

General Description

The MAX4090 3V/5V, 6dB video buffer with sync-tip clamp, and low-power shutdown mode is available in tiny SOT23 and SC70 packages. The MAX4090 is designed to drive DC-coupled, 150Ω back-terminated video loads in portable video applications such as digital still cams, portable DVD players, digital camcorders, PDAs, video-enabled cell phones, portable game systems, and notebook computers. The input clamp positions the video waveform at the output and allows the MAX4090 to be used as a DC-coupled output driver.

The MAX4090 operates from a single 2.7V to 5.5V supply and consumes only 6.5mA of supply current. The low-power shutdown mode reduces the supply current to 150nA, making the MAX4090 ideal for low-voltage, battery-powered video applications.

The MAX4090 is available in tiny 6-pin SOT23 and SC70 packages and is specified over the extended -40°C to +85°C temperature range.

Applications

Portable Video/Game Systems/DVD Players Digital Camcorders/Televisions/Still Cameras **PDAs**

Video-Enabled Cell Phones Notebook Computers Portable/Flat-Panel Displays

Features

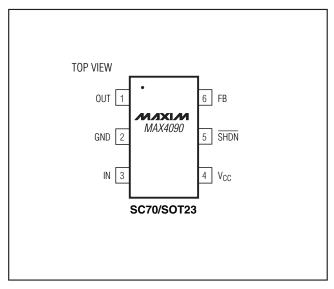
- ♦ Single-Supply Operation from 2.7V to 5.5V
- ♦ Input Sync-Tip Clamp
- **♦ DC-Coupled Output**
- **♦ Low-Power Shutdown Mode Reduces Supply** Current to 150nA
- ♦ Available in Space-Saving SOT23 and SC70 **Packages**

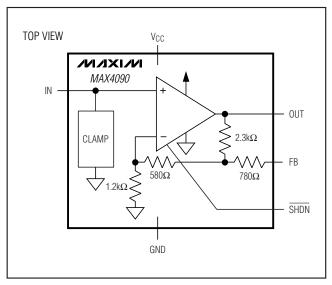
Ordering Information

PART	TEMP RANGE	PIN- PACKAGE	TOP MARK
MAX4090EXT-T	-40°C to +85°C	6 SC70-6	ABM
MAX4090EUT-T	-40°C to +85°C	6 SOT23-6	ABOX

Pin Configuration

Block Diagram





NIXIN

Maxim Integrated Products 1

ABSOLUTE MAXIMUM RATINGS

V _{CC} to GND0.3V to +6V
OUT, FB, SHDN to GND0.3V to (V _{CC} + 0.3V)
IN to GND (Note 1)
IN Short-Circuit Duration from -0.3V to VCLP1min
Output Short-Circuit Duration to V _{CC} or GND Continuous
Continuous Power Dissipation ($T_A = +70^{\circ}C$)
6-Pin SOT23 (derate 8.7mW/°C above +70°C)695mW
6-Pin SC70 (derate 3.1mW/°C above +70°C)245mW

Operating Temperature Range	40°C to +85°C
Junction Temperature	+150°C
Storage Temperature Range	65°C to +150°C
Lead Temperature (soldering, 10	0s)+300°C

Note 1: V_{CLP} is the input clamp voltage as defined in the *DC Electrical Characteristics* table.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

