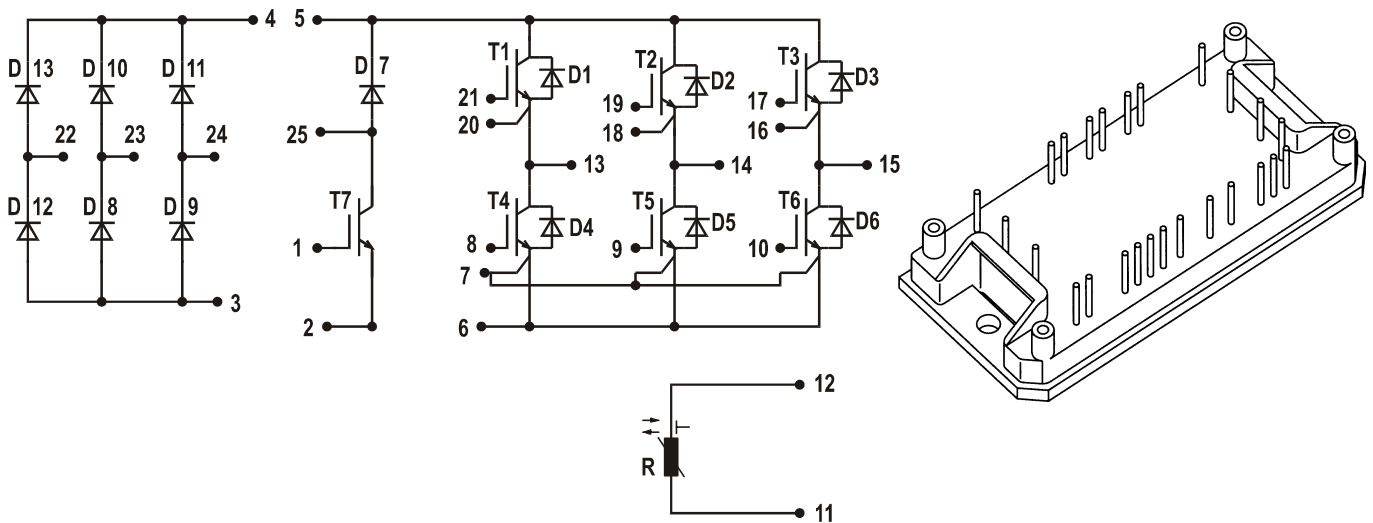


Converter - Brake - Inverter Module (CBI1)



| Rectifier | Brake | Inverter |
|-------------------|---------------------|-----------------------|
| $V_{RRM} = 1200V$ | $V_{CES} = 600 V$ | $V_{CES} = 600 V$ |
| $I_{FAVM} = 11 A$ | $I_{C25} = 11 A$ | $I_{C25} = 18 A$ |
| $I_{FSM} = 250 A$ | $V_{CE(sat)} = 2 V$ | $V_{CE(sat)} = 2.1 V$ |

Input Rectifier Bridge D8 - D13

| Symbol | Conditions | Maximum Ratings | |
|------------|---|-----------------|------------------|
| V_{RRM} | | 1200 | V |
| I_F | $T_{VJ} = 25^{\circ}C$ | 36 | A |
| I_{FAVM} | $T_{VJ} = 150^{\circ}C; T_K = 70^{\circ}C$ | 11 | A |
| I_{FSM} | $T_{VJ} = 45^{\circ}C; t = 10 \text{ ms sine } 50 \text{ Hz}$ | 250 | A |
| i^2t | $T_{VJ} = 125^{\circ}C$ | 310 | A ² s |
| T_{VJ} | | +150 | $^{\circ}C$ |

| Symbol | Conditions | Characteristic Values ($T_{VJ} = 25^{\circ}C$, unless otherwise specified) | | |
|------------|---|---|------|--------------------|
| | | min. | typ. | max. |
| I_R | $V_{RRM} = 1200 V; T_{VJ} = 25^{\circ}C$ $T_{VJ} = 125^{\circ}C$ | | | 10 μA 3 mA |
| V_F | $I_F = 36 A$ | | 1.15 | 1.4 V |
| R_{thJC} | per die | | 1.4 | $^{\circ}C/W$ |

Features

- NPT IGBT technology
- Square RBSOA, no latchup
- Free wheeling diodes with Hiperfast and soft recovery behaviour
- Isolation voltage 2500 V~
- Built in temperature sense
- High level of integration: one module for complete drive system
- **Direct Copper Bonded** Al₂O₃ ceramic base plate

Applications

- AC motor control
- AC servo and robot drives

Advantages

- No need of external isolation
- Easy to mount with two screws
- Package designed for wave soldering
- High temperature and power cycling capability

IXYS reserves the right to change limits, test conditions and dimensions.

