \times 190^\circ\text{C}} \text{ where } T_1 = -40\text{ °C}; T_2 = 150\text{ °C}.$$

5. Bridge resistance between pins 8 and 4, pins 7 and 3, pins 5 and 1, and pins 6 and 2.

$$6. TC_{R_{bridge}} = 100 \times \frac{R_{bridge(T_2)} - R_{bridge(T_1)}}{R_{bridge(T_1)} \times 190^\circ\text{C}} \text{ where } T_1 = -40\text{ °C}; T_2 = 150\text{ °C}.$$

$$7. TC_{V_{offset}} = \frac{V_{offset(T_2)} - V_{offset(T_1)}}{190^\circ\text{C}} \text{ where } T_1 = -40\text{ °C}; T_2 = 150\text{ °C}.$$

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$$8. FH_1 = 100 \times \left| \frac{V_{O1(67.5^\circ) 135^\circ \Rightarrow 45^\circ} - V_{O1(67.5^\circ) 45^\circ \Rightarrow 135^\circ}}{2 \times V_{peak1}} \right|.$$

$$FH_2 = 100 \times \left| \frac{V_{O2(22.5^\circ) 90^\circ \Rightarrow 0^\circ} - V_{O2(22.5^\circ) 0^\circ \Rightarrow 90^\circ}}{2 \times V_{peak2}} \right|.$$

$$9. k = 100 \times \frac{V_{peak1}}{V_{peak2}}.$$

$$10. TC_k = 100 \times \frac{k_{T_2} - k_{T_1}}{k_{T_1} \times 190^\circ C} \text{ where } T_1 = -40^\circ C; T_2 = 150^\circ C.$$

$$11. \Delta\alpha = |\alpha_{real} - \alpha_{measured}| \text{ without offset voltage influences due to deviations from ideal sinusoidal characteristics.}$$

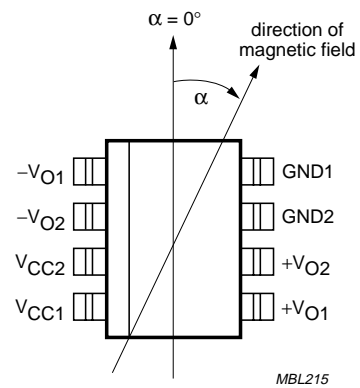
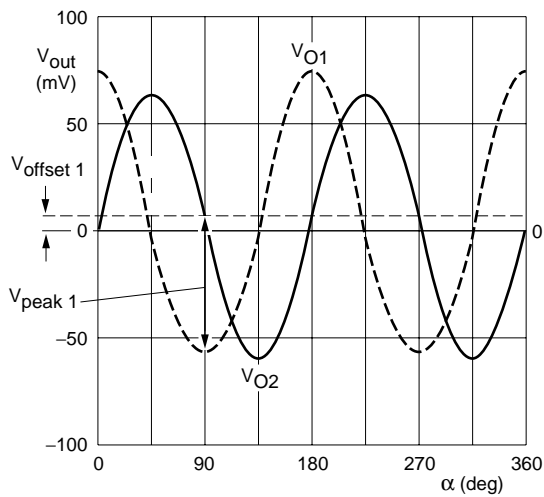


Fig.3 Output signals related to the direction of the magnetic field.

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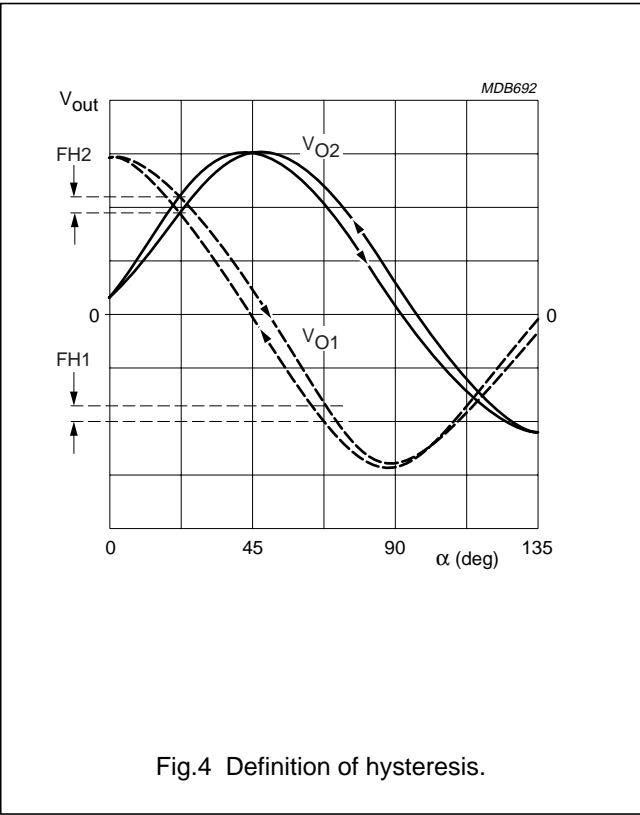


Fig.4 Definition of hysteresis.