DC ELECTRICAL CHARACTERISTICS

(V_{CC} = 3.0V, GND = 0V, C_{IN} = 0.1 μ F from IN to GND, R_L = infinity to GND, FB shorted to OUT, \overline{SHDN} = 3.0V, T_A = -40°C to +85°C. Typical values are at T_A = +25°C, unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Supply Voltage Range	Vcc	Guaranteed by PSRR		2.7		5.5	V
Outland and Cumply Command	la a		V _{CC} = 3V		6.5	10	mA
Quiescent Supply Current	lcc	VIN = VCLP	$V_{CC} = 5V$		6.5	10	
Shutdown Supply Current	ISHDN	SHDN = 0V			0.15	1	μΑ
Input Clamp Voltage	VCLP	Input referred		0.27	0.38	0.47	V
Input Voltage Range	VIN	Inferred from voltage	gain (Note 3)	VCLP		1.45	V
Input Bias Current	I _{BIAS}	V _{IN} = 1.45V			22.5	35	μΑ
Input Resistance		V _{CLP} + 0.5V < V _{IN} <	V _{CLP} + 1V		3		MΩ
Voltage Gain	Ay	$R_L = 150\Omega, 0.5V < V$	IN < 1.45V (Note 4)	1.9	2	2.1	V/V
Power-Supply Rejection Ratio	PSRR	2.7V < V _{CC} < 5.5V		60	80		dB
0		$R_L = 150\Omega$ to GND	V _{CC} = 3V	2.55	2.7		V
Output Voltage High Swing	Voн		$V_{CC} = 5V$	4.3	4.6		
Output Voltage Low Swing	V _{OL}	$R_L = 150\Omega$ to GND			VCLP	0.47	V
Outroot Outroot	1 -	Sourcing, $R_L = 20\Omega$ to GND		45	85		^
Output Current	lout	Sinking, $R_L = 20\Omega$ to V_{CC}		40	85		mA
Output Short-Circuit Current	Isc	OUT shorted to V _{CC}	or GND		110		mA
SHDN Logic-Low Threshold	VIL					V _C C x 0.3	V
SHDN Logic-High Threshold	VIH			V _{CC} x 0.7			V
SHDN Input Current	lін				0.003	1	μΑ
	_		At DC	4 2			
Shutdown Output Impedance	Rout (Disabled)	SHDN = 0V	At 3.58MHz or 4.43MHz				kΩ

AC ELECTRICAL CHARACTERISTICS

 $(V_{CC}=3.0V,\,GND=0V,\,FB\,$ shorted to OUT, $C_{IN}=0.1\mu F,\,R_{IN}=75\Omega$ to GND, $R_{L}=150\Omega$ to GND, $\overline{SHDN}=V_{CC},\,T_{A}=+25^{\circ}C,\,$ unless otherwise noted.)

PARAMETER	SYMBOL	COND	DITIONS	MIN	TYP	MAX	UNITS	
Small-Signal -3dB Bandwidth	BWSS	$V_{OUT} = 100 \text{mVp-p}$			55		MHz	
Large-Signal -3dB Bandwidth	BWLS	V _{OUT} = 2V _{P-P}			45		MHz	
Small-Signal 0.1dB Gain Flatness	BW _{0.1dBSS}	$V_{OUT} = 100 \text{mV}_{P-P}$			25		MHz	
Large-Signal 0.1dB Gain Flatness	BW _{0.1dBLS}	V _{OUT} = 2V _{P-P}			17		MHz	
Slew Rate	SR	V _{OUT} = 2V step			275		V/µs	
Settling Time to 0.1%	ts	V _{OUT} = 2V step			25		ns	
Power-Supply Rejection Ratio	PSRR	f = 100kHz			50		dB	
Output Impedance	Z _{OUT}	f = 5MHz			2.5		Ω	
Differential Gain	DG	NTSC	$V_{CC} = 3V$		1		_ %	
Differential Gain			$V_{CC} = 5V$		0.5		/0	
Differential Phase	DP	NTSC	$V_{CC} = 3V$		0.8		Dograda	
Differential Friase	DI	NISC	$V_{CC} = 5V$		0.5		Degrees	
Group Delay	D/dT	f = 3.58MHz or 4.43N	ЛНz		20		ns	
Peak Signal to RMS Noise	SNR	$V_{IN} = 1V_{P-P}$, $10MHz$	BW		65		dB	
Droop		$C_{IN} = 0.1 \mu F \text{ (Note 4)}$			2	3	%	
SHDN Enable Time	ton	$V_{IN} = V_{CLP} + 1V$, $\overline{SHDN} = 3V$, V_{OUT} settled to within 1% of the final voltage			250		ns	
SHDN Disable Time	toff	$V_{IN} = V_{CLP} + 1V$, $\overline{SHDN} = 0V$, V_{OUT} settled to below 1% of the output voltage			50		ns	