Output Inverter T1 - T6, D1 - D6

| Symbol | Conditions | Maximum Ratings | |
|-----------|---|----------------------------|--------------------|
| V_{CES} | $T_{VJ} = 25^{\circ}\text{C}$ | 600 | V |
| V_{CGR} | $T_{VJ} = 25^{\circ}\text{C}; R_{GE} = 20\text{k}\Omega$ | 600 | V |
| V_{GE} | $T_{VJ} = 25^{\circ}\text{C}$ | ± 20 | V |
| I_C | $T_C = 25^{\circ}\text{C}$ | 18 | A |
| | $T_C = 90^{\circ}\text{C}$ | 10 | A |
| I_{CM} | $t_p = 1 \text{ ms} = 1\% \text{ duty cycle}; T_C = 25^{\circ}\text{C}$ | 36 | A |
| | | $T_C = 90^{\circ}\text{C}$ | 20 |
| t_{SC} | IGBT $V_{CE} = 600 \text{ V}; T_{VJ} = 125^{\circ}\text{C}$ non-repetitive | 10 | μs |
| P_{tot} | $T_C = 25^{\circ}\text{C}$ | 61 | W |
| T_{VJ} | Free-Wheeling Diode | +150 | $^{\circ}\text{C}$ |
| T_{VJ} | IGBT | +150 | $^{\circ}\text{C}$ |

| Symbol | Conditions | Characteristic Values ($T_{VJ} = 25^{\circ}\text{C}$, unless otherwise specified) | | | |
|---------------|---|--|------------|-----------------------------|----|
| | | min. | typ. | max. | |
| I_{CES} | $V_{GE} = 0 \text{ V}; V_{CE} = 600 \text{ V}$ | | | 1 mA | |
| I_{GES} | $V_{CE} = 0 \text{ V}; V_{GE} = 25 \text{ V}$ | | | 100 nA | |
| $V_{GE(th)}$ | $V_{GE} = V_{CE}; I_C = 0.35 \text{ mA}$ | 4.5 | 5.5 | 6.5 V | |
| $V_{(BR)CES}$ | $V_{GE} = 0 \text{ V}; I_C = 10 \text{ mA}; T_{VJ} = -40^{\circ}\text{C}$ | 600 | | V | |
| $V_{CE(sat)}$ | $V_{GE} = 15 \text{ V}; I_C = 10 \text{ A}; T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | 2.1 | 2.5 V | |
| | | | 2.4 | 2.8 V | |
| t_f | Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CC} = 300 \text{ V}; I_C = 10 \text{ A}$ $R_G = 100 \Omega; V_{GE} = \pm 15 \text{ V}$ | | 25 | ns | |
| | | t_r | 25 | ns | |
| $t_{d(on)}$ | | 35 | ns | | |
| $t_{d(off)}$ | | 250 | ns | | |
| E_{off} | | 0.38 | mJ | | |
| E_{on} | | 0.58 | mJ | | |
| C_{iss} | | $V_{GE} = 0 \text{ V}$ $V_{CE} = 25 \text{ V}$ $f = 1 \text{ MHz}$ | | 570 | pF |
| | | | C_{oss} | 80 | pF |
| | | | C_{riss} | 55 | pF |
| g_{fs} | | $V_{CE} = 20 \text{ V}; I_C = 10 \text{ A}$ | 3 | | S |
| Q_g | $V_{CC} = 300 \text{ V}; I_C = 10 \text{ A pulse}; V_{GE} = 15 \text{ V}$ | | 39 | nC | |
| V_F | $I_F = 10 \text{ A}; V_{GE} = 0 \text{ V}; T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | 2 | V | |
| | | | 1.8 | V | |
| t_{rr} | $I_F = 10 \text{ A}; V_R = -300 \text{ V}; V_{GE} = 0 \text{ V}$ $di_F/dt = -350 \text{ A}/\mu\text{s}; T_{VJ} = 100^{\circ}\text{C}$ | | 0.2 | μs | |
| Q_r | $I_F = 10 \text{ A}; V_R = -300 \text{ V}; T_{VJ} = 25^{\circ}\text{C}$ $di_F/dt = -350 \text{ A}/\mu\text{s}; V_{GE} = 0 \text{ V}; T_{VJ} = 125^{\circ}\text{C}$ | | 0.3 | μC | |
| | | | 0.9 | μC | |
| I_r | | | | 250 μA | |
| R_{thJC} | IGBT (per die) | | 1.7 | $^{\circ}\text{C}/\text{W}$ | |
| | Diode (per die) | | 2.3 | $^{\circ}\text{C}/\text{W}$ | |