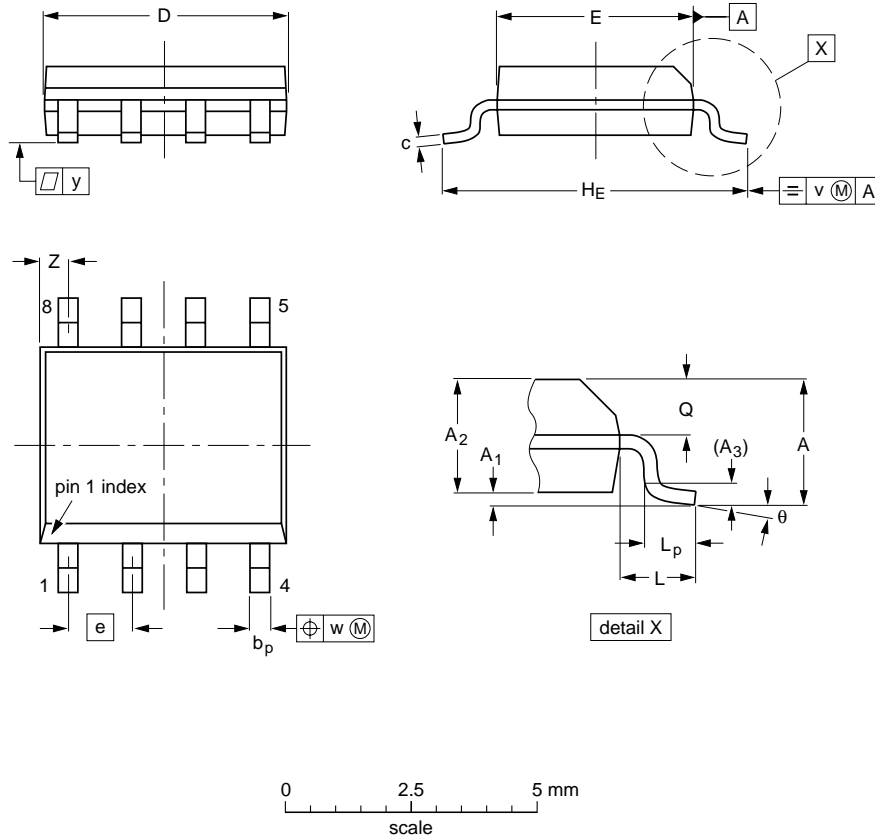
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PACKAGE OUTLINE

SO8: plastic small outline package; 8 leads; body width 3.9 mm

SOT96-1



DIMENSIONS (inch dimensions are derived from the original mm dimensions)

UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	b <sub>p</sub>	c	D <sup>(1)</sup>	E <sup>(2)</sup>	e	H <sub>E</sub>	L	L <sub>p</sub>	Q	v	w	y	z <sup>(1)</sup>	θ
mm	1.75	0.25 0.10	1.45 1.25	0.25	0.49 0.36	0.25 0.19	5.0 4.8	4.0 3.8	1.27	6.2 5.8	1.05	1.0 0.4	0.7 0.6	0.25	0.25	0.1	0.7 0.3	8° 0°
inches	0.069	0.010 0.004	0.057 0.049	0.01	0.019 0.014	0.0100 0.0075	0.20 0.19	0.16 0.15	0.05	0.244 0.228	0.041	0.039 0.016	0.028 0.024	0.01	0.01	0.004	0.028 0.012	

Notes

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.
2. Plastic or metal protrusions of 0.25 mm (0.01 inch) maximum per side are not included.

OUTLINE VERSION	REFERENCES			EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	JEITA		
SOT96-1	076E03	MS-012			99-12-27 03-02-18

## Magnetic field sensor

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## DATA SHEET STATUS

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For additional information please visit <http://www.semiconductors.philips.com>. Fax: +31 40 27 24825

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