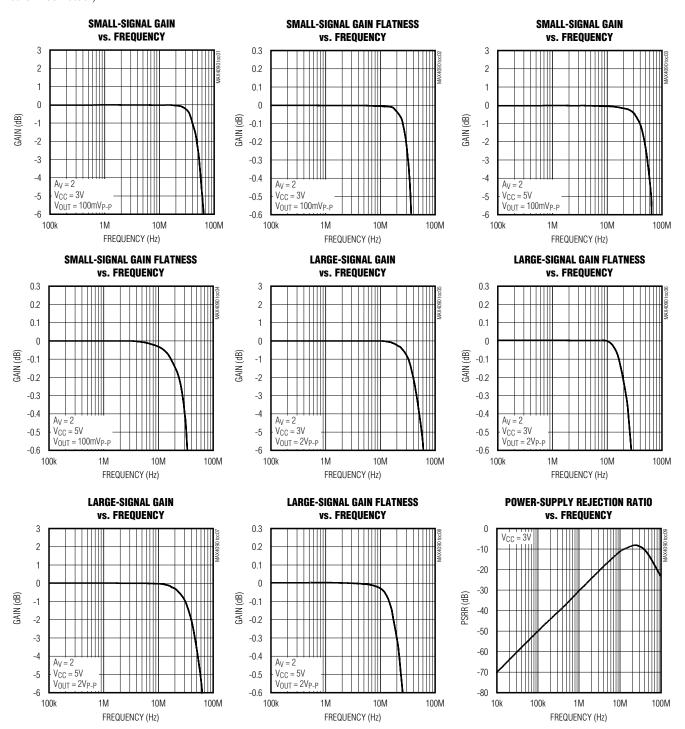
Note 2: All devices are 100% production tested at $T_A = +25^{\circ}C$. Specifications over temperature limits are guaranteed by design.

Note 3: Voltage gain (A_V) is referenced to the clamp voltage, i.e., an input voltage of $V_{IN} = V_{CLP} + VI$ would produce an output voltage of $V_{OUT} = V_{CLP} + A_V \times VI$.

Note 4: Droop is guaranteed by the Input Bias Current specification.

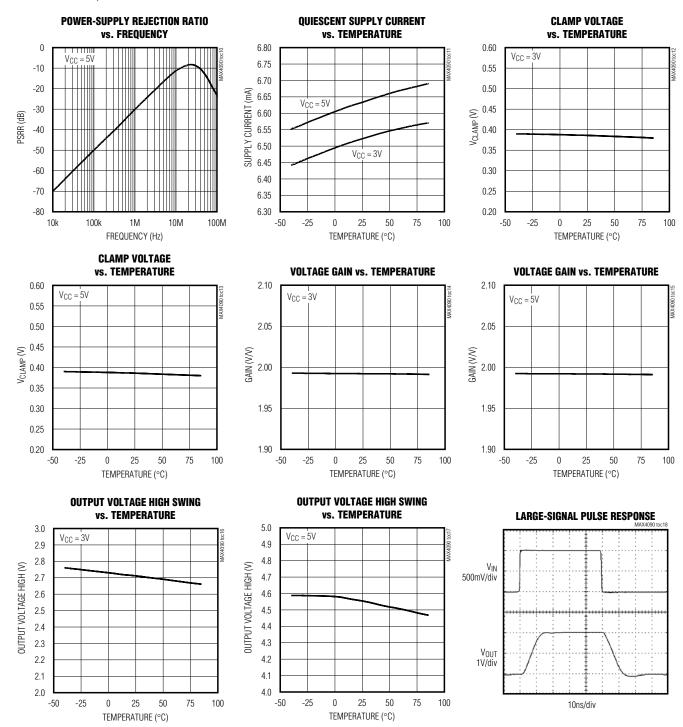
Typical Operating Characteristics

 $(V_{CC}=3.0V, \text{ GND}=0V, \text{ FB shorted to OUT}, C_{IN}=0.1\mu\text{F}, R_{IN}=75\Omega \text{ to GND}, R_L=150\Omega \text{ to GND}, \overline{SHDN}=V_{CC}, T_A=+25^{\circ}\text{C}, \text{ unless otherwise noted.})$