Brake Chopper T7, D7

| Symbol | Conditions | Maximum Ratings | |
|-----------|--|----------------------------|--------------------|
| V_{CES} | $T_{VJ} = 25^{\circ}\text{C}$ | 600 | V |
| V_{CGR} | $T_{VJ} = 25^{\circ}\text{C}; R_{GE} = 20\text{k}\Omega$ | 600 | V |
| V_{GE} | $T_{VJ} = 25^{\circ}\text{C}$ | ± 20 | V |
| I_C | $T_C = 25^{\circ}\text{C}$ | 11 | A |
| | $T_C = 90^{\circ}\text{C}$ | 8 | A |
| I_{CM} | $t_p = 1\text{ ms} = 1\% \text{ duty cycle}; T_C = 25^{\circ}\text{C}$ | 22 | A |
| | | $T_C = 90^{\circ}\text{C}$ | 16 |
| t_{SC} | IGBT $V_{CE} = 600\text{ V}; T_{VJ} = 125^{\circ}\text{C}$ non-repetitive | 10 | μs |
| P_{tot} | $T_C = 25^{\circ}\text{C}$ | 45 | W |
| T_{VJ} | Free-Wheeling Diode | +150 | $^{\circ}\text{C}$ |
| T_{VJ} | IGBT | +150 | $^{\circ}\text{C}$ |

| Symbol | Conditions | Characteristic Values ($T_{VJ} = 25^{\circ}\text{C}$, unless otherwise specified) | | | |
|---------------|---|--|------------|-----------------------------|--------|
| | | min. | typ. | max. | |
| I_{CES} | $V_{GE} = 0\text{ V}; V_{CE} = 600\text{ V}$ | | | 20 μA | |
| I_{GES} | $V_{CE} = 0\text{ V}; V_{GE} = 25\text{ V}$ | | | 100 nA | |
| $V_{GE(th)}$ | $V_{GE} = V_{CE}; I_C = 0.5\text{ mA}$ | 3 | 4 | 5 V | |
| $V_{(BR)CES}$ | $V_{GE} = 0\text{ V}; I_C = 0.5\text{ mA}; T_{VJ} = -40^{\circ}\text{C}$ | 600 | | V | |
| $V_{CE(sat)}$ | $V_{GE} = 15\text{ V}; I_C = 6\text{ A}; T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 150^{\circ}\text{C}$ | | 2 | 2.5 V | |
| | | | 2.3 | 2.8 V | |
| t_f | Inductive load, $T_{VJ} = 150^{\circ}\text{C}$ $V_{CC} = 400\text{ V}; I_C = 6\text{ A}$ $R_G = 50\ \Omega; V_{GE} = \pm 15\text{ V}$ | | 75 | 110 ns | |
| | | t_r | 30 | 45 ns | |
| $t_{d(on)}$ | | 50 | 80 ns | | |
| $t_{d(off)}$ | | 250 | 375 ns | | |
| E_{off} | | 0.21 | mJ | | |
| E_{on} | | 0.25 | mJ | | |
| C_{iss} | | $V_{GE} = 0\text{ V}$ $V_{CE} = 25\text{ V}$ $f = 1\text{ MHz}$ | | 350 | 435 pF |
| | | | C_{oss} | 40 | 50 pF |
| | | | C_{riss} | 25 | 30 pF |
| g_{fs} | | $V_{CE} = 20\text{ V}; I_C = 6\text{ A}$ | 4.2 | | S |
| Q_g | $V_{CC} = 400\text{ V}; I_C = 6\text{ A pulse}; V_{GE} = 15\text{ V}$ | | 32.5 | nC | |
| V_F | $I_F = 10\text{ A}; V_{GE} = 0\text{ V}; T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 150^{\circ}\text{C}$ | | 2 | V | |
| | | | 1.8 | V | |
| t_{rr} | $I_F = 10\text{ A}; V_R = -300\text{ V}; V_{GE} = 0\text{ V}$ $di_F/dt = -350\text{ A}/\mu\text{s}; T_{VJ} = 150^{\circ}\text{C}$ | | 0.2 | μs | |
| Q_r | $I_F = 10\text{ A}; V_R = -300\text{ V}; T_{VJ} = 25^{\circ}\text{C}$ $di_F/dt = -350\text{ A}/\mu\text{s}; V_{GE} = 0\text{ V}; T_{VJ} = 125^{\circ}\text{C}$ | | 0.3 | μC | |
| | | | 0.9 | μC | |
| I_r | | | | 250 μA | |
| R_{thJC} | IGBT (per die) | | 2.3 | $^{\circ}\text{C}/\text{W}$ | |
| | Diode (per die) | | 2.3 | $^{\circ}\text{C}/\text{W}$ | |

