





The CS3210 and CS3212 Reed-Solomon decoders are designed to provide high performance solutions for a broad range of applications requiring forward error correction. These application specific virtual components (ASVCs) are developed for high data rate digital video and audio, satellite broadcast or data storage and retrieval applications, and are fully compliant with the European DVB (CS3210) and IntelSat (CS3212). The ASVCs are configurable Reed-Solomon decoders featuring user-selectable codeword length (50-255 symbols) and number of parity symbols (0-20 symbols), providing up to 880Mbits per second data throughput. The CS3210 and CS3212 are available in both ASIC and programmable logic versions that have been handcrafted by Amphion for optimal performance while minimizing power consumption and silicon area.



Figure 1: CS3210/12

DECODER FEATURES

- Configurable Codeword Length (N) and Number of Parity Symbols (T)
 - N = 50 255 symbols
 - T = 0 20 symbols
 - Single implementation supports any valid block length and parity length
- High Performance Solution for High Data Rate Reed-Solomon Decoding
 - Can process burst and continuous data
 - Low latency
- Supports a Range of Standards Including Intelsat, European DVB Telecommunication Standards ETS 300-421 and ETS 300-429
- Byte-Wide Input and Output, Clocked by a Single Symbol Rate Clock
- Ease of Integration
 - Tapeout-Ready™ firm-IP targeted netlist

Simple core interface for easy integration into larger systems

KEY METRICS AND SPECIFICATIONS

- Size: 104k Gates
- Maximum Frequency: 110 MHz¹
- 8 Bits per Symbol Yields 880 Mbits/second1 Throughput
- CS3210 (DVB Compliant)
 - Generator Polynomial: g(x)=(x+1)(x+a)(x+a²). . .(x+a^(2t-1)) [²]
 - Field Polynomial: f(x)=x⁸+x⁴+x³+x²+1
- CS3212 (Intelsat Compliant)
 - Generator Polynomial: g(x)=(x+a¹²⁰)(x+a¹²¹). . .(x+a^{120+(2t-1)})
 - Field Polynomial: $f(x)=x^8+x^7+x^2+x+1$

APPLICATIONS

- Digital video and Audio Broadcast
- Digital Satellite Broadcast
- Data Storage and Retrieval Systems (e.g. Hard Disk Drives, CD-ROM, DVD, etc.)

Performance is dependent on the silicon process and libraries selected. 110MHz/880Mbps operation is representative of 0.18-micron silicon using standard cell libraries.
 "t" represents the number of correctable symbol errors (excluding erasures) and equals one-half the number of parity symbols "T".

BLOCK CODES FOR ERROR CORRECTION

In digital communications systems, channel coding is used to introduce controlled redundancy into a data sequence on the transmission (encode) side of a communications channel. The receiver (decoder) uses this redundant information to overcome the effects of data corrupting channel distortions and noise. Block codes are a type of channel coding scheme characterized by the independent coding of successive discrete blocks or groups of information bits with no dependencies between successive blocks of data. Binary codes operate on sequences of bits, whereas non-binary codes decode data as multi-bit symbols – 8 bits per symbol for most applications. Reed-Solomon codes are a particularly powerful type of non-binary, linear block code.

The CS3210 and CS3212 are designed to provide high performance forward error correction (FEC) compliant with digital video broadcast (DVB) standards and other applications using the Reed-Solomon technique. The core is capable of processing both burst and continuous data streams and input and out-put will be symbol wide, clocked by a single symbol rate clock. The implementation is low latency and the simple core interface allows easy integration into larger systems.

The decoder accepts an input block consisting of data with appended parity symbols and outputs the corrected (if necessary) code block. As shown in Figure 1, the length of the input data stream "N" ranges between 50 and 255 symbols and is a function of the original code block "K" and parity symbols "T". K ranges between 50 to 255 symbols. Between T/2 and T errors can be detected and corrected by the decoder, depending on the specific mix of erasure and random errors.

CS3210/CS3212 OPERATION

Within the Reed-Solomon decoder structure, there are 7 primary blocks as shown in Figure 2. Operation of key individual blocks is described below. User programmable registers are provided which allow the codeword length and number of parity symbols to be defined. These are programmed via a standard microprocessor type interface.