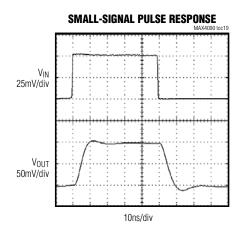
Typical Operating Characteristics (continued)

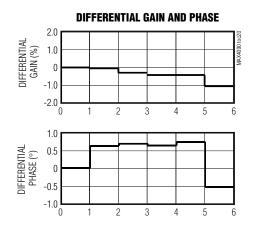
 $(V_{CC}=3.0V, GND=0V, FB \text{ shorted to OUT}, C_{IN}=0.1\mu F, R_{IN}=75\Omega \text{ to GND}, R_{L}=150\Omega \text{ to GND}, \overline{SHDN}=V_{CC}, T_{A}=+25^{\circ}C, unless otherwise noted.)}$



Typical Operating Characteristics (continued)

 $(V_{CC}=3.0V, GND=0V, FB \text{ shorted to OUT}, C_{IN}=0.1\mu F, R_{IN}=75\Omega \text{ to GND}, R_L=150\Omega \text{ to GND}, \overline{SHDN}=V_{CC}, T_A=+25^{\circ}C, unless otherwise noted.)}$

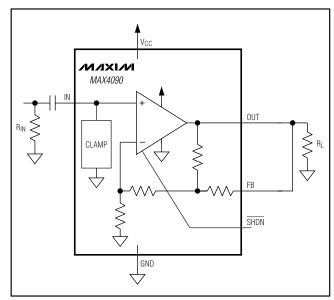




Pin Description

PIN	NAME	FUNCTION
1	OUT	Video Output
2	GND	Ground
3	IN	Video Input
4	Vcc	Power-Supply Voltage. Bypass with a 0.1µF capacitor to ground as close to pin as possible.
5	SHDN	Shutdown. Pull SHDN low to place the MAX4090 in low-power shutdown mode.
6	FB	Feedback. Connect to OUT.

Typical Application Circuit



Detailed Description

The MAX4090 3V/5V, 6dB video buffer with sync-tip clamp and low-power shutdown mode is available in tiny SOT23 and SC70 packages. The MAX4090 is designed to drive DC-coupled, 150Ω back-terminated video loads in portable video applications such as digital still cams, portable DVD players, digital camcorders, PDAs, videoenabled cell phones, portable game systems, and notebook computers. The input clamp positions the video waveform at the output and allows the MAX4090 to be used as a DC-coupled output driver.

The MAX4090 operates from a single 2.7V to 5.5V supply and consumes only 6.5mA of supply current. The low-power shutdown mode reduces the supply current to 150nA, making the MAX4090 ideal for low-voltage, battery-powered video applications.

The input signal to the MAX4090 is AC-coupled through a capacitor into an active sync-tip clamp circuit, which places the minimum of the video signal at approximately 0.38V. The output buffer amplifies the video signal while still maintaining the 0.38V clamp voltage at the output. For example, if $V_{IN} = 0.38V$, then $V_{OUT} = 0.38V$. If $V_{IN} = (0.38V + 1V) = 1.38V$, then $V_{OUT} = (0.38V + 2 \text{ X} (1V)) = 2.38V$. The net result is that a 2V video output signal swings within the usable output voltage range of the output buffer when $V_{CC} = 3V$.