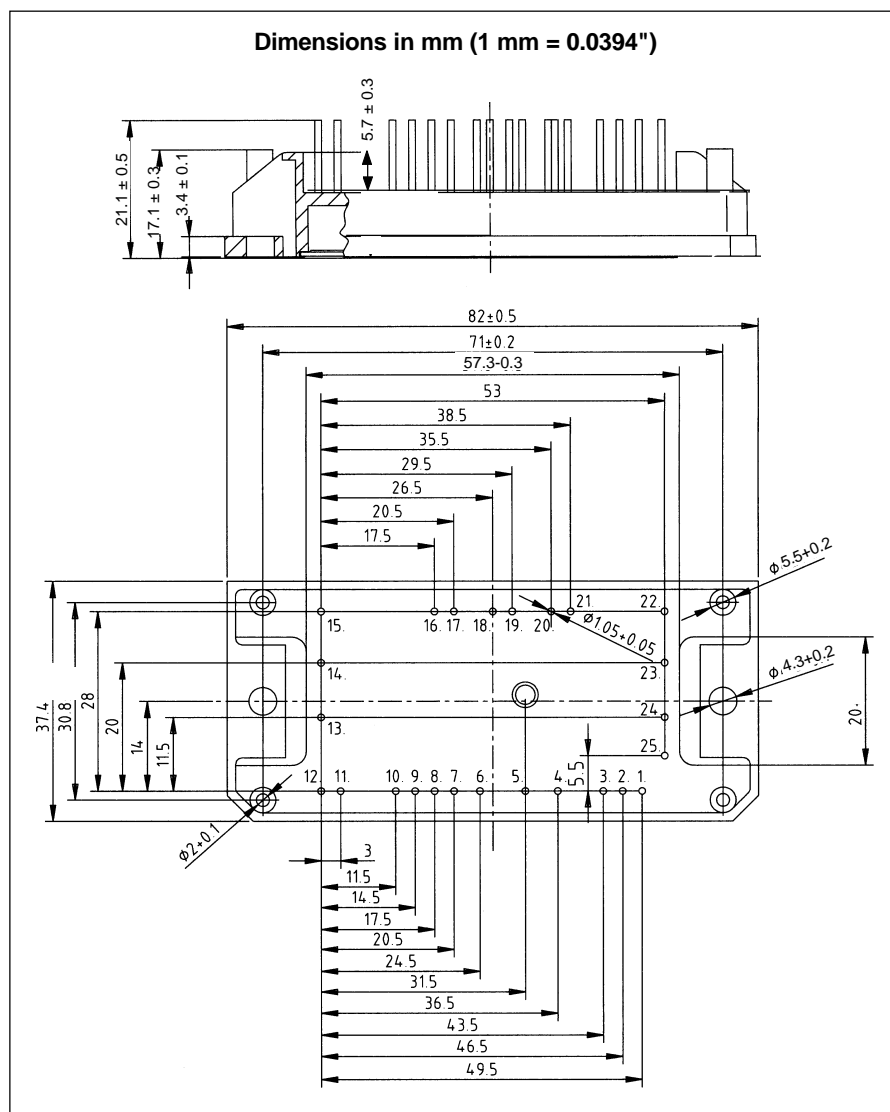
Module

| Symbol | Conditions | Maximum Ratings | |
|------------|--|----------------------|--------------|
| T_{stg} | | -40...+125 | °C |
| V_{ISOL} | $I_{ISOL} \leq 1 \text{ mA}$; 50/60 Hz; $t = 1 \text{ min}$ | 2500 | V~ |
| M_d | Mounting torque (M4) | 2.0 - 2.2 18 - 20 | Nm lb.in. |
| d_s | Creepage distance on surface | 12.7 | mm |
| d_A | Strike distance in air | 12.7 | mm |
| Weight | typ. | 42 | g |

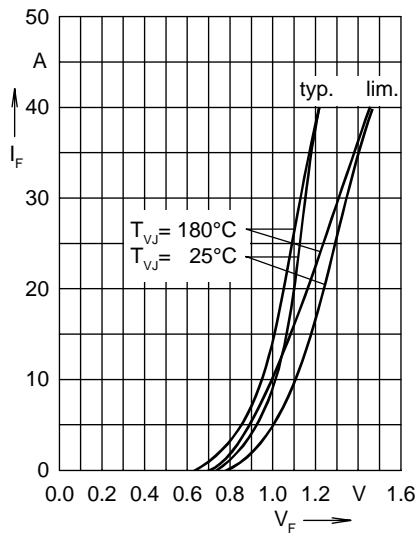
Temperature Sensor R

| Symbol | Conditions | Maximum Ratings | |
|--------|------------------------------|-----------------|------------|
| R | $T_{amb} = 20^\circ\text{C}$ | 4.7 | k Ω |