DECODER

The decoding calculation is subdivided into 5 components performing the decoding calculation along with a FIFO used to store codewords input to the core. The operation of the FIFO is to present uncorrected codewords for the application of correction symbols calculated in the main body of the decoder. A description of the individual functional blocks follows.

SYNDROME CALCULATION

The Syndrome Calculation Block contains control circuitry to ensure that complete and valid codewords are applied to the decoder. For a code with NCB ("number of check bytes") parity symbols, a set of NCB syndromes are produced. The values of these syndromes are subsequently forwarded to error location and evaluation circuitry to resolve the positions and magnitudes of codeword errors.

ERASURE CALCULATION

Operating in parallel with the Syndrome calculator is the Erasure Calculator. Forward error correction systems often include concatenated schemes to provide higher coding gains than are achievable with a Reed-Solomon correction system in isolation. These concatenated systems provide the Reed-Solomon decoder with information regarding symbols that are suspected of being received erroneously. Known as erasures, such symbols are flagged as potentially incorrect; the ability of the decoder to repair erased symbols extends its correction ability. Normally the number of corrected symbols is limited to half the number of parity symbols, while using the Erasure Calculator means that up to twice as many erasure errors may be corrected. For combinations of erasure errors (s) and random errors (v), the total number of errors correctable by a (n,k) code is given by

$$s + 2v \le N - K$$

The decoder stores and forwards locations of erased symbols to the key equation calculation module concurrently with the syndromes from the Syndrome Calculation Block.



Figure 2: CS3210/CS3212 Block Diagram



KEY EQUATION BLOCK

Solving the key equation is a complex iterative process, and this module constitutes the main arithmetic engine of the CS3210/CS3212. Inputs from the Syndrome and Erasure Blocks are used to check if the received codeword contains errors. This is performed by the calculation of polynomials that describe the positions and values of any errors discovered in the codeword. The key equation calculation occurs after the Syndrome Calculation Block signals that a complete Reed-Solomon codeword has been received and the syndrome and erasure values are available. The greater the value of (N-K), the more iterations are necessary to complete the calculations. It should be noted that this is independent of the number of actual errors in the received codeword.

It is the processing delay incurred in the solution of the Key Equation that limits the minimum value of N for a required number of parity symbols when continuous messages are received by the CS3210. Smaller values of N may be used, but messages should then be burst to the core, with appropriate gaps between the end of one and the start of the next, in order that the Key Equation calculation may be solved between subsequent sets of syndromes.

POLYNOMIAL EVALUATION

After the key equation is solved, the Polynomial Evaluation block finds the roots of the above-mentioned polynomials. This requires successive Galois Field multiplications and addition of the resulting components, producing a set of data that is related to the correction vectors which are then applied to the received codeword. The presence of a⁻¹ values in the location datastream implies a symbol in need of correction. The evaluation values are used to calculate the value required to correct the located error.

FORNEY COMPUTATION

The Forney algorithm is used to perform the final evaluation calculation and the application of the correction vectors to the received codewords. Often systems using Reed-Solomon decoding need to know when an uncorrectable block has been received. Normally it is not possible for the decoder to determine if it can correct all errors until the complete block has been processed. In order therefore to flag this condition (that a block cannot be corrected) simultaneously with the output of a codeword, it is necessary to perform the correctability check and buffer the codeword for a codeword length before applying the correction vectors. Uncorrectable blocks are flagged as soon as their first symbol is output and erroneous correction vectors are not applied to uncorrectable blocks.

PIN/PORT DESCRIPTION

Table 1 gives the descriptions of the input and output ports ofthe CS3210 and CS3212 Reed-Solomon decoders. Unless

otherwise stated, all signals are active high and bit (0) is the least significant bit.