Shutdown Mode

The MAX4090 features a low-power shutdown mode ($\overline{\text{SHDN}} = 150\text{nA}$) for battery-powered/portable applications. Pulling the $\overline{\text{SHDN}}$ pin high enables the output. Connecting the $\overline{\text{SHDN}}$ pin to ground (GND) disables the output and places the MAX4090 into a low-power shutdown mode.

Applications Information Input Coupling the MAX4090

The MAX4090 input must be AC-coupled because the input capacitor stores the clamp voltage. The MAX4090 requires a typical value of 0.1 μ F for the input clamp to meet the Line Droop specification. A minimum of a ceramic capacitor with an X7R temperature coefficient is recommended to avoid temperature-related problems with Line Droop. For extended temperature operation, such as outdoor applications, or where the impressed voltage is close to the rated voltage of the capacitor, a film dielectric is recommended. Increasing the capacitor value slows the clamp capture time. Values above 0.5 μ F should be avoided since they do not improve the clamp's performance.

The active sync-tip clamp also requires that the input impedance seen by the input capacitor be less than 100Ω typically to function properly. This is easily met by the 75Ω input resistor prior to the input-coupling capacitor and the back termination from a prior stage. Insufficient input resistance to ground causes the MAX4090 to appear to oscillate. Never operate the MAX4090 in this mode.

Using the MAX4090 with the Reconstruction Filter

In most video applications, the video signal generated from the DAC requires a reconstruction filter to smooth out the signal and attenuate the sampling aliases. The MAX4090 is a direct DC-coupled output driver, which can be used after the reconstruction filter to drive the video signal. The driving load from the video DAC can be varied from 75Ω to 300Ω . A low input impedance (< 100Ω) is required by the MAX4090 in normal operation, special care must be taken when a reconstruction filter is used in front of the MAX4090.

For standard video signal, the video passband is about 6MHz and the system oversampling frequency is at 27MHz. Normally, a 9MHz BW lowpass filter can be used for the reconstruction filter. This section demonstrates the methods to build simple 2nd- and 3rd-order passive butterworth lowpass filters at the 9MHz cutoff frequency and the techniques to use them with the MAX4090 (Figures 1 and 4).

2nd-Order Butterworth Lowpass Filter Realization Table 1 shows the normalized 2nd-order butterworth LPF component values at 1rad/s with a source/load impedance of 1Ω .

With the following equations, the L and C can be calculated for the cutoff frequency at 9MHz. Table 2 shows the appropriated L and C values for different source/load impedance, the bench measurement values for the -3dB BW and attenuation at 27MHz. There is approximately 20dB attenuation at 27MHz, which effectively attenuates the sampling aliases. The MAX4090 requires low input impedance for stable operation and it does not like the reactive input impedance. For R1/R2 greater than 100 Ω , a series resistor RIS (Figure 1)

Table 1. 2nd Order Butterworth Lowpass Filter Normalized Values

$Rn1 = Rn2 (\Omega)$	Cn1 (F)	Ln1 (H)
1	1.414	1.414

between 20Ω to 100Ω is needed to isolate the input capacitor (C4) to the filter to prevent the oscillation problem.

$$C = \frac{C_n}{2\pi f_C R_l} L = \frac{L_n R_L}{2\pi f_C}$$

Figure 2 shows the frequency response for R1 = R2 = 150Ω . At 6MHz, the attenuation is about 1.4dB. The attenuation at 27MHz is about 20dB. Figure 3 shows the multiburst response for R1 = R2 = 150Ω .

3rd-Order Butterworth Lowpass Filter Realization

If more flat passband and more stopband attenuation are needed, a 3rd-order LPF can be used. The design procedures are similar to the 2nd-order butterworth LPF.

Table 3 shows the normalized 3rd-order butterworth lowpass filter with the cutoff frequency at 1 rad/s and the stopband frequency at 3 rad/s. Table 4 shows the appropriated L and C values for different source/load impedance and the bench measurement values for -3dB BW and attenuation at 27MHz. The attenuation is over 40dB at 27MHz. At 6MHz, the attenuation is approximately 0.6dB for R1 = R2 = 150Ω (Figure 5).