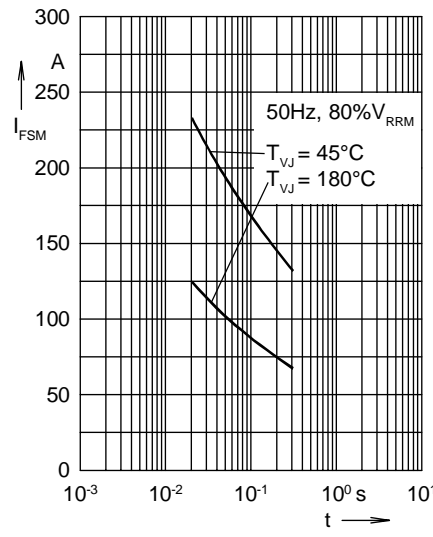
For additional data see C620/4.7k 5% S+M NTC thermistor catalog



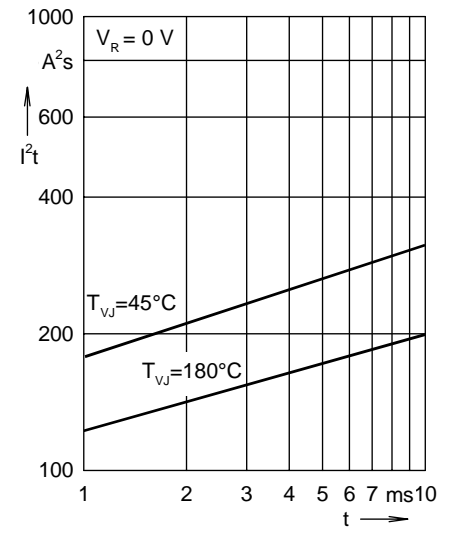
Input Rectifier Bridge D8 - D13



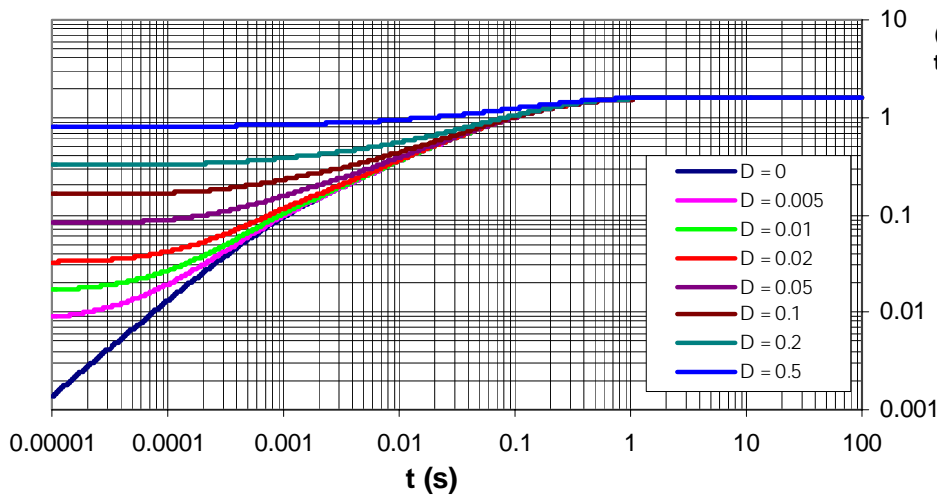
Forward characteristics



Surge overload current
 I_{FSM} : crest value, t : duration



I^2t versus time (1-10 ms)



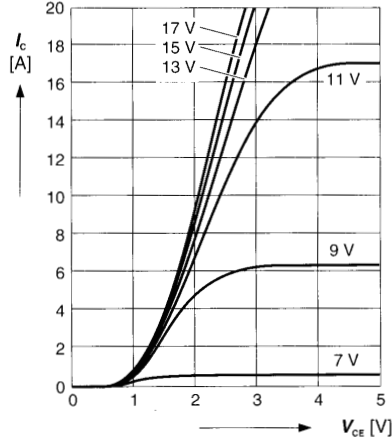
Transient thermal resistance junction to heatsink

Output Inverter T1 - T6

Typ. output characteristics

$$I_C = f(V_{CE})$$

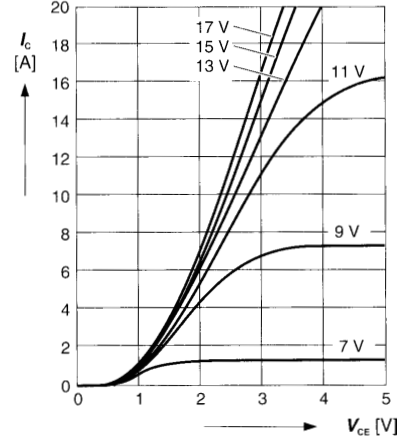
parameter: $t_p = 250 \mu s$; $T_j = 25^\circ C$