 Table 1: Input and Output Descriptions

Signal	I/O	Width (Bits)	Description
CLK	I	1	Symbol rate clock, rising edge active
Reset	I	1	Asynchronous Master Reset, active high
Data Stream Inp	ut Port		
Data_In[7:0]	I	8	Input data symbol, 8 bits wide
FStart_In	I	1	When high, indicates the data on Data_In is the first symbol in a new information sequence
Data_Valid_In	I	1	When high signifies that the signals at the Data_In, Erased and F_Start_In ports contain valid information
Erased	I	1	When high, signifies that the data on Data_In has been flagged as an erasure
Data Stream Out	put Po	rt	
Data_Out[7:0]	0	8	Output data symbol, 8 bits wide
FStart_Out	0	1	When high, indicates the data on Data_Out is the first symbol in a new coded block
Data_Valid_Out	0	1	When high, signifies that the signals at the Data_Out and FStart_Out ports contain valid information
Control and Con	figurat	ion	
UP-Din[7:0]	I	8	Data Bus input from microprocessor
Add[1:0]	1	2	Address Bus from microprocessor
RD[1:0]	I	1	Read Enable for Data Bus
WR	I	1	Write Enable for Data Bus
UP_Dout[7:0]	0	8	Data Bus output to microprocessor

PROCESSOR INTERFACE

Before the decoder can commence operation, the codeword length and the parity length must be loaded into their appropriate registers via the microprocessor interface. The addresses of the respective registers are given in Table 2. When changing codeword formats the user must ensure that the there is no partially processed data within the CS3210, which occurs after the latency has expired. Changing the codeword format while the core is still processing will cause unpredictable behavior until such time as the codeword format is changed in the correct manner.

Values are loaded into their respective registers by applying the correct address signal to *Add*, the parameter values to *UP_Din* and then asserting the write enable signal. The inputs *Add* and *UP_Din* are sampled on the write signal, WR, rising edge. Polling the addresses 00 and 01 (CWL_REG and NCB_REG) will output the current codeword length and number of check bytes used in the decoder on the rising edge of *RD*. Addressing 10 and strobing RD will output the number of errors corrected in the codeword presently output at *SYMBOL_OUT*. In cases where the current codeword is uncorrectable a value of "1111111" will be output on *UP_DOUT* on reading address 10.

CODEWORD FORMATS

The number of symbols within a codeword (N) may be varied between 50 and 255. The number of these symbols that are parity (N-K) may be varied between 0 and 20.

It should be noted that not all combinations of codewords are valid. Due to the processing delay of the decoder it is not possible to decode continuous messages for small values of N with large values of (N-K). Table 3 outlines the minimum codeword length allowable for a given number of check symbols for the processing of continuous messages.

Shorter codeword formats may be used for larger values of N-K; however, it will be necessary to insert gaps between the codewords entering the decoder to ensure that the core operates correctly. This gap must be long enough to allow for the equivalent number of clock cycles required to extend the codeword length to the minimum allowed for the required value of N-K. For example: an application requires a codeword format of N=100 and N-K=16. From Table 3 it can be observed that the minimum value of N required for this number of parity symbols is 155. For this application, messages in the required format can be processed as long as a gap of 55 clock cycles is inserted between the last symbol in a given codeword and the first symbol of the next codeword, satisfying the minimum processing time of 155 cycles.

Also note that the absolute minimum codeword length is 50 under any conditions.

ADDRESS REGISTER CONTENTS CONTENT WIDTH CWL_REG 00 Codeword Length 8 bits 01 NCB REG Number of Check Bytes 8 bits 10 STAT REG Statistics Output 8 bits 11 Not used N/A

Table 2: Register Address Contents for Microprocessor Interface



NUMBER OF CHECK BYTES	MINIMUM CODEWORD LENGTH	NUMBER OF CHECK BYTES	MINIMUM CODEWORD LENGTH
20	207	19	194
18	180	17	167
16	155	15	142
14	131	13	120
12	110	11	99
10	90	9	81
8	72	7	65
6	57	5	50
4	50	3	50
2	50	1	50

Table 3: Minimum Allowable Codeword Lengths

SETTING THE CODEWORD FORMAT

With Data_Valid_In low (hence values on *FStart_In*, *Data_In* and *Erased* are ignored), the number of check bytes register (NCB_REG) should be addressed by placing the 2 bit binary value "01" on the *Add* input port. Simultaneously, the required number of check bytes used in the received code-words should be placed in binary format on the *UP_Din* port. With the values on *Add* and *UP_Din* held constant, the *WR* input should be strobed high and low for the duration of one clock cycle.