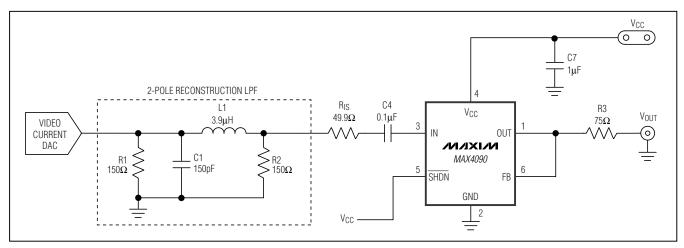


Figure 1. 2nd-Order Butterworth LPF with MAX4090

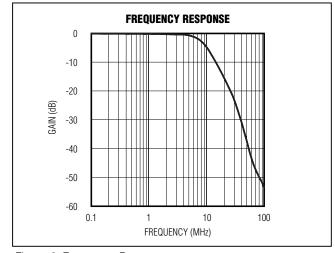


Figure 2. Frequency Response

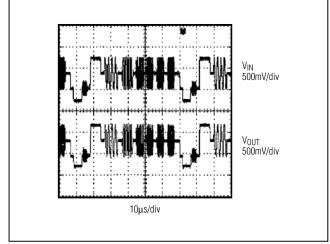


Figure 3. Multiburst Response

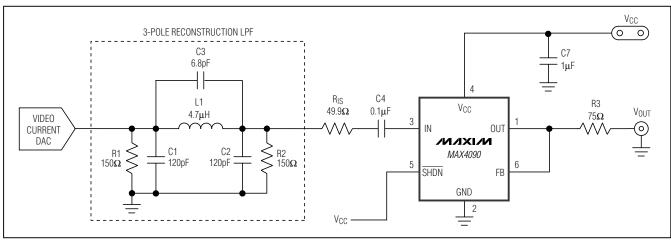


Figure 4. 3rd-Order Butterworth LPF with MAX4090

Table 2. Bench Measurement Values

R1 = R2 (Ω)	C1 (pf)	L1 (μΗ)	R _{IS} (Ω)	3dB BW (MHz)	ATTENUATION AT 27MHz (dB)
75	330	1.8	0	8.7	20
150	150	3.9	50	9.0	20
200	120	4.7	50	9.3	22
300	82	8.2	100	8.7	20

Table 3. 3rd-Order Butterworth Lowpass Filter Normalized Values

$Rn1 = Rn2$ (Ω)	Cn1 (F)	Cn2 (F)	Cn3 (F)	Ln1 (H)	
1	0.923	0.923	0.06	1.846	

Table 4. Bench Measurement Values

$R1 = R2 (\Omega)$	C1 (pF)	C2 (pF)	C3 (pF)	L (µH)	R _{IS} (Ω)	3dB BW (MHz)	ATTENUATION AT 27MHz (dB)
75	220	220	15.0	2.2	0	9.3	43
150	120	120	6.8	4.7	50	8.9	50
300	56	56	3.3	10.0	100	9.0	45

Sag Correction

In a 5V application, the MAX4090 can use the sag configuration if an AC-coupled output video signal is required. Sag correction refers to the low-frequency compensation for the highpass filter formed by the 150Ω load and the output capacitor. In video applications, the cutoff frequency must be low enough to pass the vertical sync interval to avoid field tilt. This cutoff frequency should be less than 5Hz, and the coupling capacitor must be very large in normal configuration,

typically > 220 μ F. In sag configuration, the MAX4090 eliminates the need for large coupling capacitors, and instead requires two 22 μ F capacitors (Figure 6) to reach the same performance as the large capacitor. Bench experiments show that increasing the output coupling capacitor C5 beyond 47 μ F does not improve the performance. If the supply voltage is less than 4.5V, the sag correction is not recommended for the MAX4090.