Typ. output characteristics

$$I_C = f(V_{CE})$$

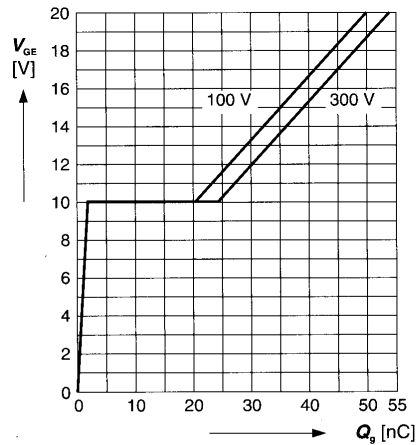
parameter: $t_p = 250 \mu s$; $T_j = 125^\circ C$



Typ. gate charge

$$V_{GE} = f(Q_g)$$

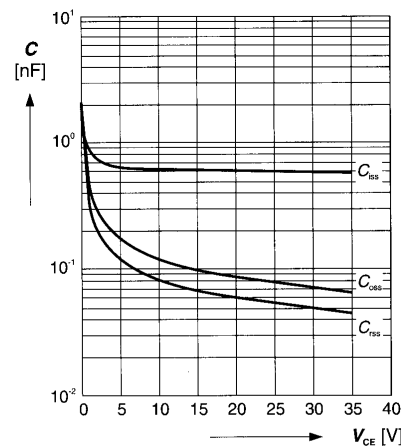
parameter: $I_{C\ pulse} = 10 A$



Typ. capacitances

$$C = f(V_{CE})$$

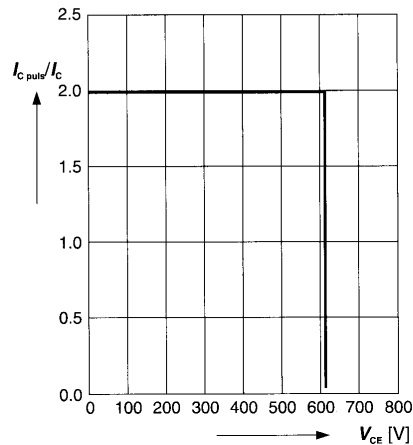
parameter: $V_{GE} = 0 V$; $f = 1 MHz$



Reverse biased safe operating area

$$I_{C\ pulse} = f(V_{CE}), T_j = 150^\circ C$$

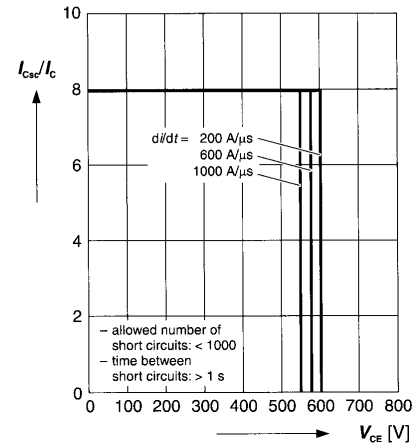
parameter: $V_{GE} = 15 V$



Short circuit safe operating area

$$I_{C\ sc} = f(V_{CE}), T_j = 150^\circ C$$

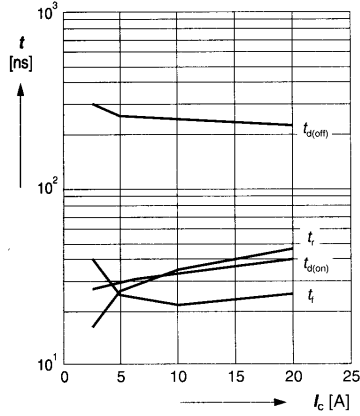
parameter: $V_{GE} = \pm 15 V$; $t_{sc} \le 10 \mu s$; $L < 60 nH$



Output Inverter T1 - T6

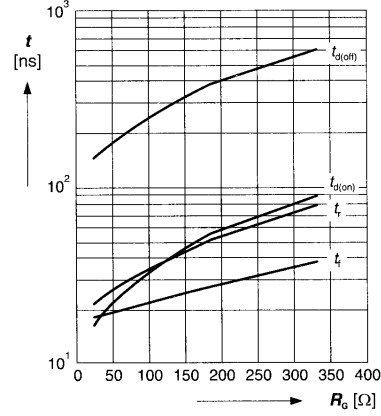
Typ. switching time

$t = f(I_C)$, inductive load, $T_j = 125^\circ\text{C}$
 parameter: $V_{CE} = 300\text{ V}$; $V_{GE} = \pm 15\text{ V}$; $R_G = 100\ \Omega$



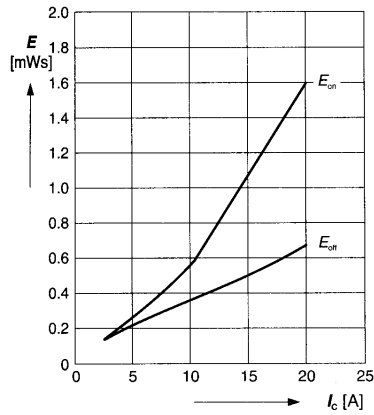
Typ. switching time

$t = f(R_G)$, inductive load, $T_j = 125^\circ\text{C}$
 parameter: $V_{CE} = 300\text{ V}$; $V_{GE} = \pm 15\text{ V}$; $I_C = 10\text{ A}$