Once the number of check bytes has been set, the codeword length may be input. Again with *Data_Valid_In* remaining low, the codeword length register can be addressed (CWL_REG) by placing the 2 bit binary value "00" on the microprocessor interface port *Add*. Simultaneously, the required number of symbols in each codeword of the received messages (information symbols and parity symbols) should be set on the *UP_Din* port. With the values on *Add* and *UP_Din* held constant, the *WR* input should be strobed high and low for 1 system clock duration. Loading of Reed-Solomon messages may commence with the following rising clock edge.

RESET AND CLOCKING STRATEGY

All synchronous elements in the decoders are clocked using the rising edge of the *CLK* signal. The exceptions to this are the registers holding the generator polynomial coefficients, codeword length and parity length. These are written and read using strobe signals present in the processor interface. Additionally, all I/O signals are registered on the rising edge of *CLK*, with the exception of Reset. When the reset signal Reset is asserted, all registers will be set to zero value. The codeword length register will be loaded with the value FF_{HEX} (255₁₀) and the parity length register will be loaded with the value 10_{HEX} (16₁₀). The code generator polynomial registers are loaded with the corresponding coefficients for the given parity length. The default code rate is therefore (255, 239).

INPUT DATA INTERFACE

The *Data_Valid_In* signal should be asserted whenever valid data is present on *Data_In* and *FStart_In*. *Data_Valid_In* acts as a clock enable and if de-asserted, the decoder will not sample the signals at *FStart_In* and *Data_In*. Therefore, there is no requirement for the information sequence to be input in a continuous stream. If *Data_Valid_In* is de-asserted after a complete information sequence has been input, the decoder will continue to process and clock out the corrected message, despite the fact that the input data flow has stalled.

FStart_In should be asserted for one clock cycle at the same time as the first information symbol in a new sequence is applied to *Data_In*, allowing the appropriate parameters to be read. After N information symbols have been applied to the decoder, the completely received codeword will then be processed and output after the core latency has expired. If *FStart_In* is asserted less than N valid clock cycles since it was last asserted then a new codeword will be begun partway through the input of the previous codeword block. In this case

the incompleted codeword will be dropped and will not the core and will be output after the core latency's duration has completed.

If the values held in the codeword length and parity length registers are updated, the updated register values are not applied until the next assertion of *FStart_In*. Before changing the values in these registers the input of data to the decoder should be stalled and any partially processed data within the allowed to be completely output. In these conditions the register values may be changed and once stable, processing of a new codeblock in the new data format can begin on the next rising edge of *CLK*.

OUTPUT DATA INTERFACE

FStart_Out is asserted high for one clock cycle at the same time as the first codeword symbol appears on *Data_Out*. When valid information symbols are present on *Data_Out*, the output *Data_Valid_Out* signal is asserted high.



Figure 3: Functional Timing Characteristics of the CS3210 and CS3212



DEFINITION OF RS CODE IMPLEMENTED IN THE CS3210/CS3212

The CS3210 and CS3212 encoders support a wide range of applications and are fully compliant with the European DVB Standards ETS 300-421 and ETS 300-429 (CS3210) or Intelsat IESS 308/309 (CS3212). The Reed-Solomon Generator polynomial for the European DVB standards is

 $g(x)=(x+1)(x+a)(x+a^2)...(x+a^{(2t-1)})$, where a is 02 _{HEX}

and the Reed-Solomon primitive polynomial is

 $f(x)=x^8+x^4+x^3+x^2+1$.

Equivalently, for Intelsat the Reed-Solomon Generator polynomial is

 $g(x)=(x+a^{120})(x+a^{121})...(x+a^{120+(2t-1)})$

with a Reed-Solomon primitive polynomial of

 $f(x)=x^8+x^7+x^2+x+1$

The core is designed for high performance applications and is configurable for any valid block length (n = 50-255) and parity length ((n - k) = 0-20). For ETS 300-421 and ETS 300-429, the coding parameters are

(204,188,8)

where the rate is in the format (N, K, t)- n is the codeword

AVAILABILITY AND IMPLEMENTATION INFORMATION

ASIC CORES

For applications that require the high performance, low cost and high integration of an ASIC, Amphion delivers application specific cores that are pre-optimized by Amphion experts to a targeted silicon technology. Choose from off-the-shelf versions of the CS3210 or CS3212 available for many popular ASIC and foundry silicon supplier technologies or Amphion can port the decoders to a technology of your choice.