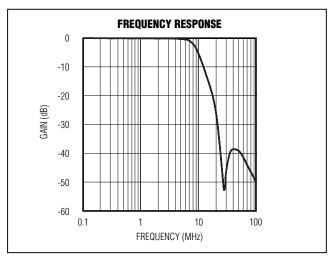


Figure 5. Frequency Response for R1 = R2 = 150Ω

Layout and Power-Supply Bypassing

The MAX4090 operates from single 2.7V to 5.5V supply. Bypass the supply with a 0.1µF capacitor as close to the pin as possible. Maxim recommends using microstrip and stripline techniques to obtain full bandwidth. To ensure that the PC board does not degrade the device's performance, design it for a frequency greater than 1GHz. Pay careful attention to inputs and outputs to avoid large parasitic capacitance. Whether or not you use a constant-impedance board, observe the following design guidelines:

- Do not use wire-wrap boards; they are too inductive.
- Do not use IC sockets; they increase parasitic capacitance and inductance.
- Use surface-mount instead of through-hole components for better, high-frequency performance.
- Use a PC board with at least two layers; it should be as free from voids as possible.
- Keep signal lines as short and as straight as possible.
 Do not make 90° turns; round all corners.

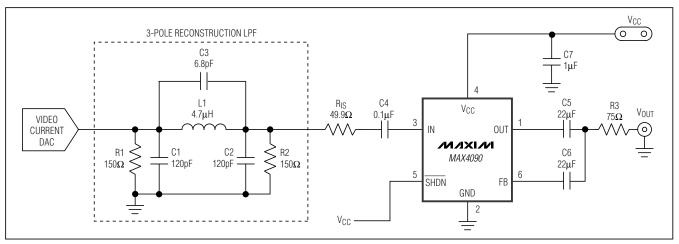


Figure 6. Sag Correction Configuration

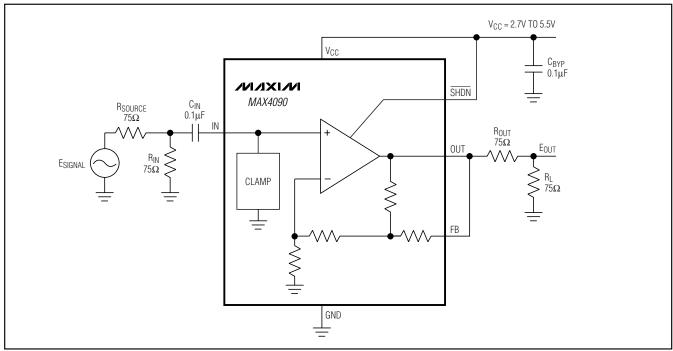


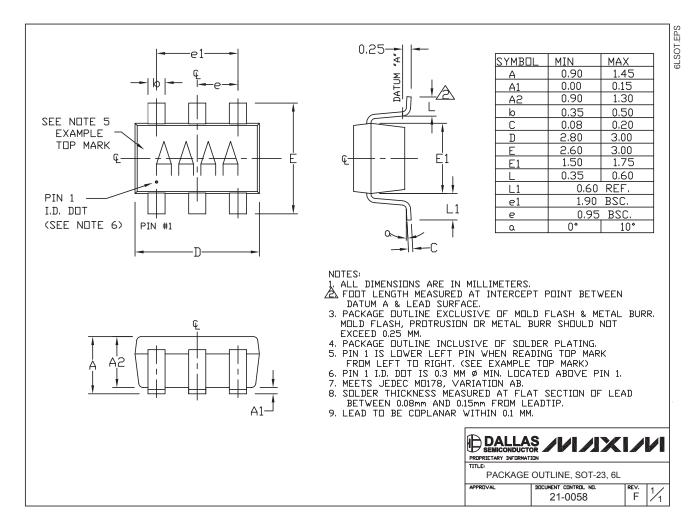
Figure 7. Typical Operating Circuit

Chip Information

TRANSISTOR COUNT: 755 PROCESS: BICMOS

Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to www.maxim-ic.com/packages.)



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