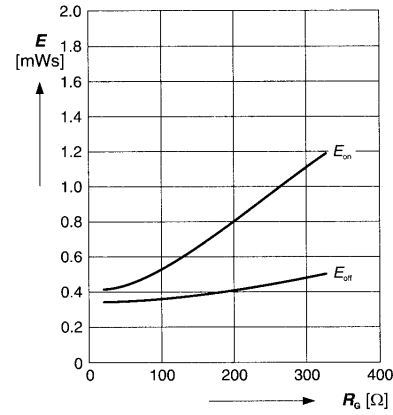
Typ. switching losses

$E = f(I_C)$, inductive load, $T_j = 125^\circ\text{C}$
 parameter: $V_{CE} = 300\text{ V}$; $V_{GE} = \pm 15\text{ V}$; $R_G = 100\ \Omega$

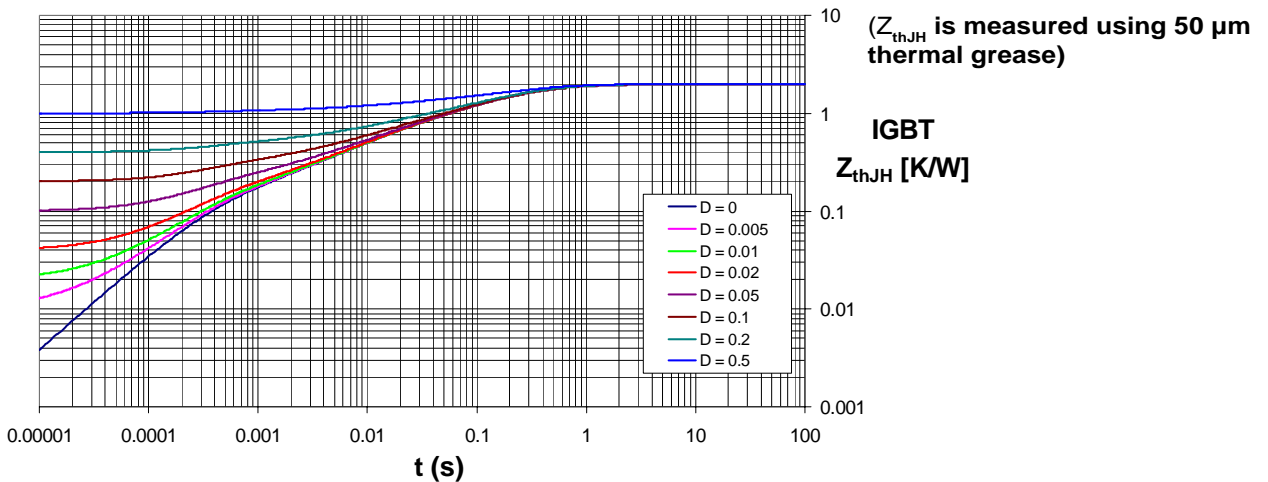


Typ. switching losses

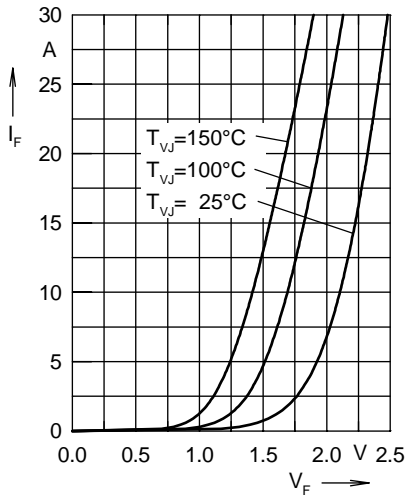
$E = f(R_G)$, inductive load, $T_j = 125^\circ\text{C}$
 parameter: $V_{CE} = 300\text{ V}$; $V_{GE} = \pm 15\text{ V}$; $I_C = 10\text{ A}$



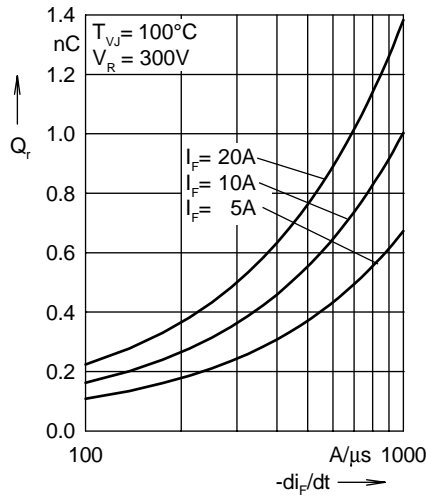
Transient thermal resistance junction to heatsink