PRODUCT ID#	SILICON VENDOR	PRODUCT NAME/PROCESS	PERFORMANCE*	LOGIC GATES**	AVAILABILITY
CS3210		Programmable Reed-Solomon Decoder			
CS3210TK	TSMC	180 nm using Artisan standard cell libraries	169 MHz	82K	Now
CS3212	TSMC	180 nm using Artisan standard cell libraries	166 MHz	82K	Now

Table 4: ASIC Cores

* Performance figures based on silicon vendor design kit information. ASIC performance is pre-layout using vendor-provided statistical wire loading information, under the following conditions: (T J = 125°C, V CC - 10%).

** Logic gates do not include clock circuitry. Consult your local Amphion representative for product specific performance information, current availability of individual products, and for lead times on Optima core porting.

PROGRAMMABLE LOGIC CORES

For ASIC prototyping or for projects requiring the fast time-to-market of a programmable logic solution, Amphion delivers programmable logic core solutions that offer the silicon-aware performance tuning found in all Amphion products, combined with the rapid design times offered by today's leading programmable logic solutions.

Table 5:	Programmable	Logic	Cores
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PRODUCT ID#	SILICON VENDOR	PROGRAMMABLE LOGIC PRODUCT	PERFORMANCE* (MSAMPLES/SEC)	DEVICE RESOURCES USED (LOGIC	DEVICE RESOURCES USED (MEMORY)	AVAILABILITY
CS3210AA	Altera	Apex 20KE FPGA	36	4967 LEs	18 ESB	Now
CS3212AA	Altera	Apex 20KE FPGA	38	5241 LEs	18 ESBs	Now
CS3210X2	Xilinx	Virtex-2 FPGA	61 MHz	2388 slices	2 block RAMs	Now
CS3212X2	Xilinx	Virtex-2 FPGA	60 MHz	2524 slices	2 block RAMs	Now

* Performance represents core only under worst case commercial conditions. Does not include timing effect of external logic and I/O circuitry.

Fax:



ABOUT AMPHION Amphion (formerly Integrated Silicon Systems) is the leading supplier of speech coding, video/ image processing and channel coding	CORPORATE HEADQUAR Amphion Semiconductor L 50 Malone Road Belfast BT9 5BS Northern Ireland, UK	RTERS WORLDWIDE SALES & MARKETING Amphion Semiconductor, Inc 2001 Gateway Place, Suite 130W San Jose, CA 95110
application specific silicon cores for system-on-a-chip (SoC) solutions in the broadband, wireless, and	Tel: +44 28 9050 4000 Fax: +44 28 9050 4001	Tel:(408) 441 1248Fax:(408) 441 1239
mulitmedia markets	EUROPEAN SALES Amphion Semiconductor L CBXII, West Wing 382-390 Midsummer Boule Central Milton Keynes MK9 2RG England, UK	canada & EAST COAST US SALES CANADA & EAST COAST US SALES Amphion Semiconductor, Inc Montreal Vard Quebec Canada
Web: www.amphion.com	Tel: +44 1908 847109	Tel: (450) 455 5544

+44 1908 847580

Email: info@amphion.com

SALES AGENTS

Voyageur Technical Sales Inc
1 Rue Holiday
Tour Est, Suite 501
Point Claire, Quebec
Canada H9R 5N3

Tel: (514) 693 5009 (514) 693 5007 Fax:

JASONTECH, INC

Hansang Building, Suite 300 Bangyidong 181-3, Songpaku Seoul Korea 138-050

Tel: +82 2 420 6700 Fax: +82 2 420 8600

Phoenix Technologies Ltd 3 Gavish Street Kfar-Saba, 44424

Tel: +972 9 7644 800 Fax: +972 9 7644 801

SPS-DA PTE LTD

Israel

21 Science Park Rd #03-19 The Aquarius Singapore Science Park II Singapore 117628

Tel:	+65 774 9070
Fax:	+65 774 9071

SPINNAKER SYSTEMS INC

(450) 455 5543

Fax:

Hatchobori SF Bldg. 5F 3-12-8 Hatchobori, Chuo-ku Tokyo 104-0033 Japan

Tel:	+81 3 3551 2275
Fax:	+81 3 3351 2614

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