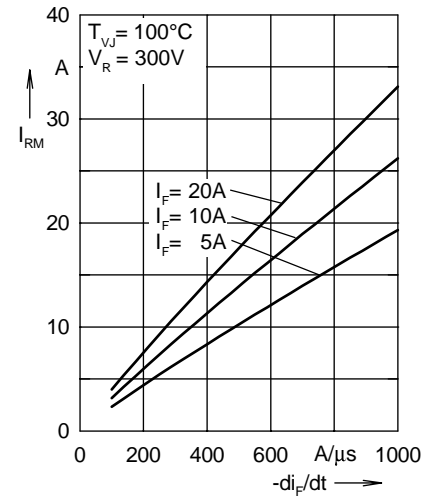
Output Inverter D1 - D6



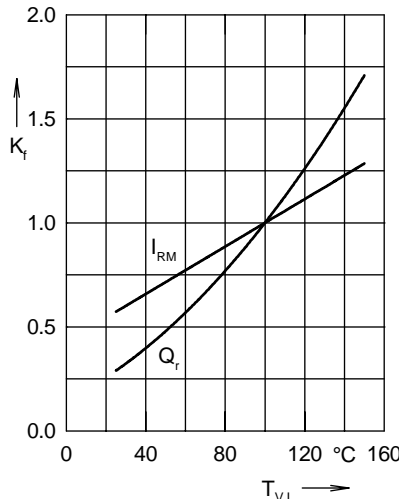
Forward current I_F versus V_F



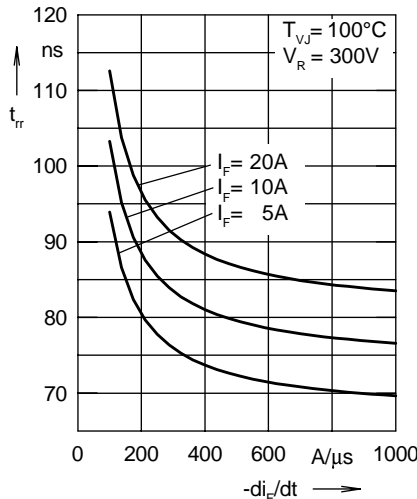
Reverse recovery charge Q_r versus $-di_F/dt$



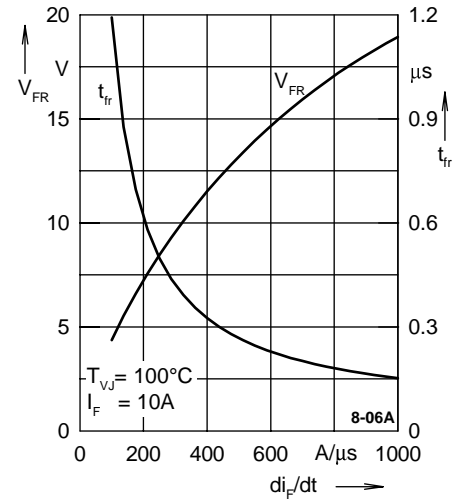
Peak reverse current I_{RM} versus $-di_F/dt$



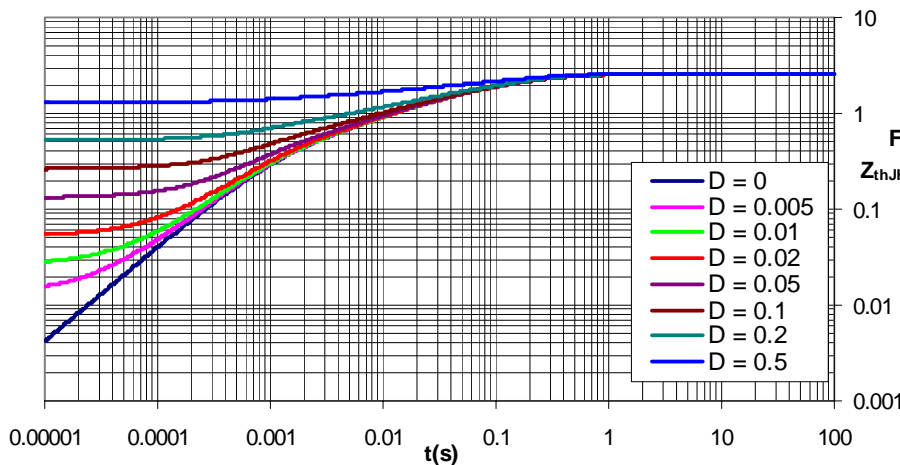
Dynamic parameters Q_r , I_{RM} versus T_{VJ}



Recovery time t_{rr} versus $-di_F/dt$



Peak forward voltage V_{FR} and t_{rr} versus di_F/dt



Transient thermal resistance junction to heatsink

(Z_{thJH} is measured using 50 μm thermal grease)

Fred
 $Z_{thJH}[\text{K/W}]$